



Battery Monitoring System

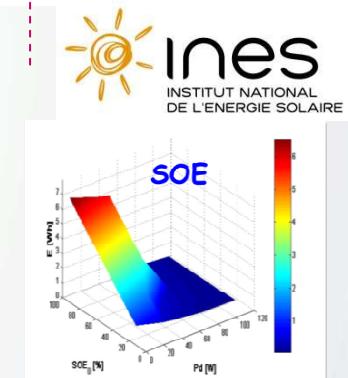
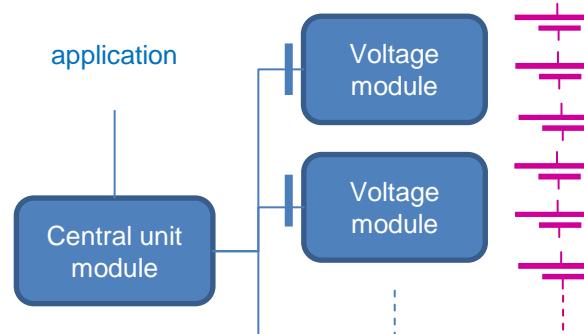
G. Despesse, S. Gery, S. Le Chat, S. Brulais, L. Cassarino, P.A. Ramahefa-Andry, J-P. Gros
CEA LETI&LITEN

BMS – rôle et fonctions

- BMS = Battery Management System
- Fonctions principales
 - Assurer le fonctionnement de la batterie dans des **conditions sécurisées**
 - Monitoring des tensions, de température
 - Permettre un **fonctionnement performant**
 - Équilibrage des cellules pour optimiser l'énergie disponible
 - Fournir l'état de charge de la batterie
- Autres fonctions
 - Pilotage des organes de sécurité
 - Information ou contrôle de l'ouverture du circuit de puissance
 - Estimateurs d'états spécifiques
 - État de santé de la batterie (ou vieillissement)
 - État d'énergie de la batterie 
 - Courant ou puissance maximale disponible
 - Contrôle de l'isolement du pack batterie
 - Gestion du management thermique (exemple : pilotage de ventilateurs ...)
 - Isolation d'un accumulateur défectueux 

Modular BMS

- Sensors characterization
- Expert on Li-ion BMS
 - Voltage measurements module
 - Passive cells balancing
 - Central unit module
 - High precision current measurement
 - Algorithms and electrochemical indicators embedded
 - CAN protocole communication
- BMS prototypes based on proven concepts

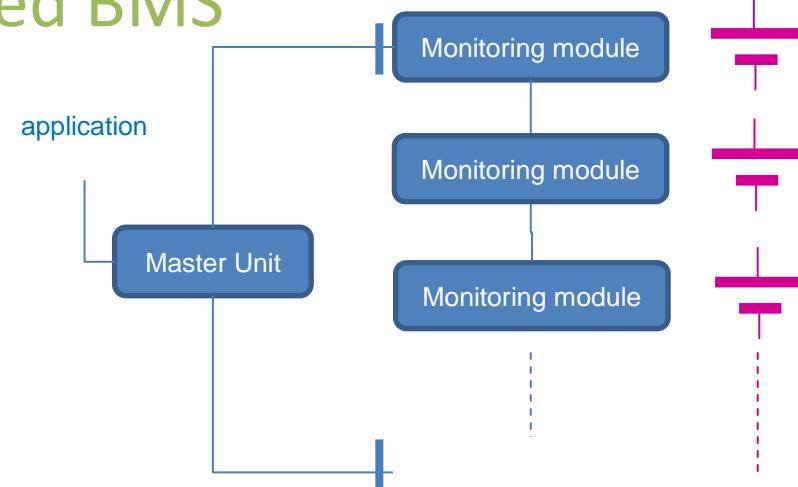


8 projects
10 to 80 kWh
< 50 000 km

transferred to industry
TRL
8

Chained BMS

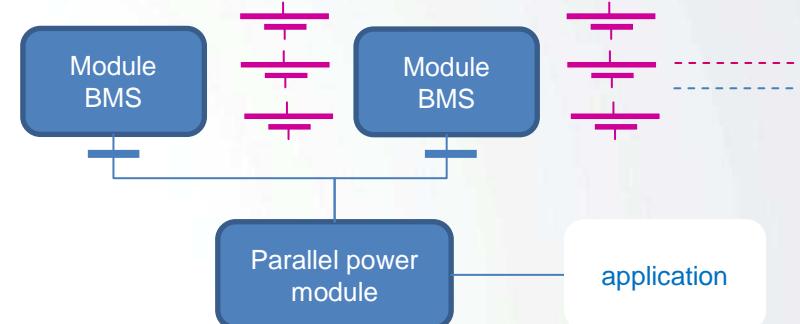
- Simplified electronic
- Redondance optimization
 - Measurement
 - Communications
- Local balancing
- Local calculators
- Isolation optimization



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Parallel plug BMS

- Local BMS for module
 - Voltage module measurements
 - Passive cells balancing
 - Current module measurement
 - Algorithms and electrochemical indicators embedded
 - Internal and external communication
- Power module to parallel plug
 - Power current control strategy



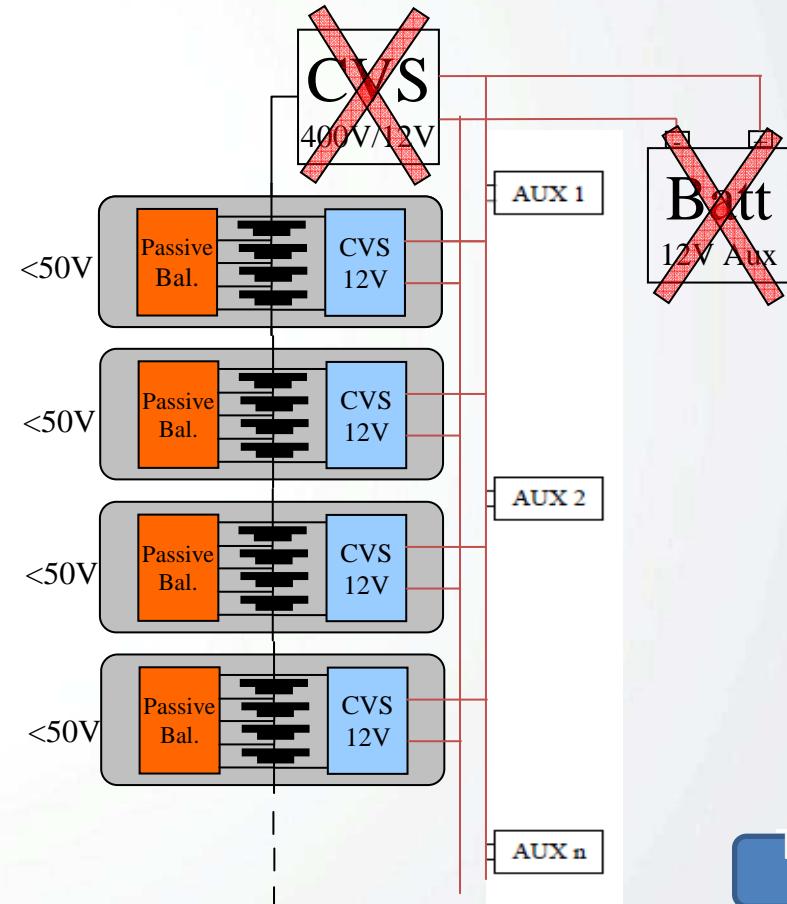
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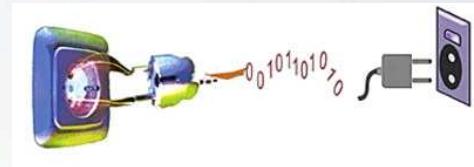
Active balancing BMS

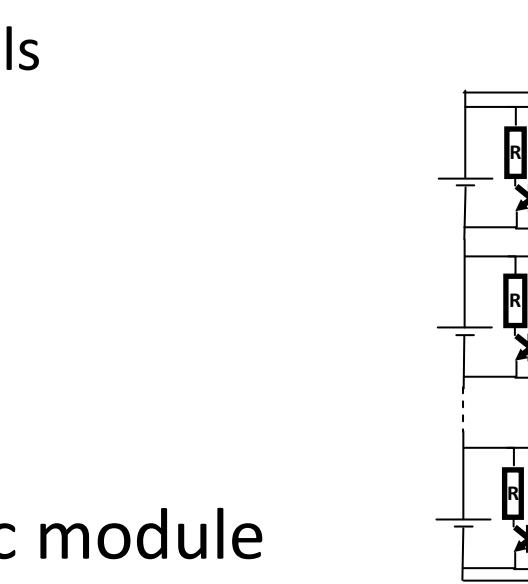
- High current
 - cell balancing
 - module balancing
- Modularity
- Safety
 - Modules voltage < 50 V
 - 12 CVS redundancy



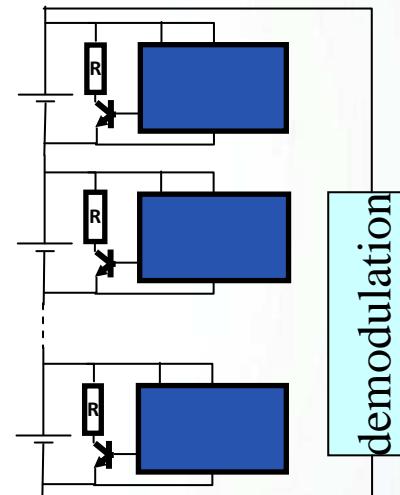
*Redistribution topologies
Cell-to-battery, battery-to-cell, bidirectional*





- Power line current of energy sources
 - On battery cells
 - On PV
 - Specific bus
 - High rate
 - redundant
 - Simply analogic module
 - Standard

Modulation /demodulation



transferred to industry

TRL
8

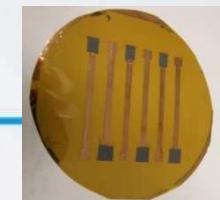
Specific measurements

In collaboration with LETI/DCOS

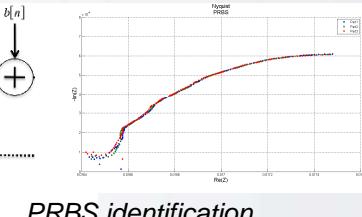
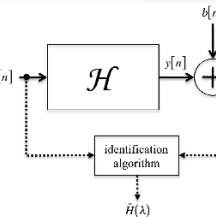
- Electric impedance measurement
- Mechanical impedance measurement
- Security battery measurements
 - Inside battery sensors
- Short circuit detection
- Electric arc measurement



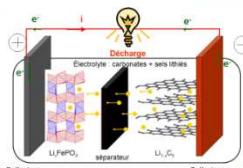
Active measurement



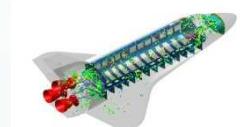
Reference electrode



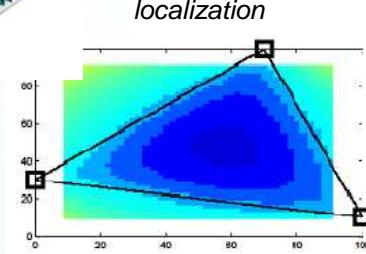
PRBS identification



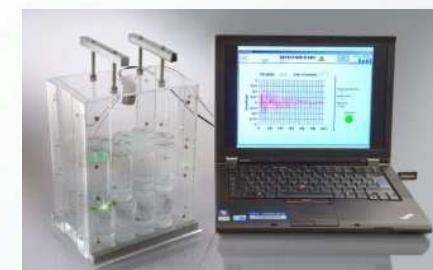
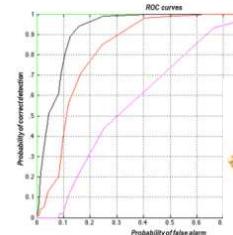
Inside mechanical impedance tracking



localization

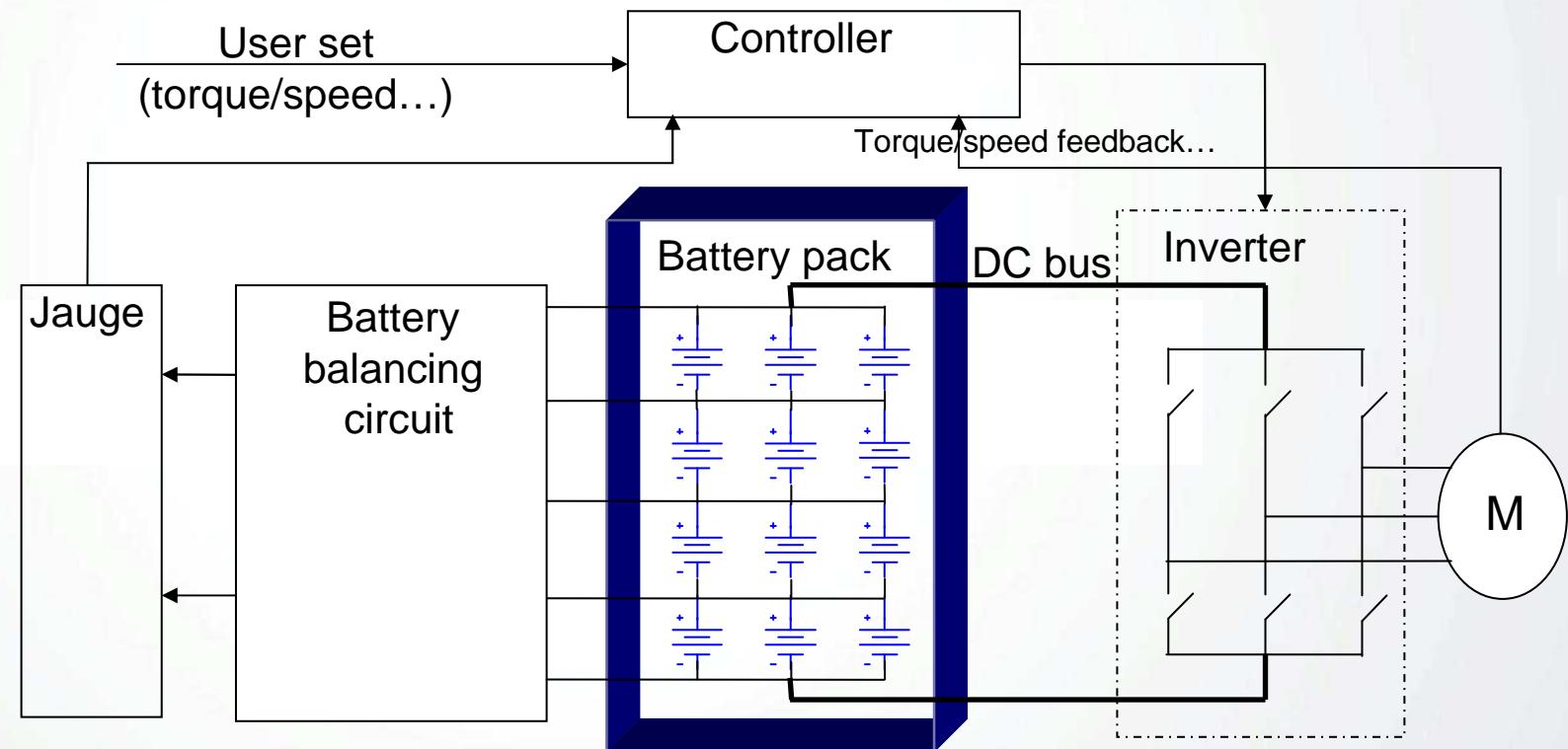


In situ detection



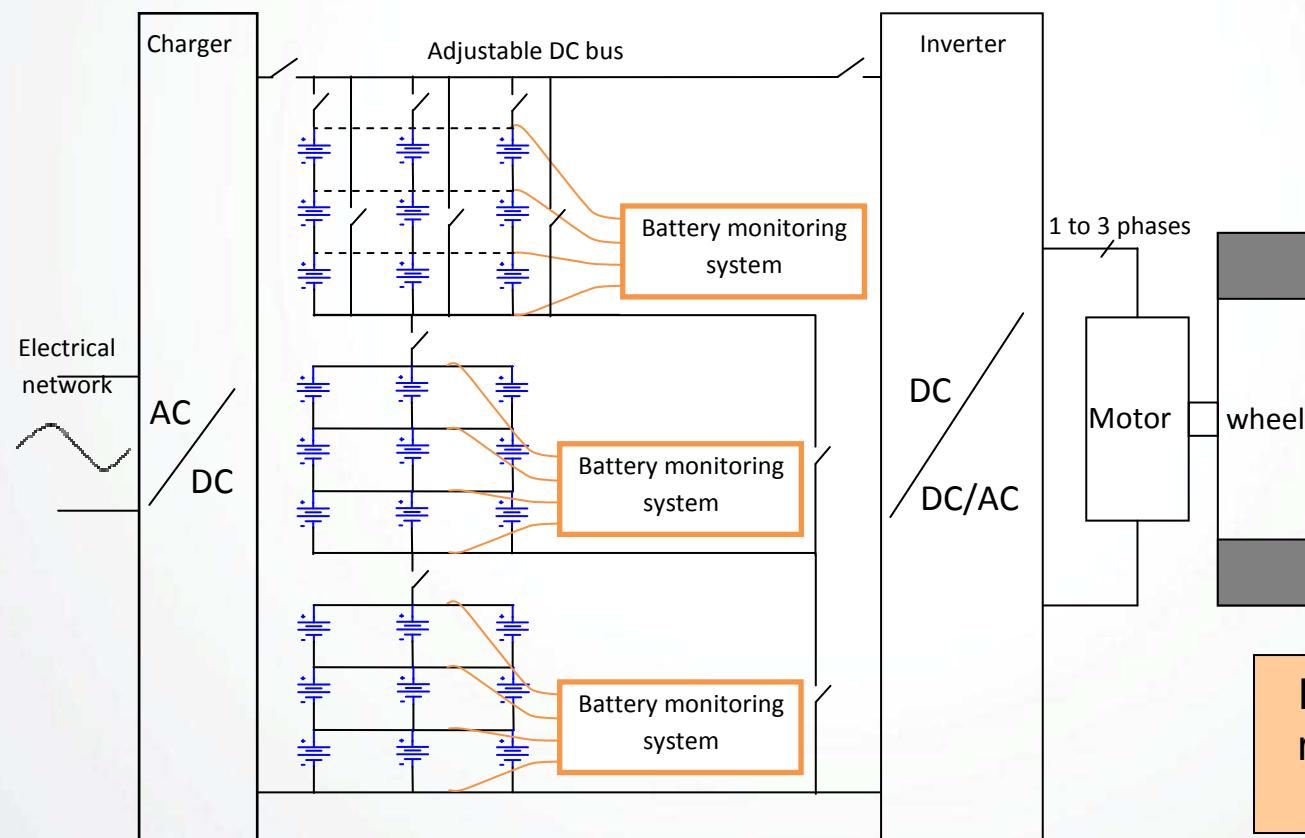
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Actual electrical propulsion principle



How to overcome a battery cell failure

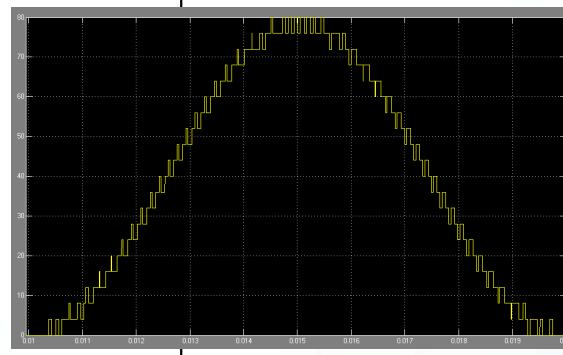
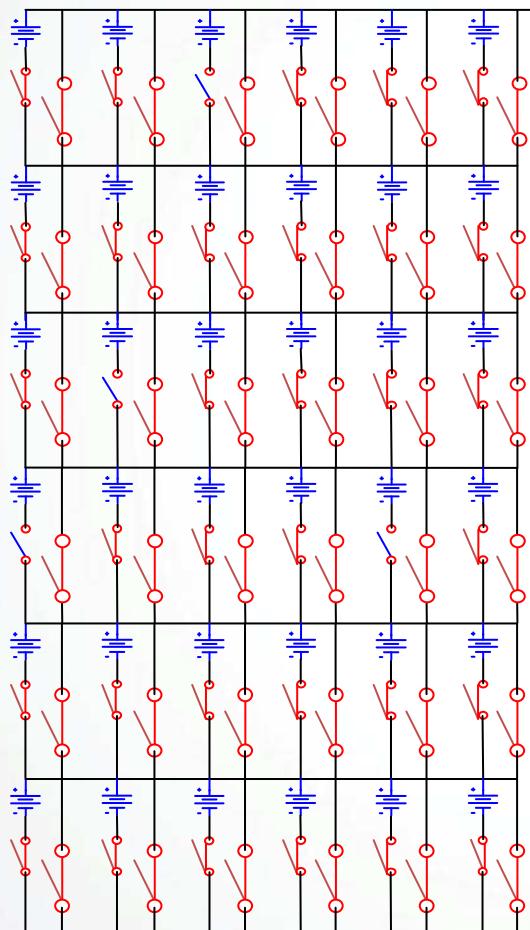
- Actually if one cell is failed, all the battery pack is impacted as all the battery cell are in serial
- One solution is to cut the battery pack in several disconnectables modules



- Adjustable DC bus voltage
- As the current can be large (up to 300 A) several transistors in parallel are required -> each module can be cut in several columns at same cost
- As transistor cost is quite proportionnal to its voltage over 25 V, it is interesting to cut the battery pack in modules voltage of around 20 V (4 to 5 serial Li-ion cells)

But that solution continues to require a charger, an inverter and a cell balancing circuit

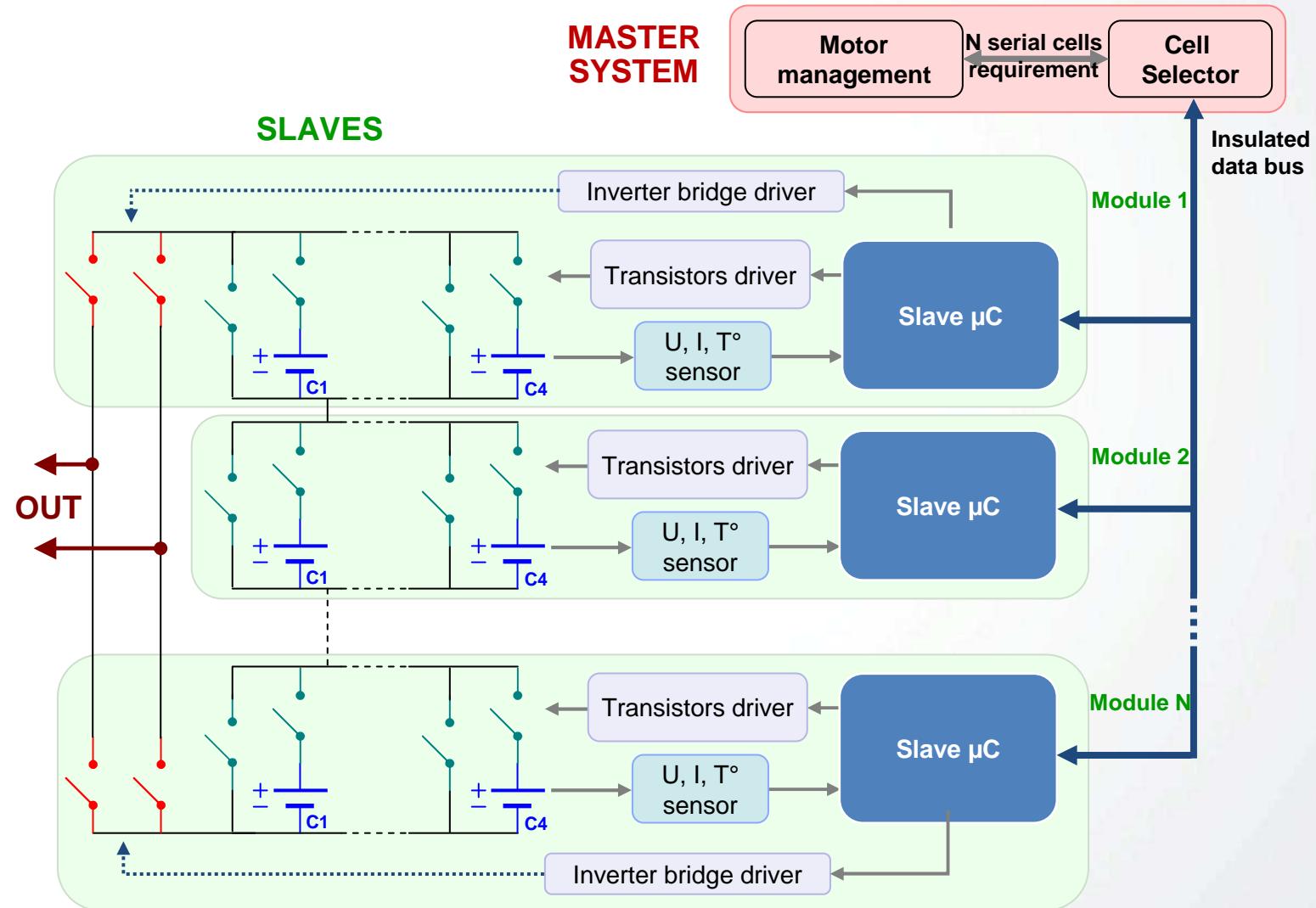
Toward modules having only one serial cell

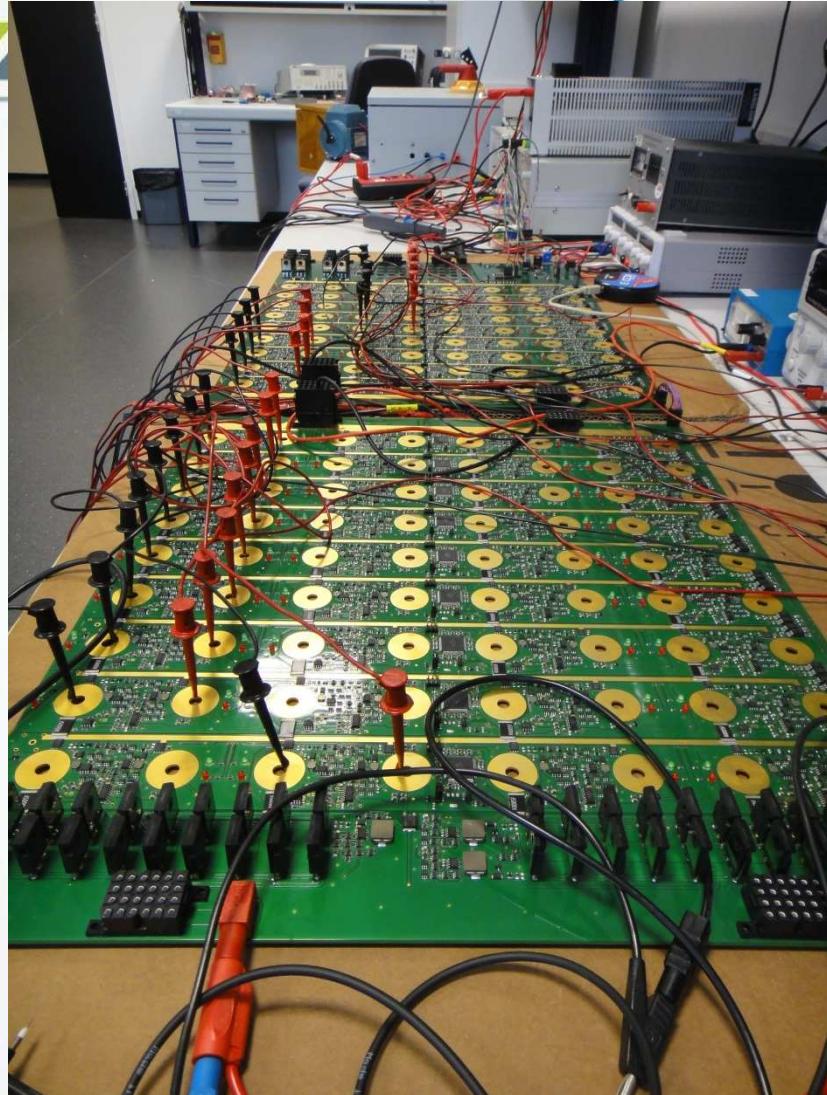


- Cell balancing in real time and with the full useful flowing current → no losses and no additional weight or cost for cell balancing
- No high frequency and high voltage switching → very low commutations losses
- Can work as well for charge or discharge
- Replace the inverter
- Replace the charger
- Replace the costly converter of high speed charger stations
- Improve the current and voltage waveforms applied to the electrical motor or get on the electrical network
- Can reduce by a factor five the losses compare to an embeddable inverter

50 to 100€ of transistors cost per 10 kW to get an efficiency of 98,5%
(catalogue price → could be significantly reduced with quantities)

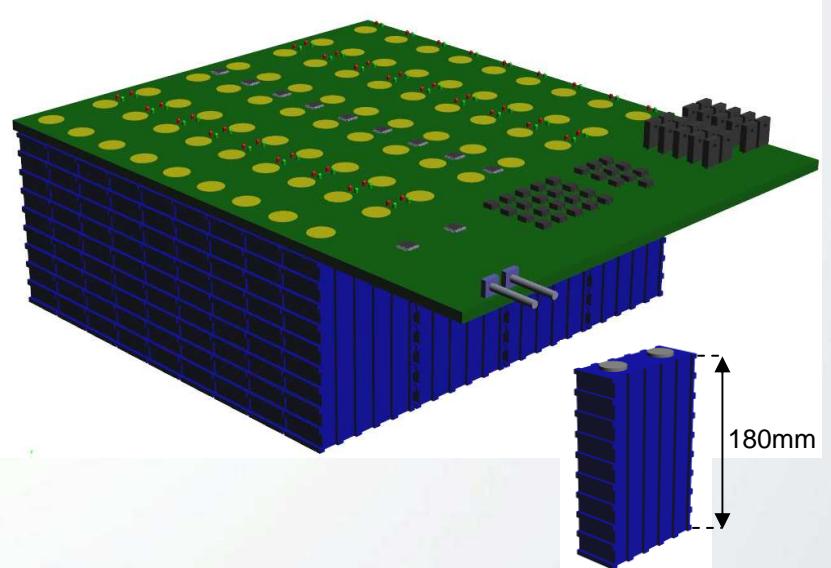
First prototype architecture



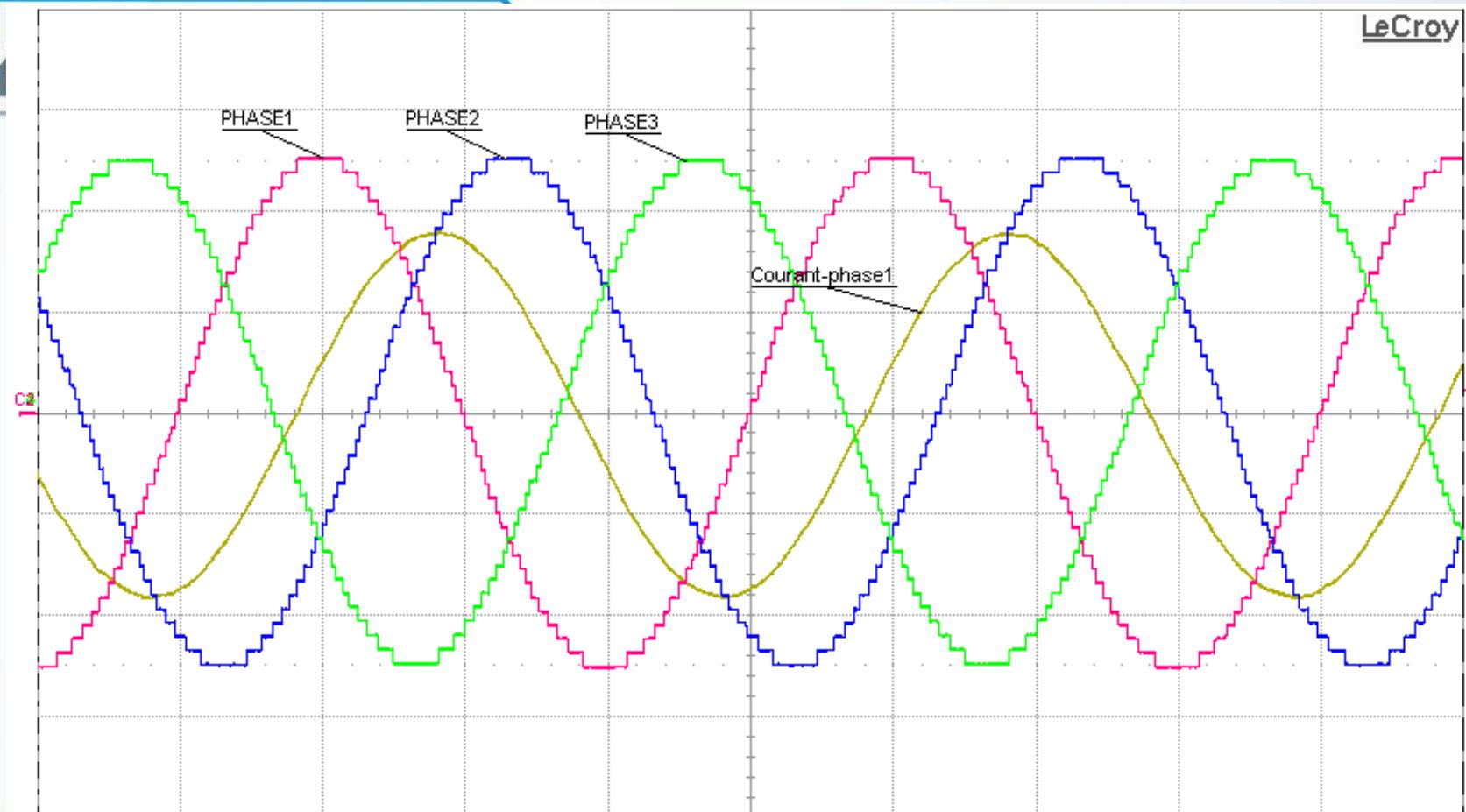


1st prototype fabrication

- 18 modules
- 4 cells of 40Ah per module
- Include an inverter to reverse the output voltage
- Permits to switch in serial/parallel two such systems



Electrical motor driving: continuous regime (measurement)

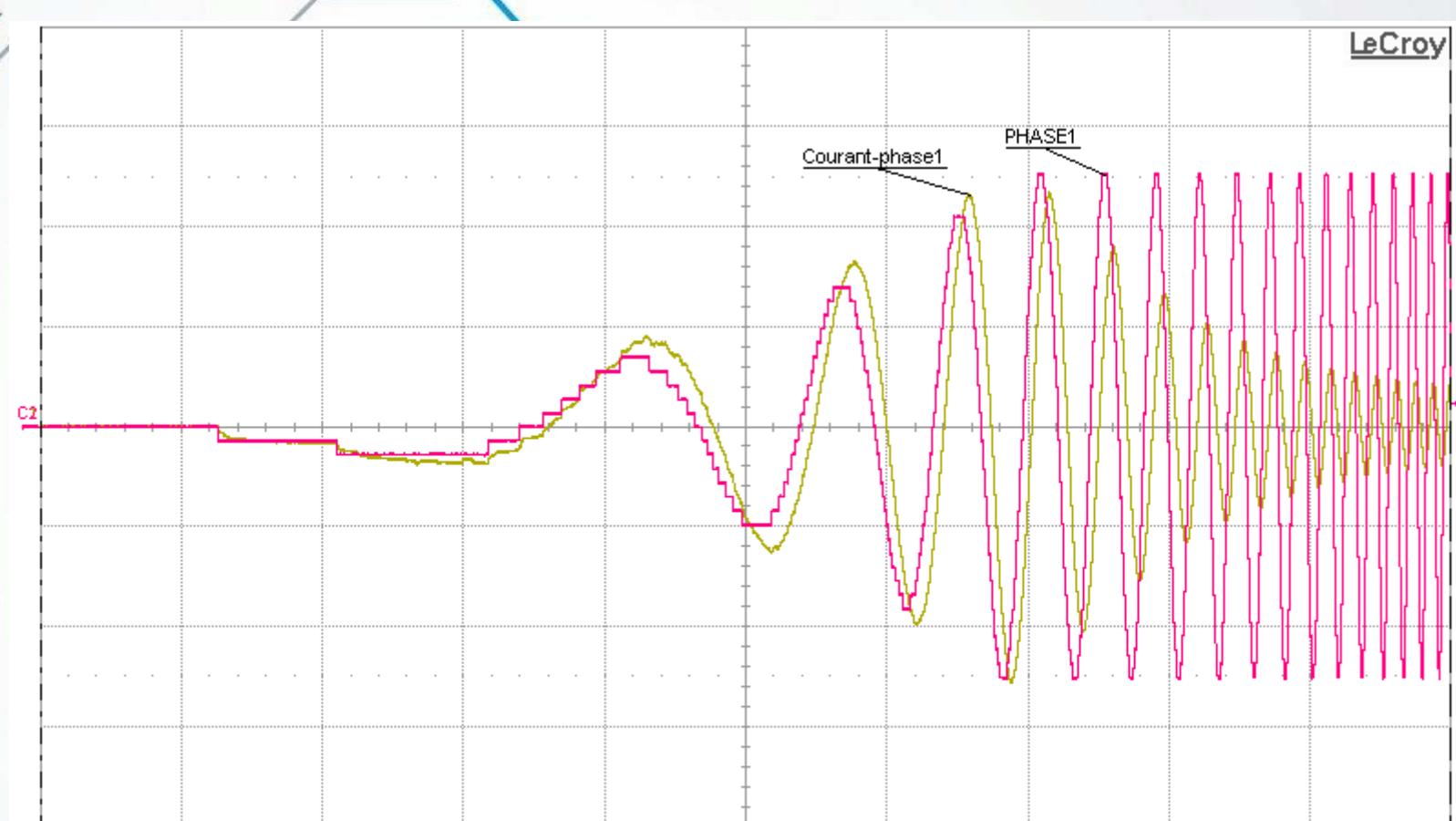


| Measure | P1:pkpk(C1) | P2:freq(C1) | P3:phase(C2,C3) | P4:phase(C2,C4) | P5:-- | P6:-- |
|---------|-------------|--------------|-----------------|------------------|-------|-------|
| value | 727 mA | 49.912155 Hz | 119.549411747 ° | -119.696490292 ° | | |
| status | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

| | | | | | | | | | | | | | |
|--------------|---|-----|----|-------------|---|-----|------|-------------|-----|------|-------------|-----|------|
| C1 | F | BwL | DC | C2 | F | BwL | DC1M | C3 | FLT | DC1M | C4 | FLT | DC1M |
| 200 mA/div | | | | 2.00 V/div | | | | 2.00 V/div | | | 2.00 V/div | | |
| 0.00 mA ofst | | | | 0.0 mV ofst | | | | 0.0 mV ofst | | | 0.0 mV ofst | | |

| | | | |
|--------|-------------|-----------|----------|
| Tbase | 0.0 ms | Déclench. | C2;DC |
| | 5.00 ms/div | Auto | 440 mV |
| 500 kS | 10 MS/s | Edge | Positive |

Electrical motor driving: transient regime (measurement)


Measure

value

P1:pkpk(C1)

4.904 A

status

C1 F BwL DC

C2 F BwL DC1M

1.00 A/div

0.0 mA ofst

2.00 V/div

0.0 mV ofst

P2:freq(C1)

23.798024 Hz

Hz

P3:phase(C2,C3)

122.04321230 °

°

P4:phase(C2,C4)

-117.24223753 °

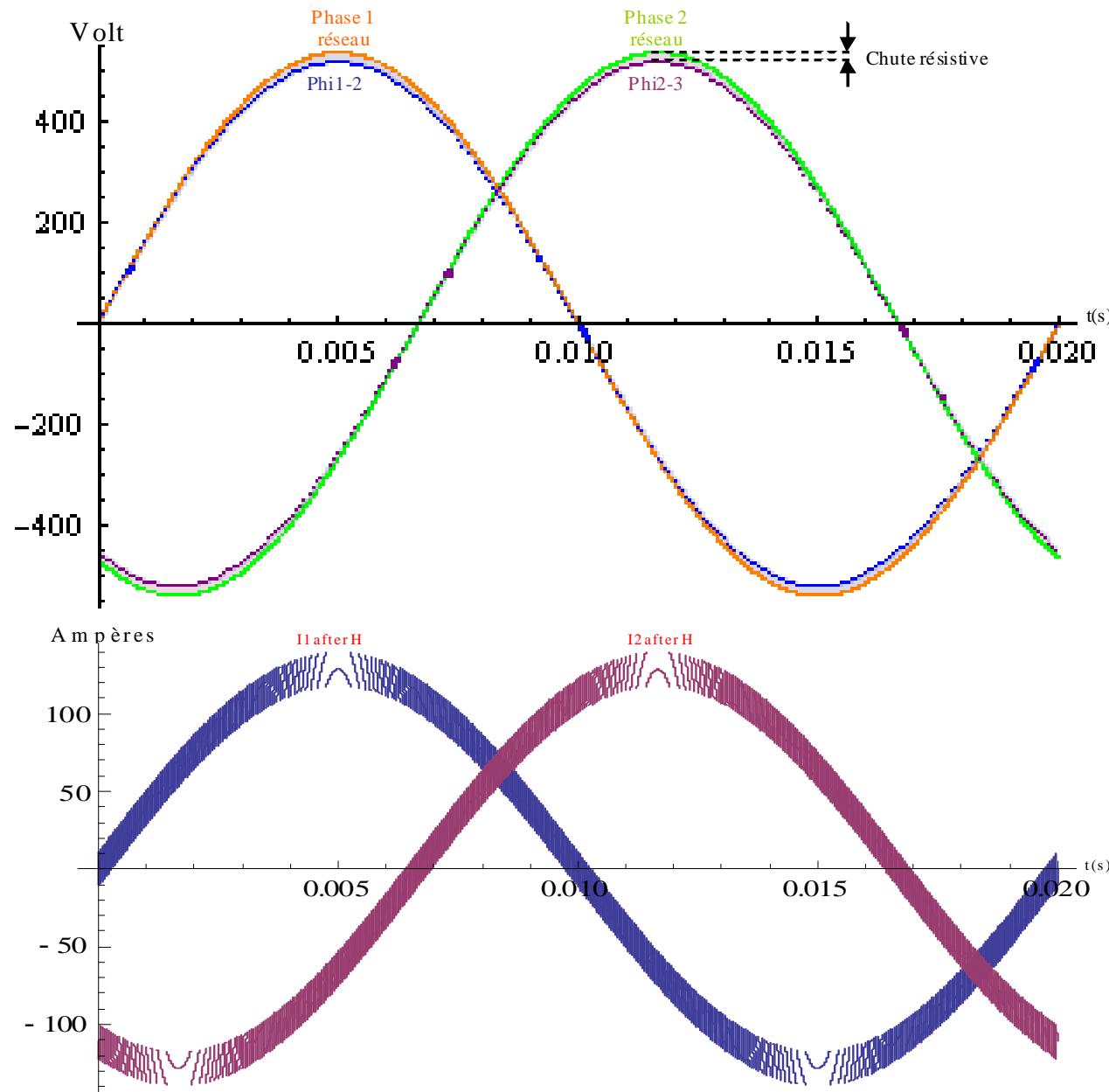
°

P5:--

P6:--

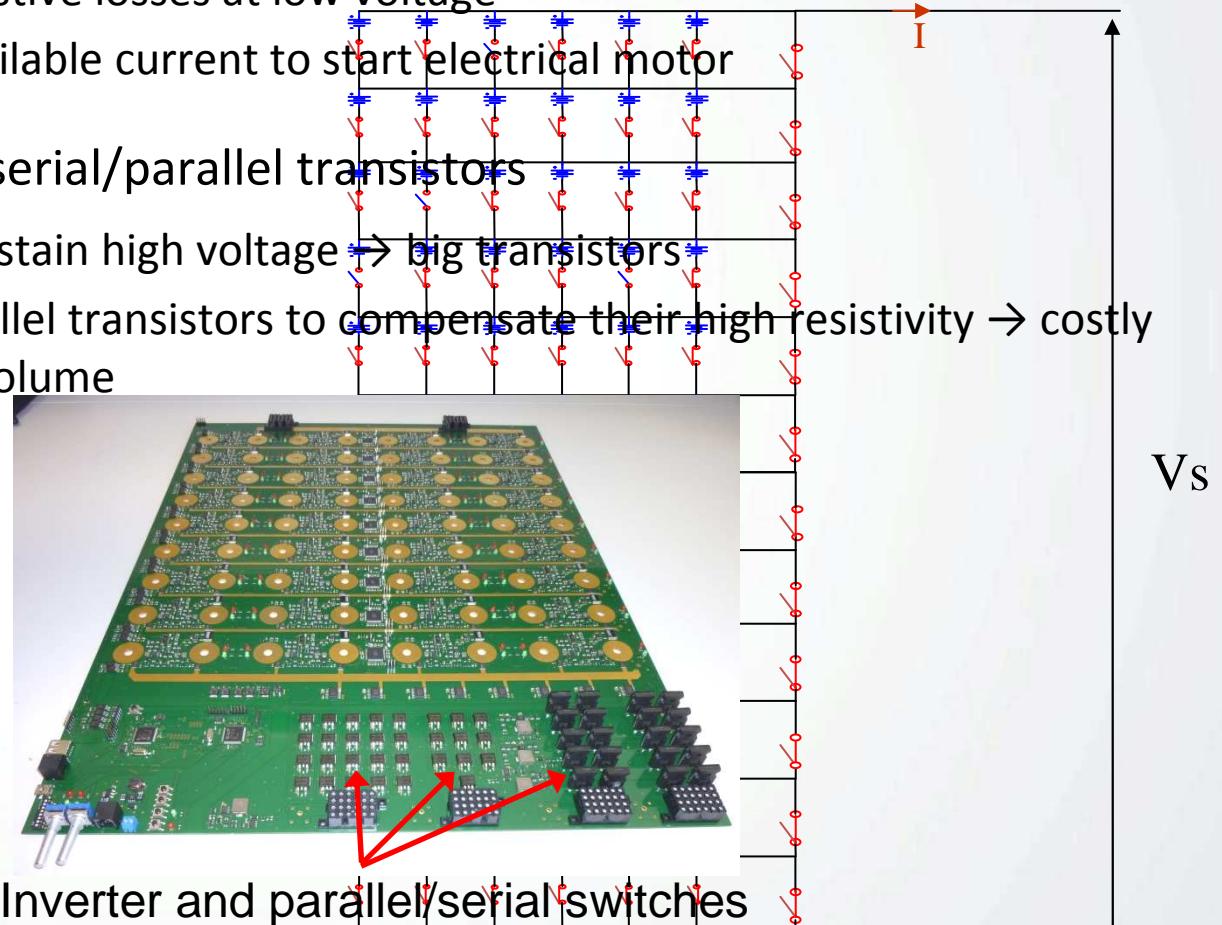
| | | | |
|--------|------------|----------|----------|
| Tbase | -288 ms | Déclench | C2:DC |
| Roll | 200 ms/div | Arrêter | 440 mV |
| 500 kS | 250 kS/s | Edge | Positive |

Under 380V electrical network recharge (simulation)



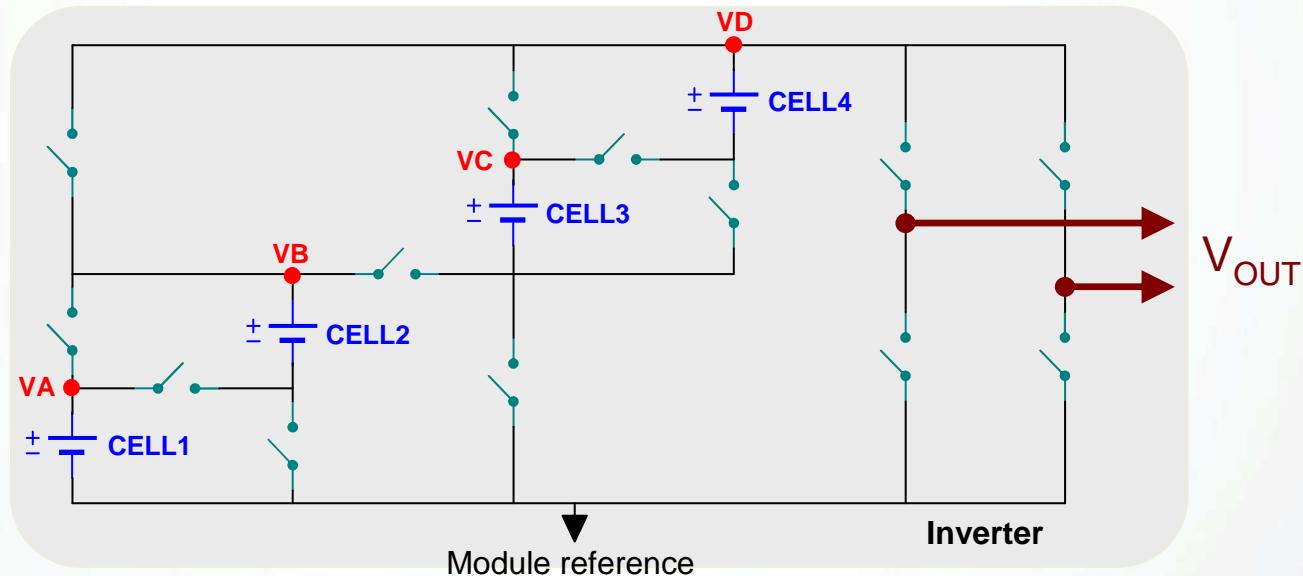
Output current capability adjustment

- Parallel/serial switching of batteries blocks
 - Lower resistive losses at low voltage
 - Higher available current to start electrical motor
- Inverter and serial/parallel transistors
 - Have to sustain high voltage \rightarrow big transistors
 - Many parallel transistors to compensate their high resistivity \rightarrow costly and high volume



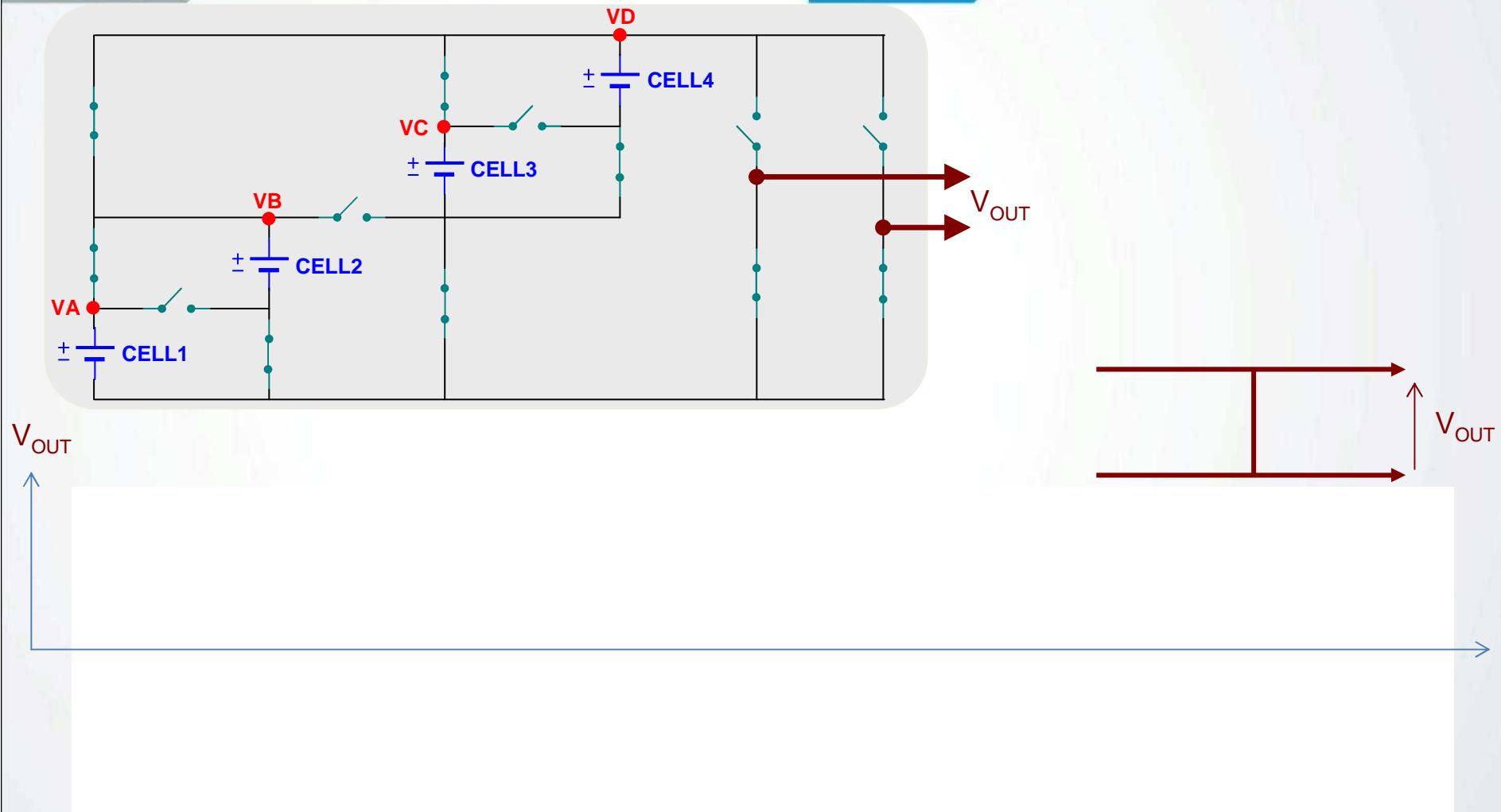
2d prototype: local switching design

- Local inversion and serial/parallel switching
 - Under lower voltage → Smaller transistors
 - Easier to drive in synchronize the inverter

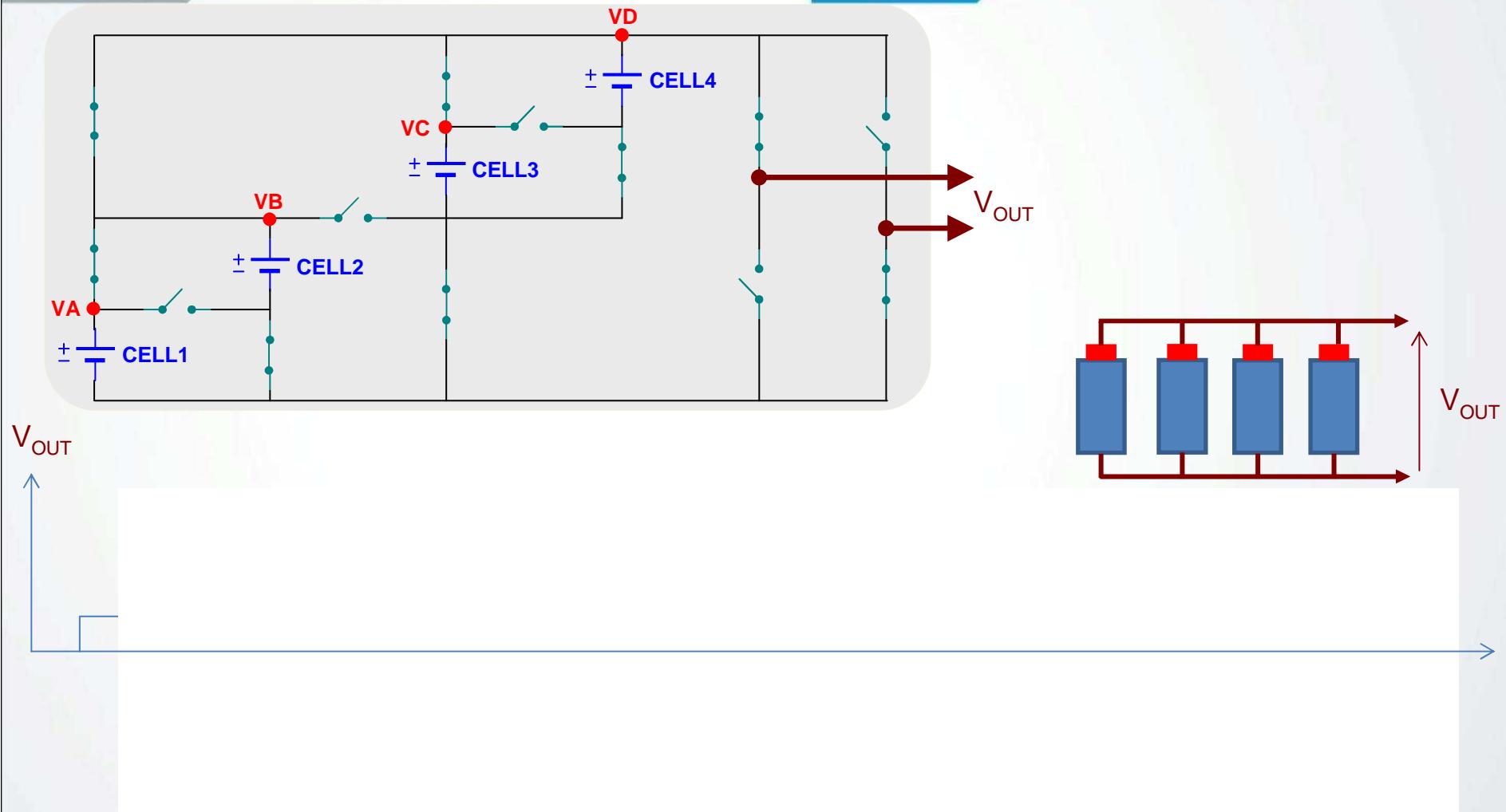


- Higher efficiency in low voltage: up to 4 cells in parallel

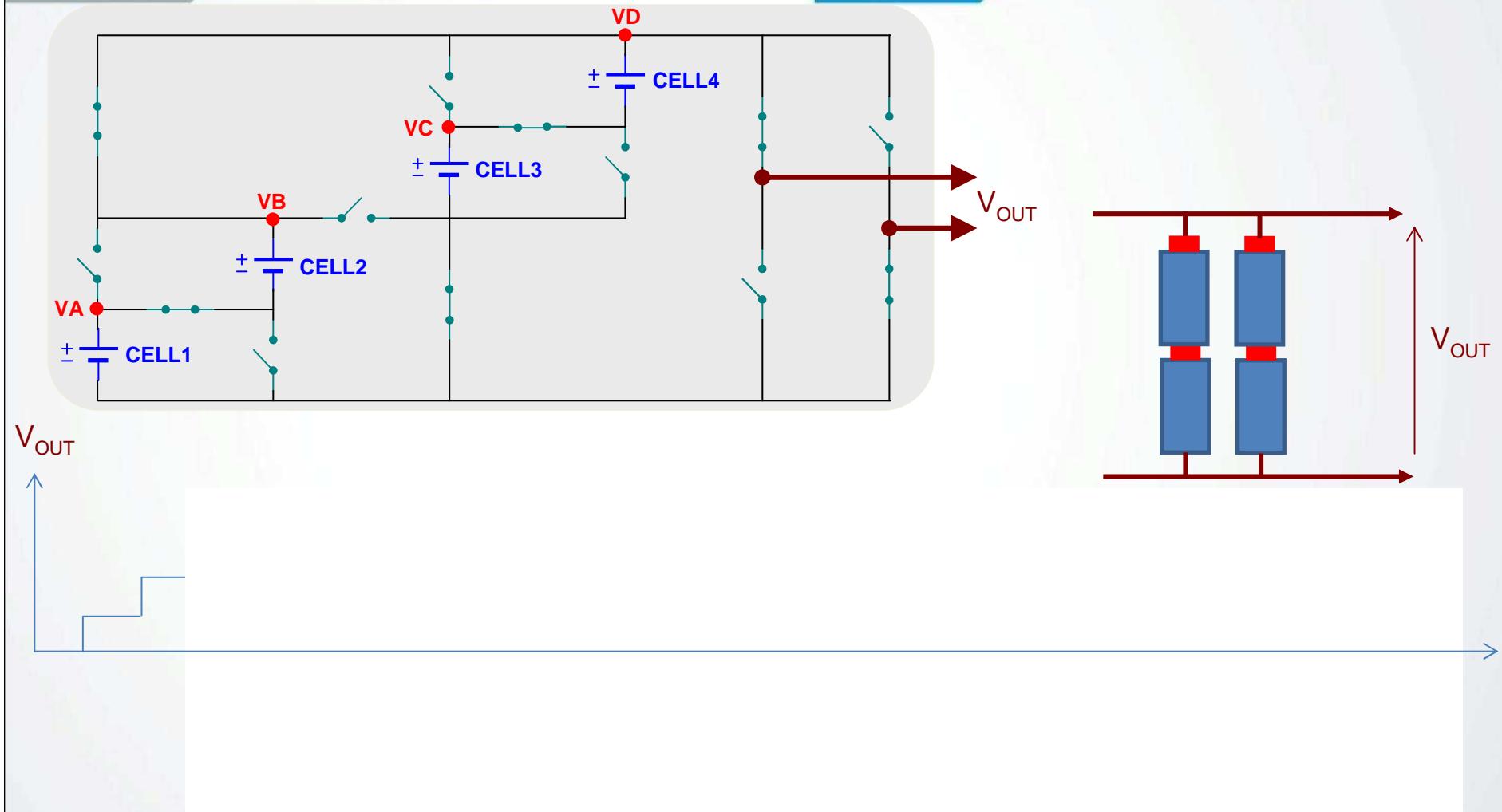
Le BMS commuté : l'architecture générique



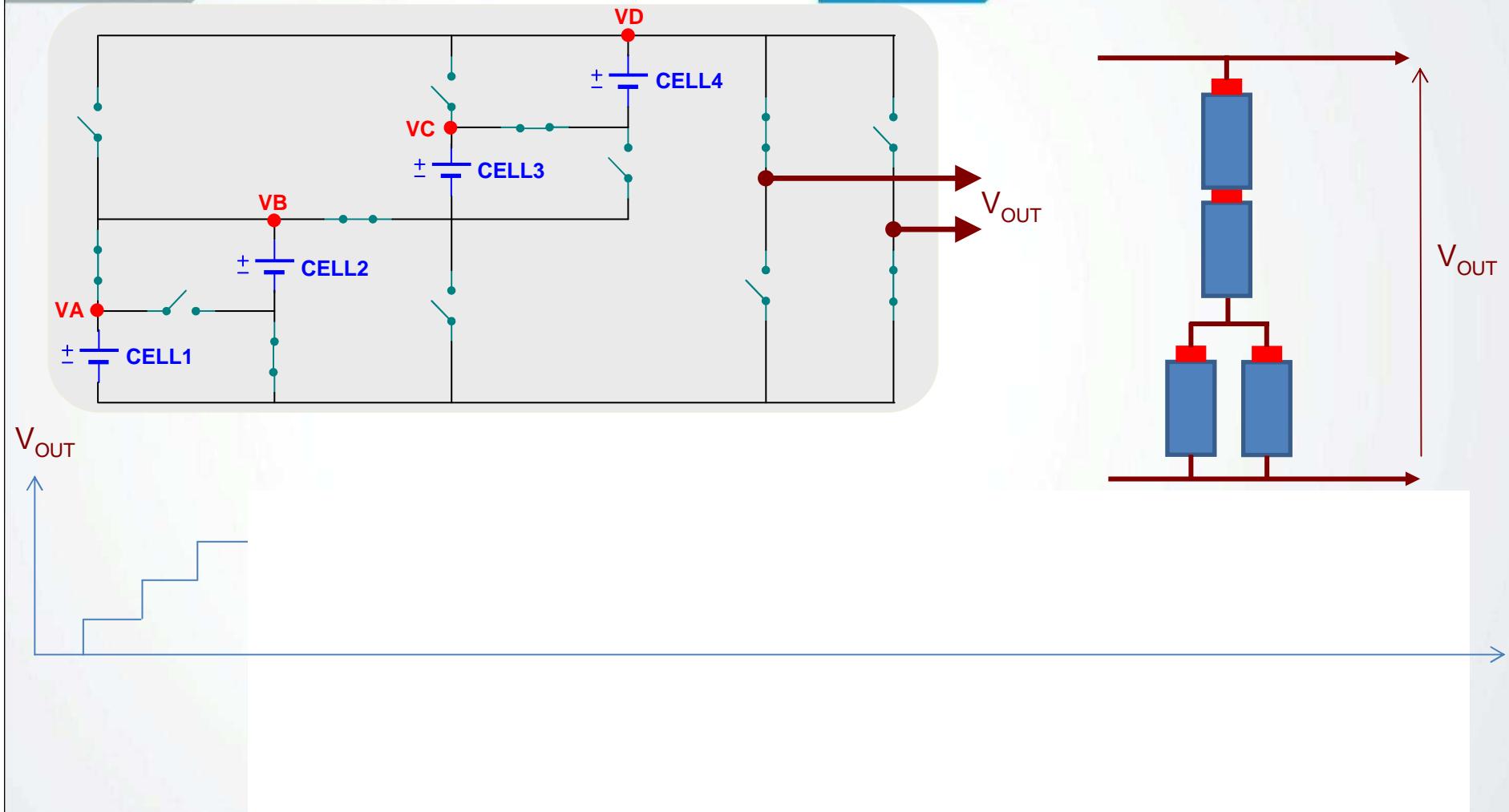
Le BMS commuté : l'architecture générée



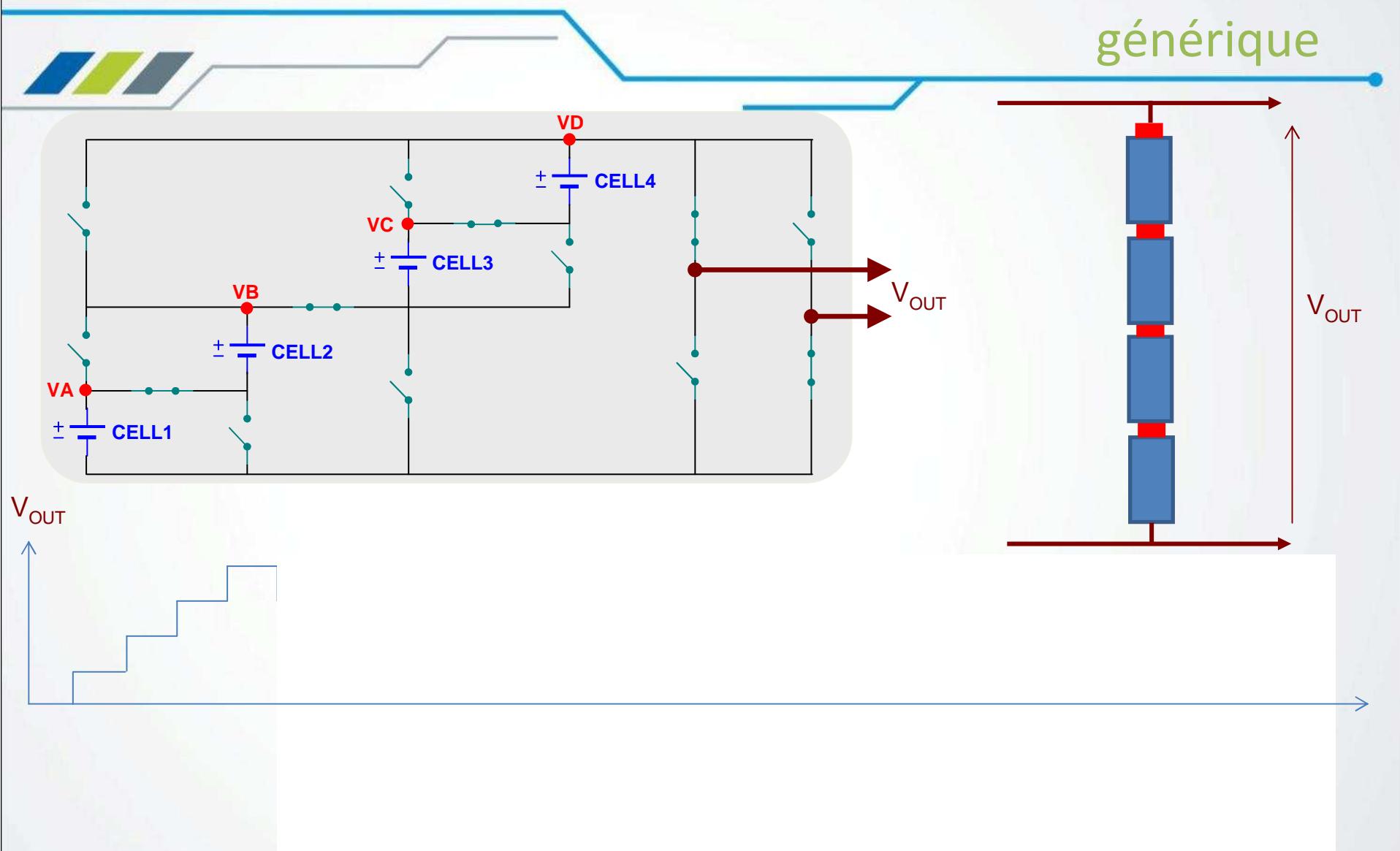
Le BMS commuté : l'architecture générée



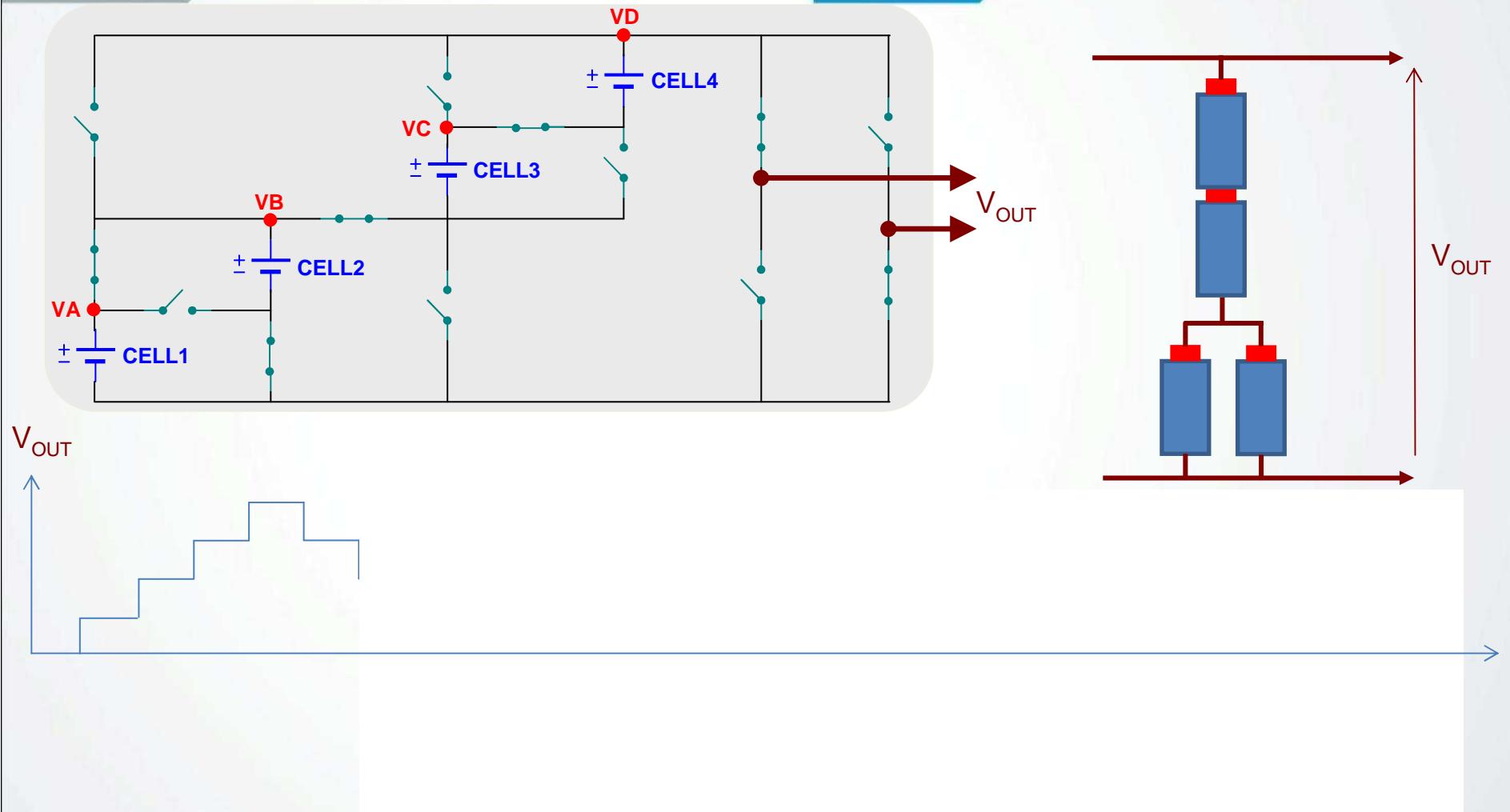
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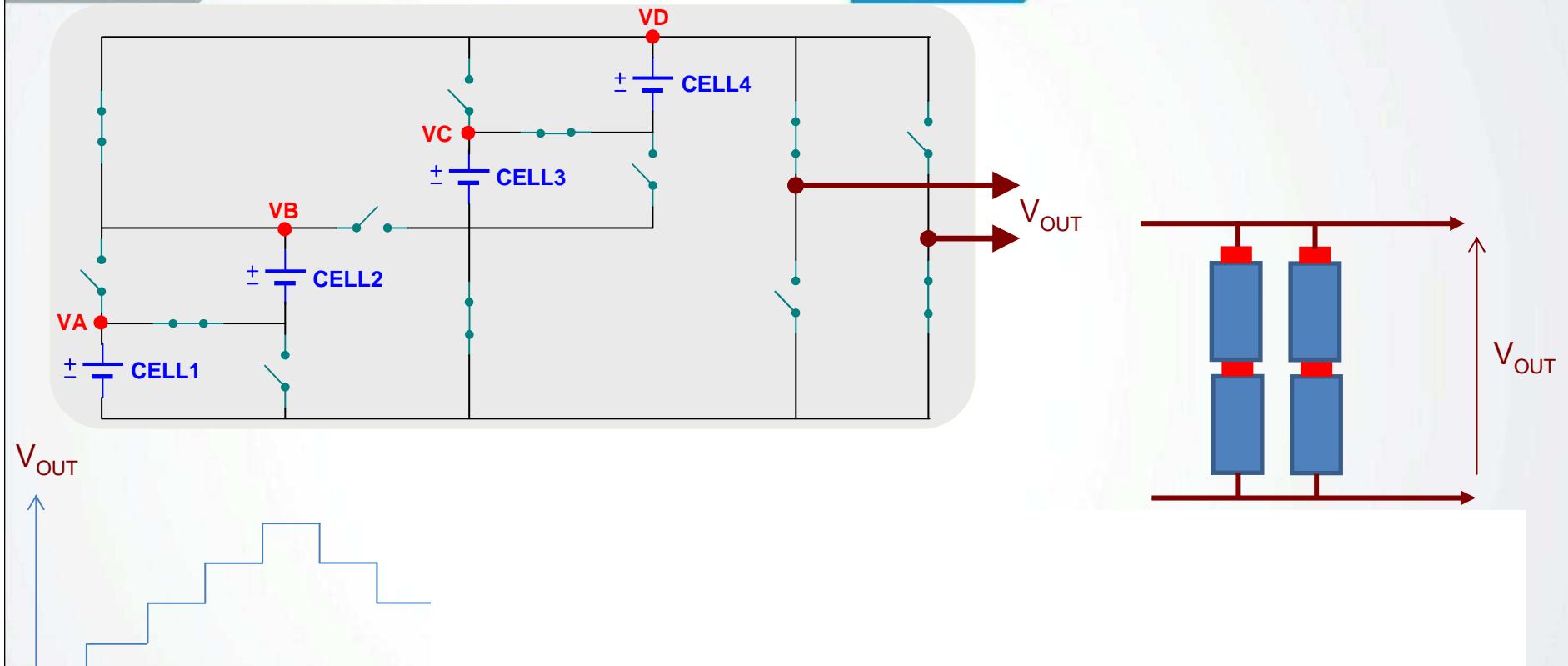
Le BMS commuté : l'architecture générée



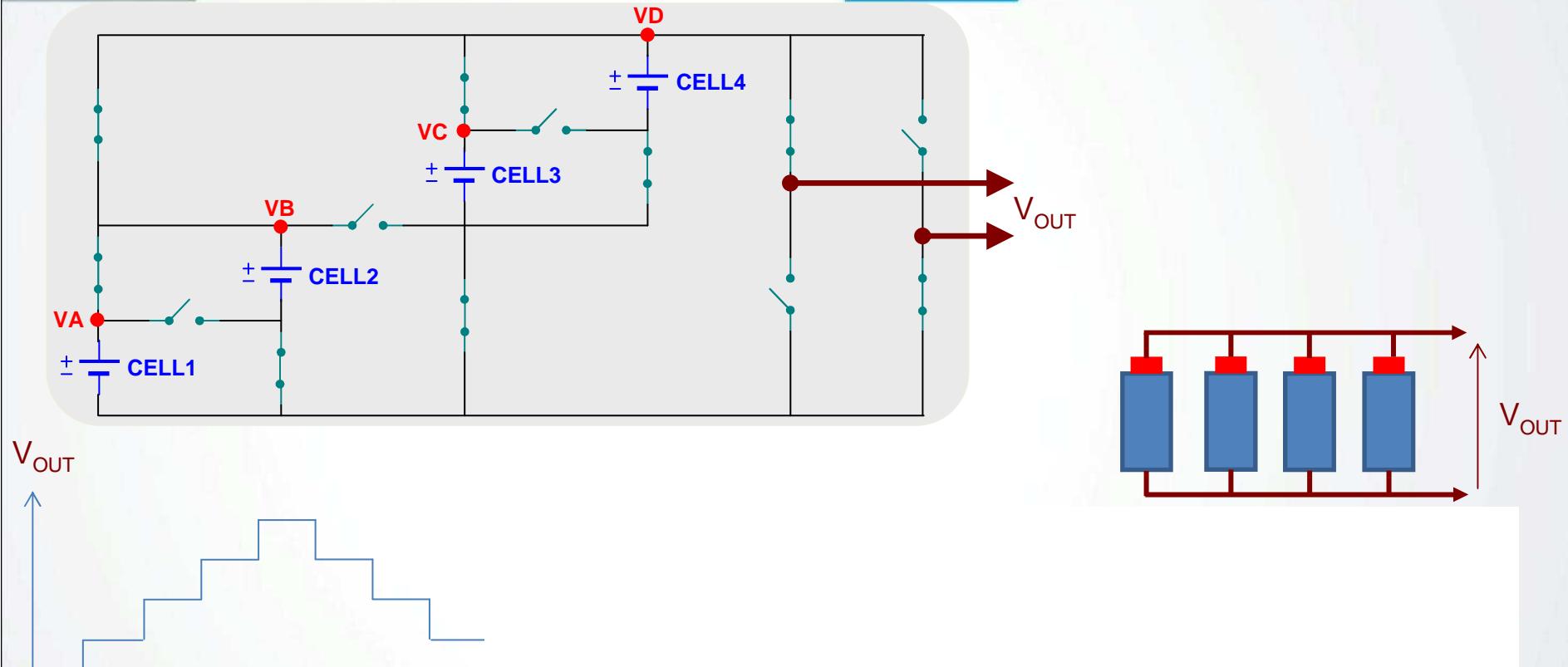
Le BMS commuté : l'architecture générée



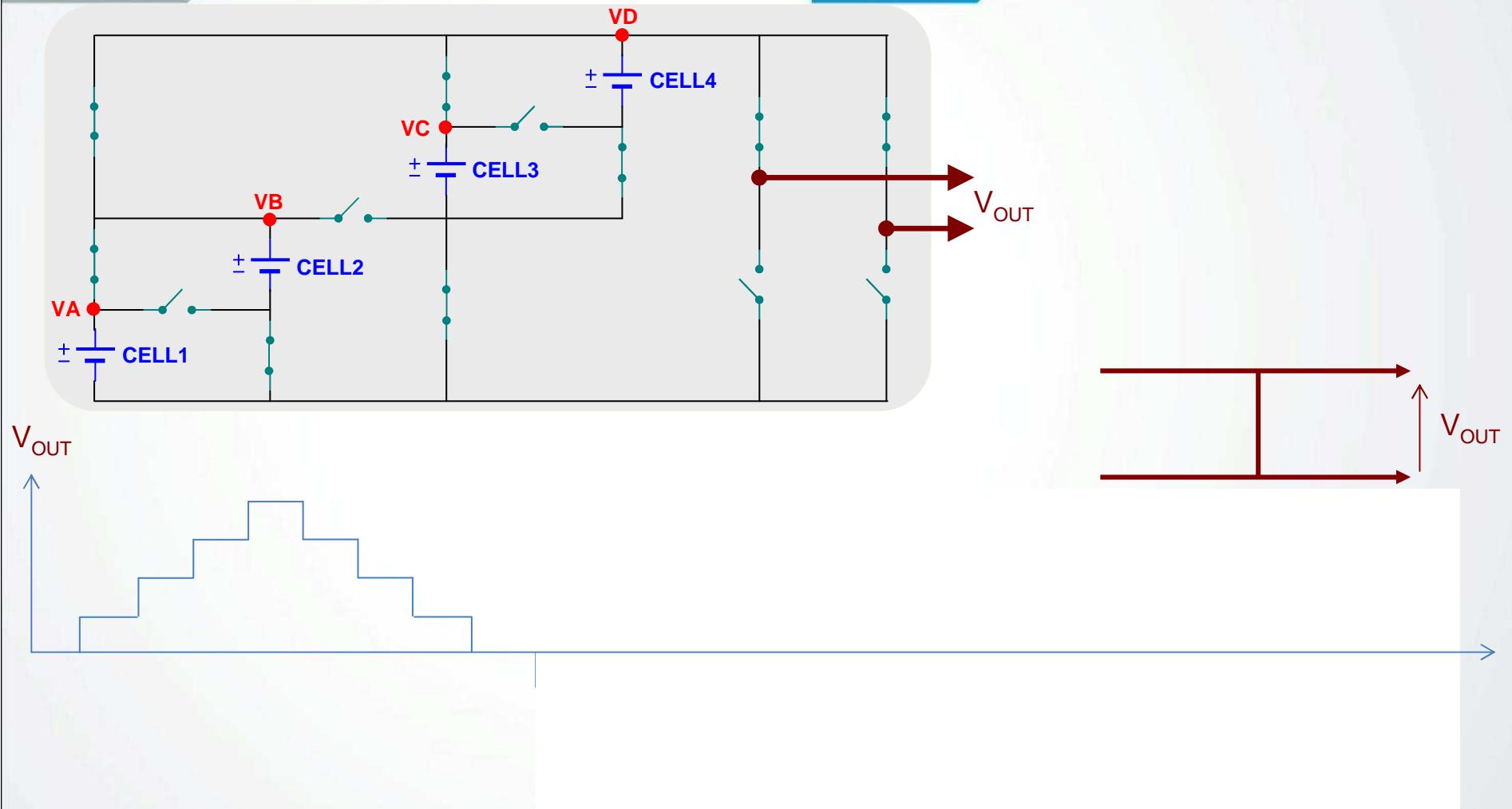
Le BMS commuté : l'architecture générée



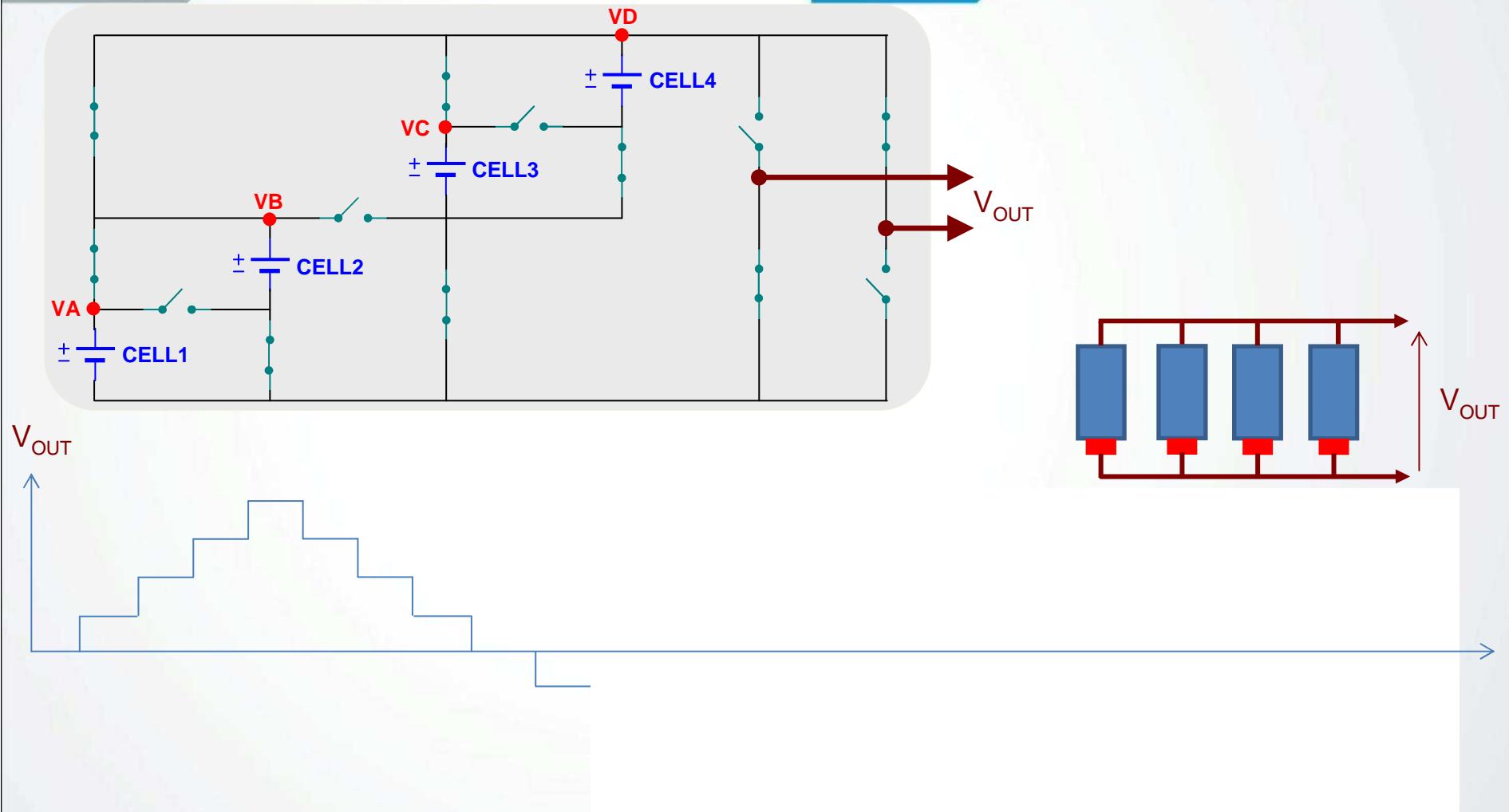
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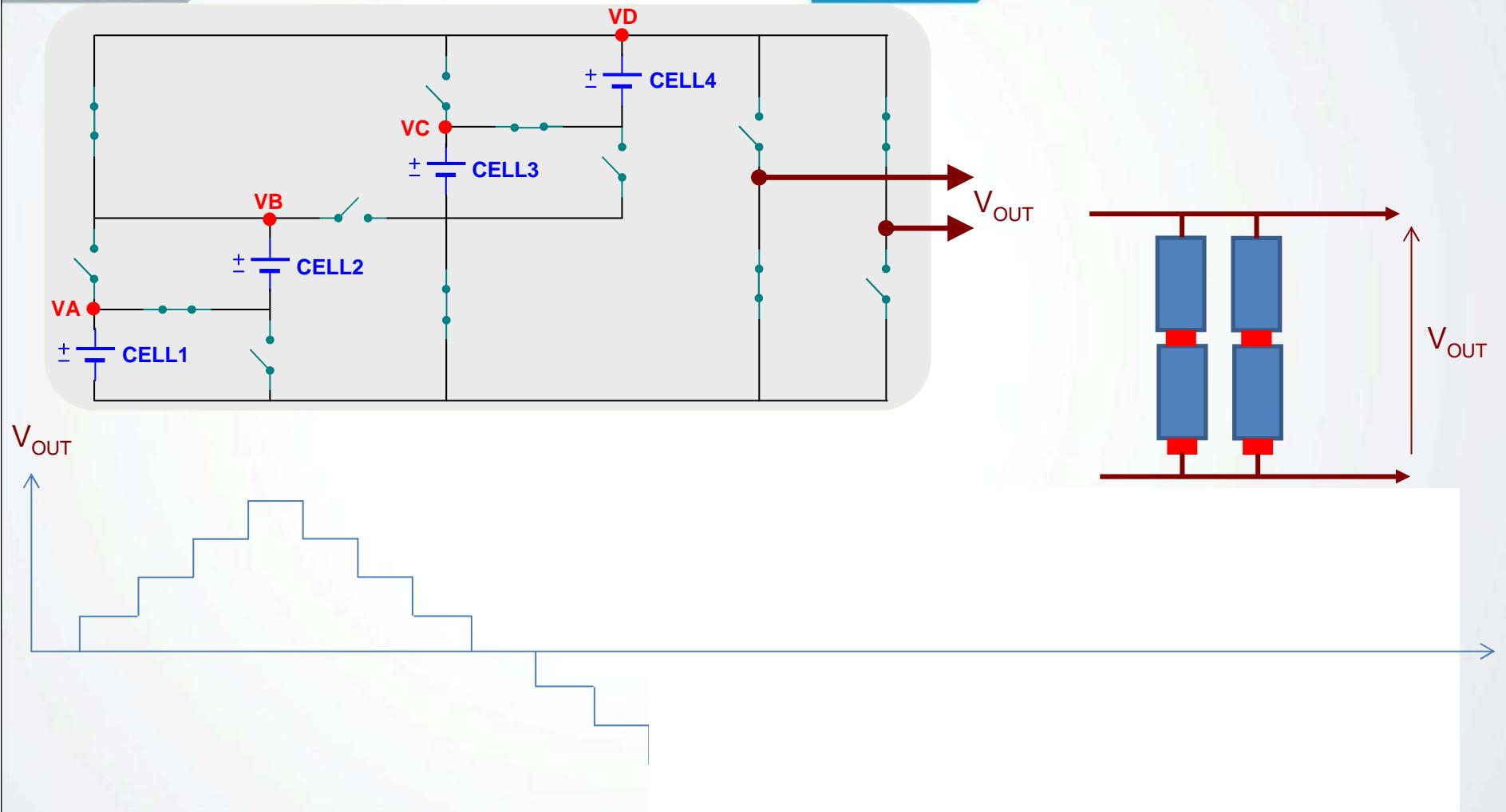
Le BMS commuté : l'architecture générée



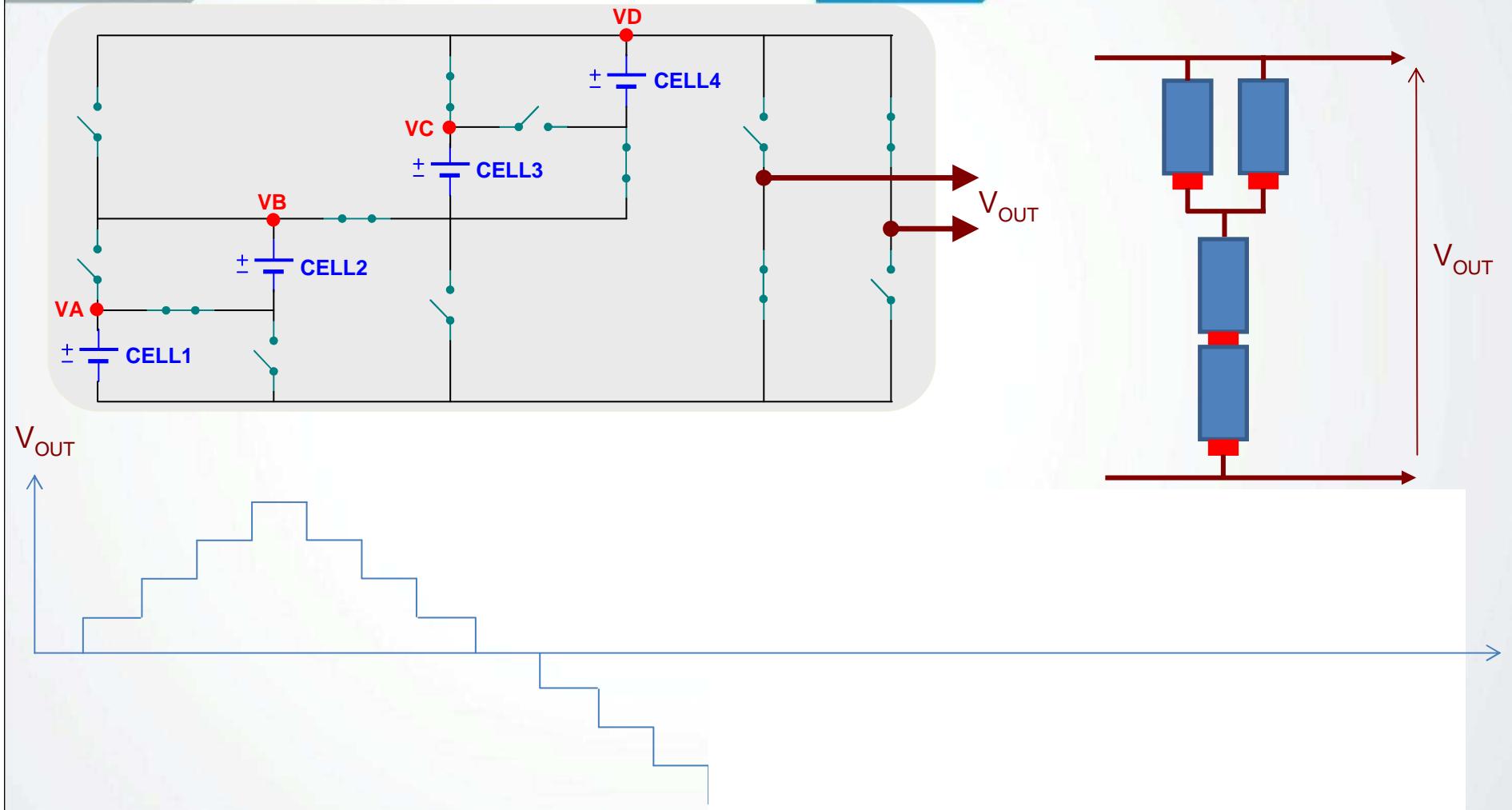
Le BMS commuté : l'architecture générative



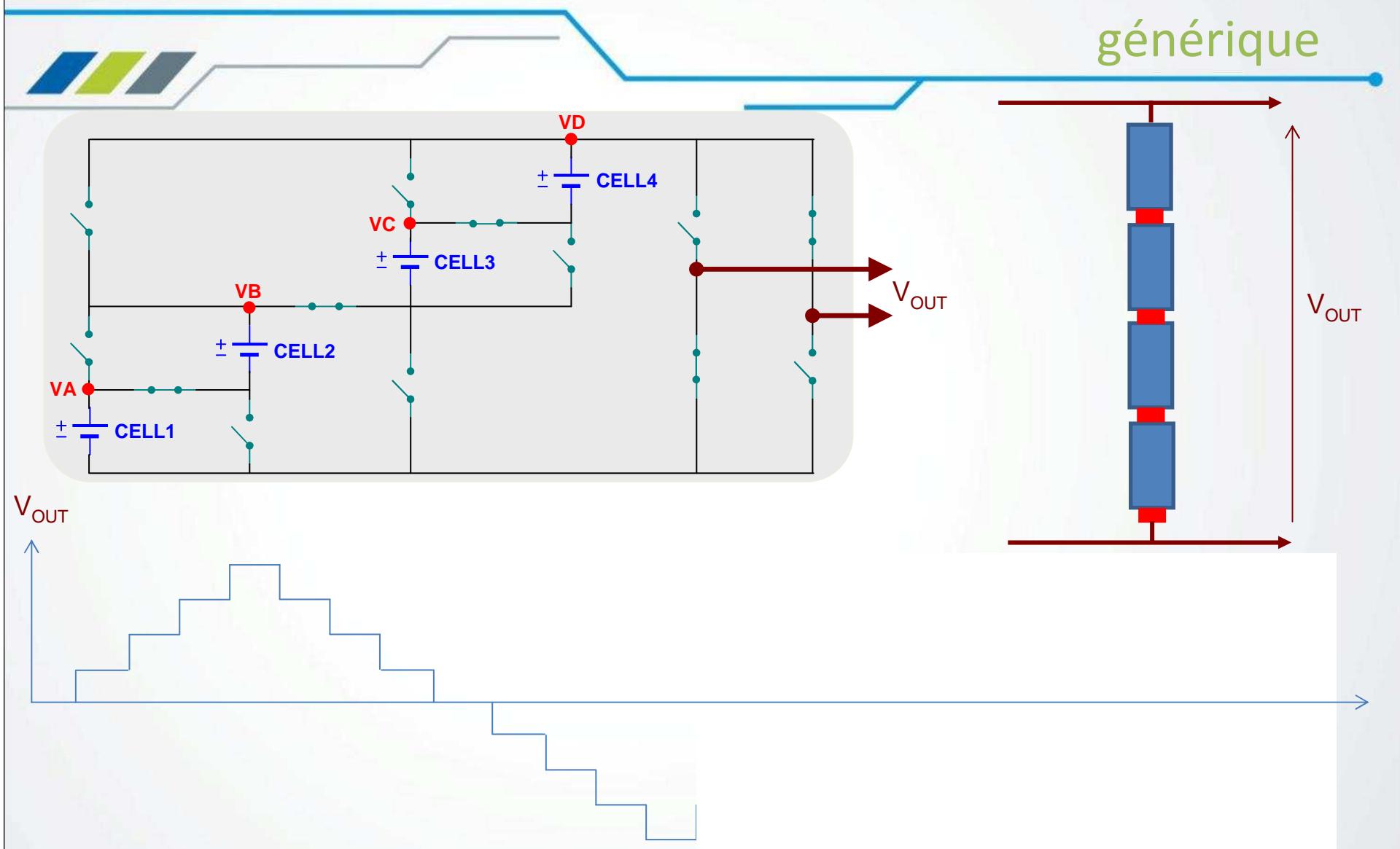
Le BMS commuté : l'architecture générée



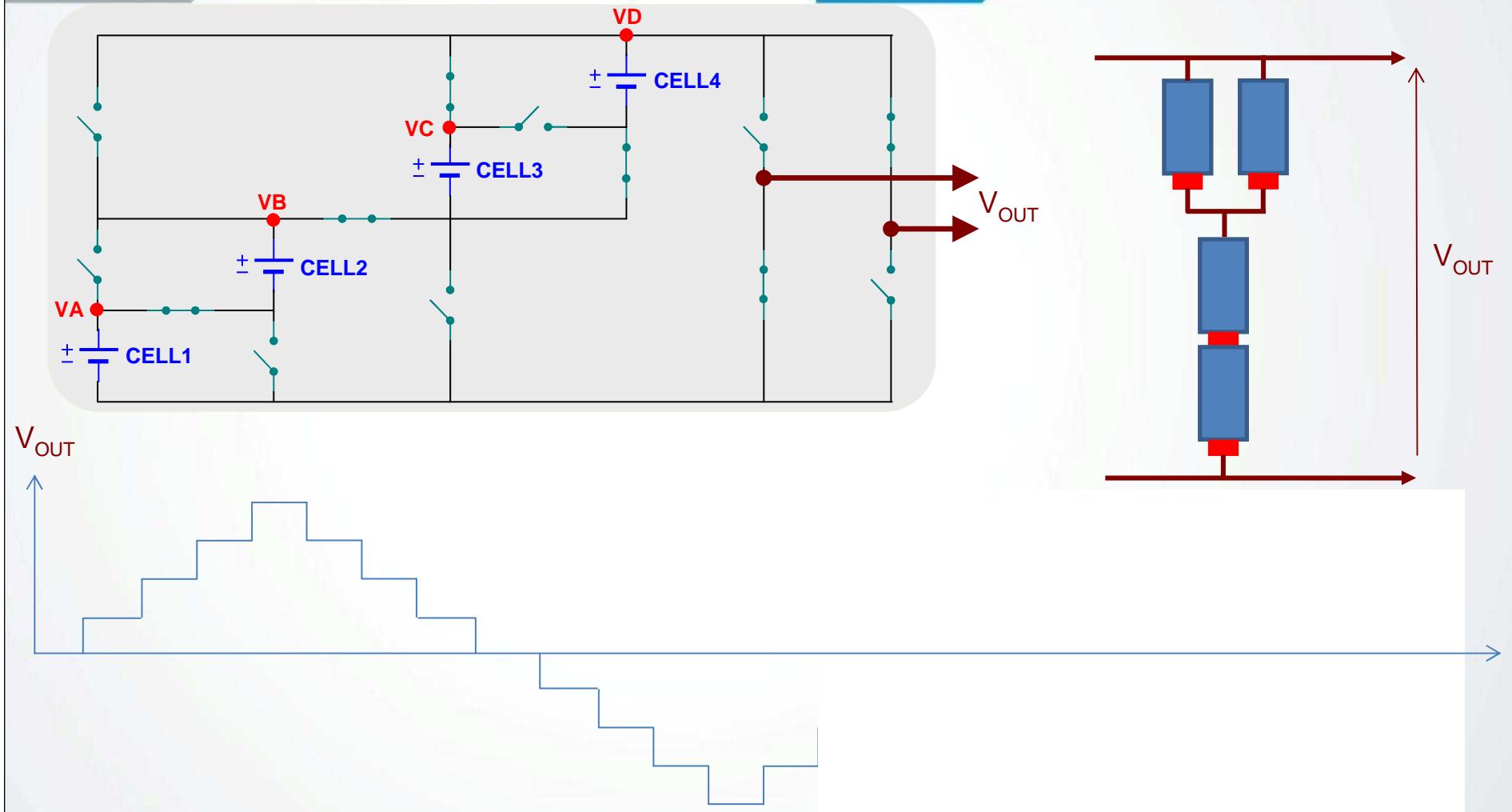
Le BMS commuté : l'architecture générative



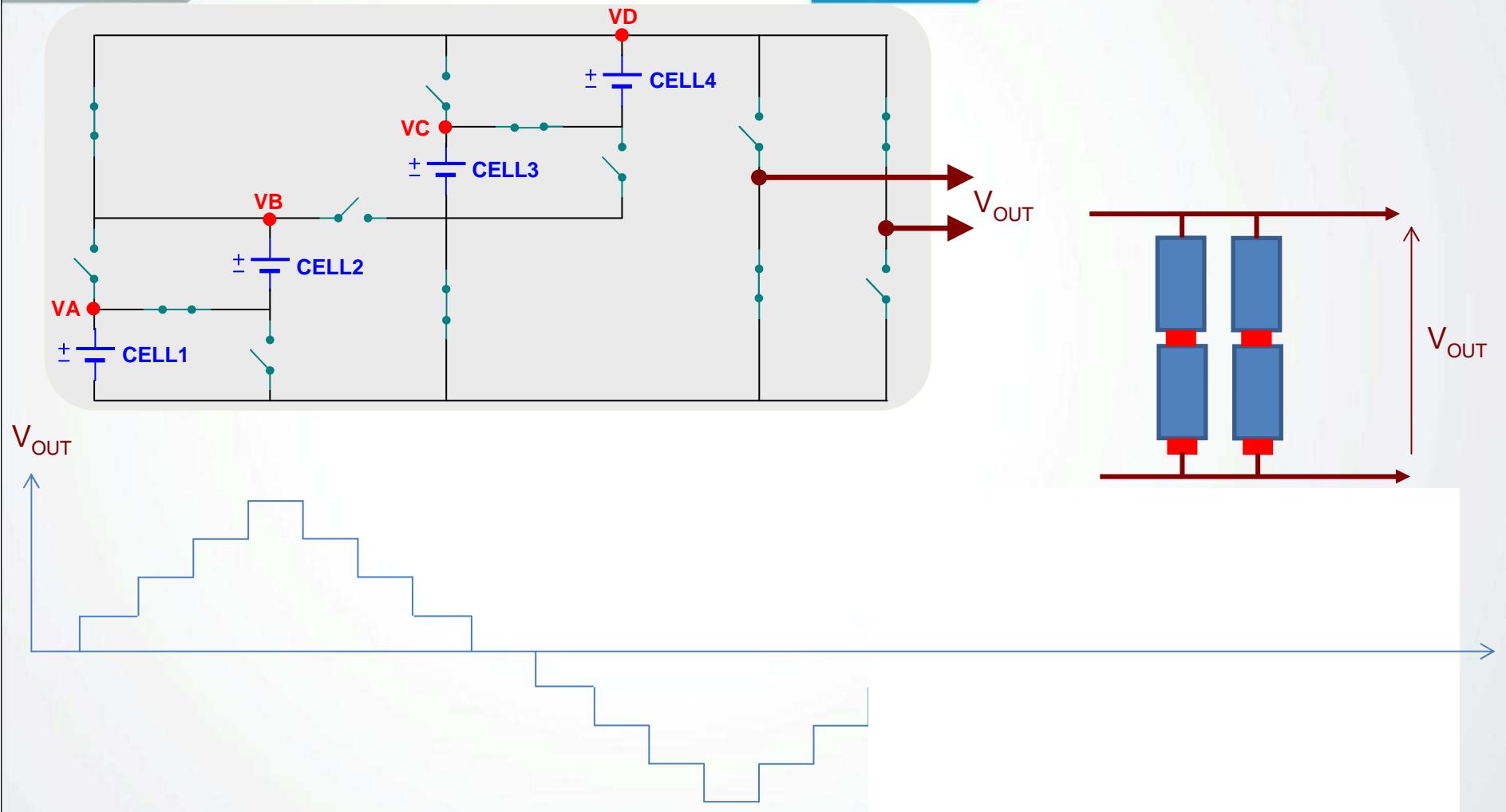
Le BMS commuté : l'architecture générée



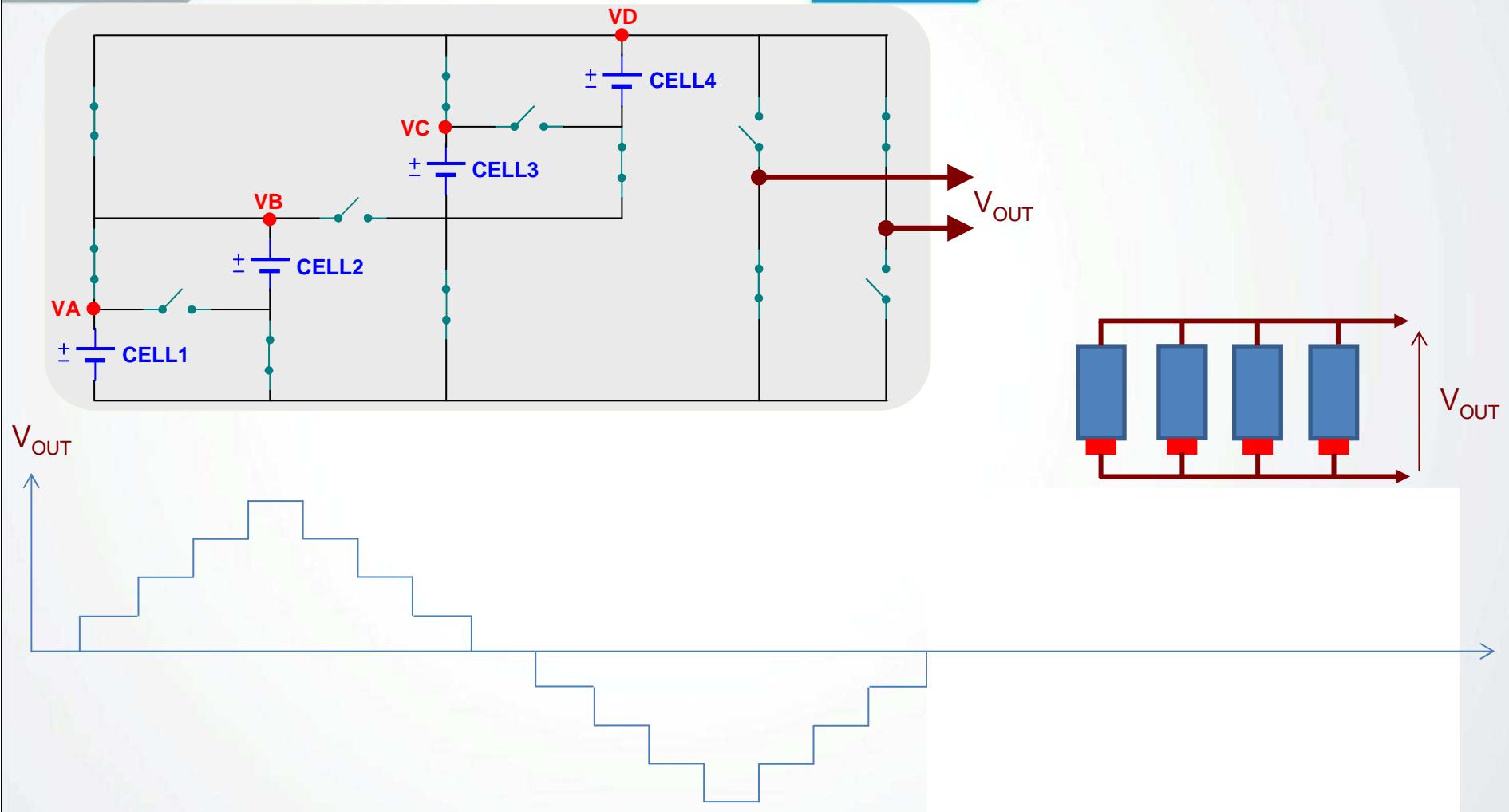
Le BMS commuté : l'architecture générée



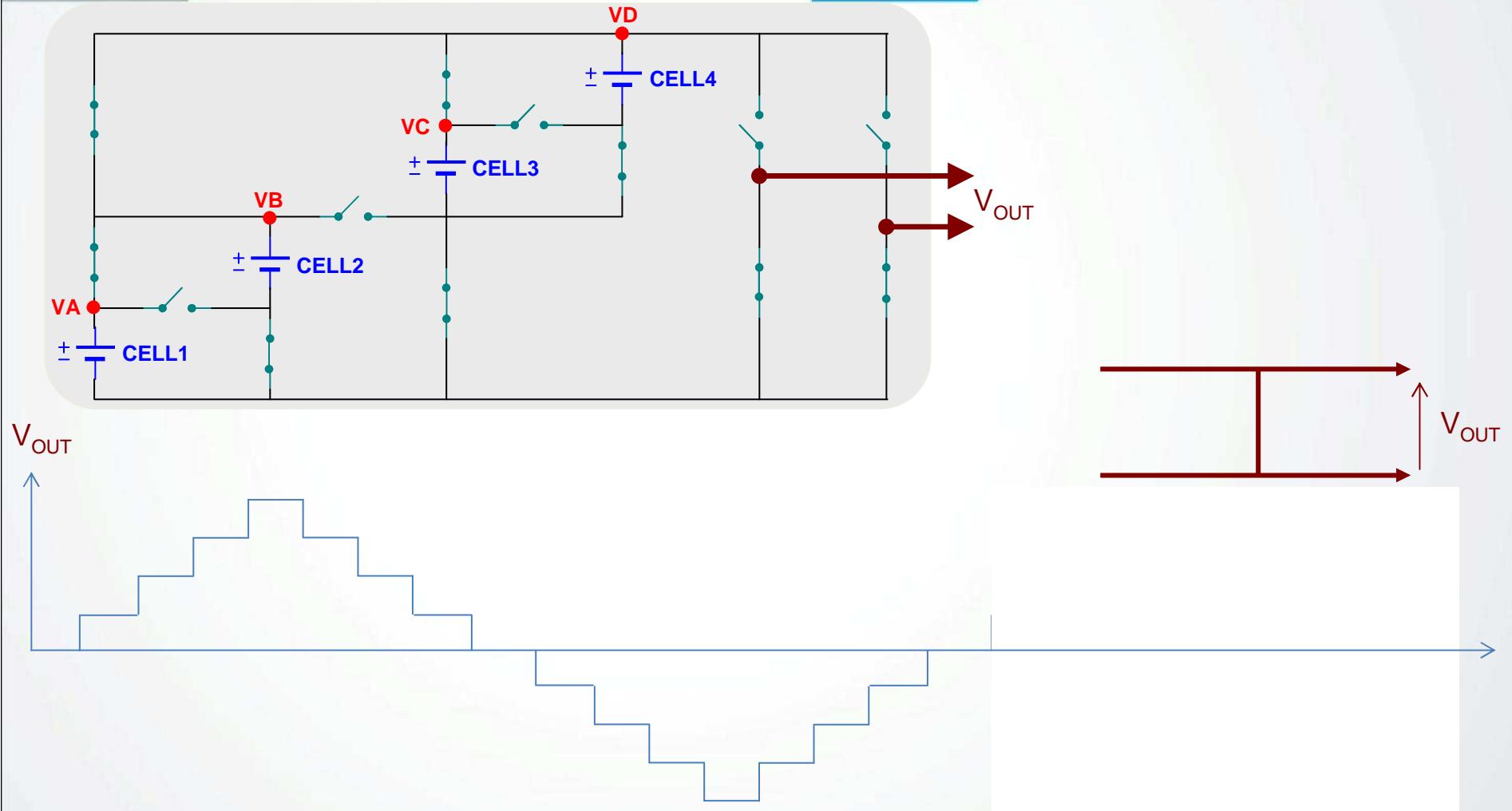
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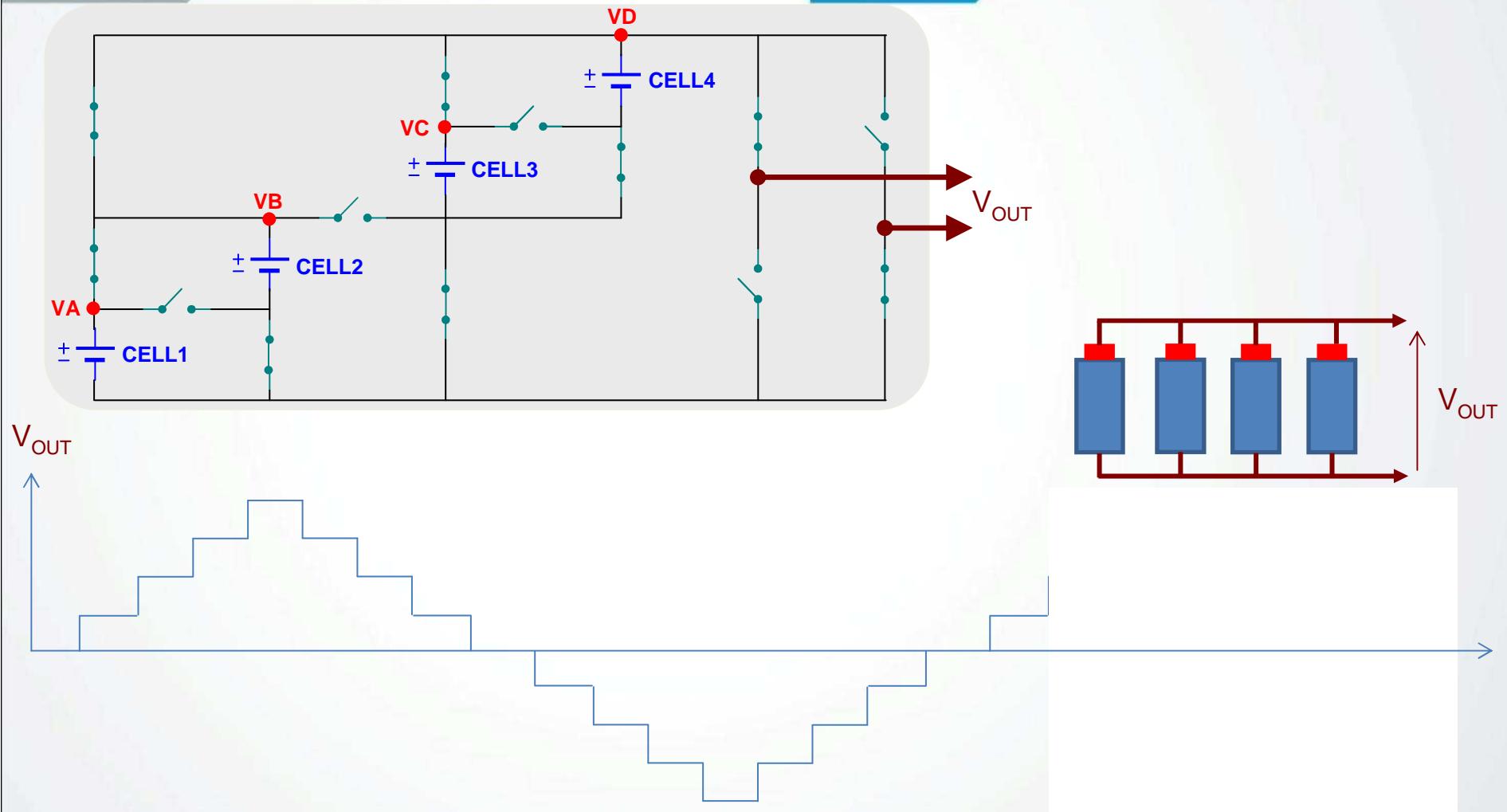
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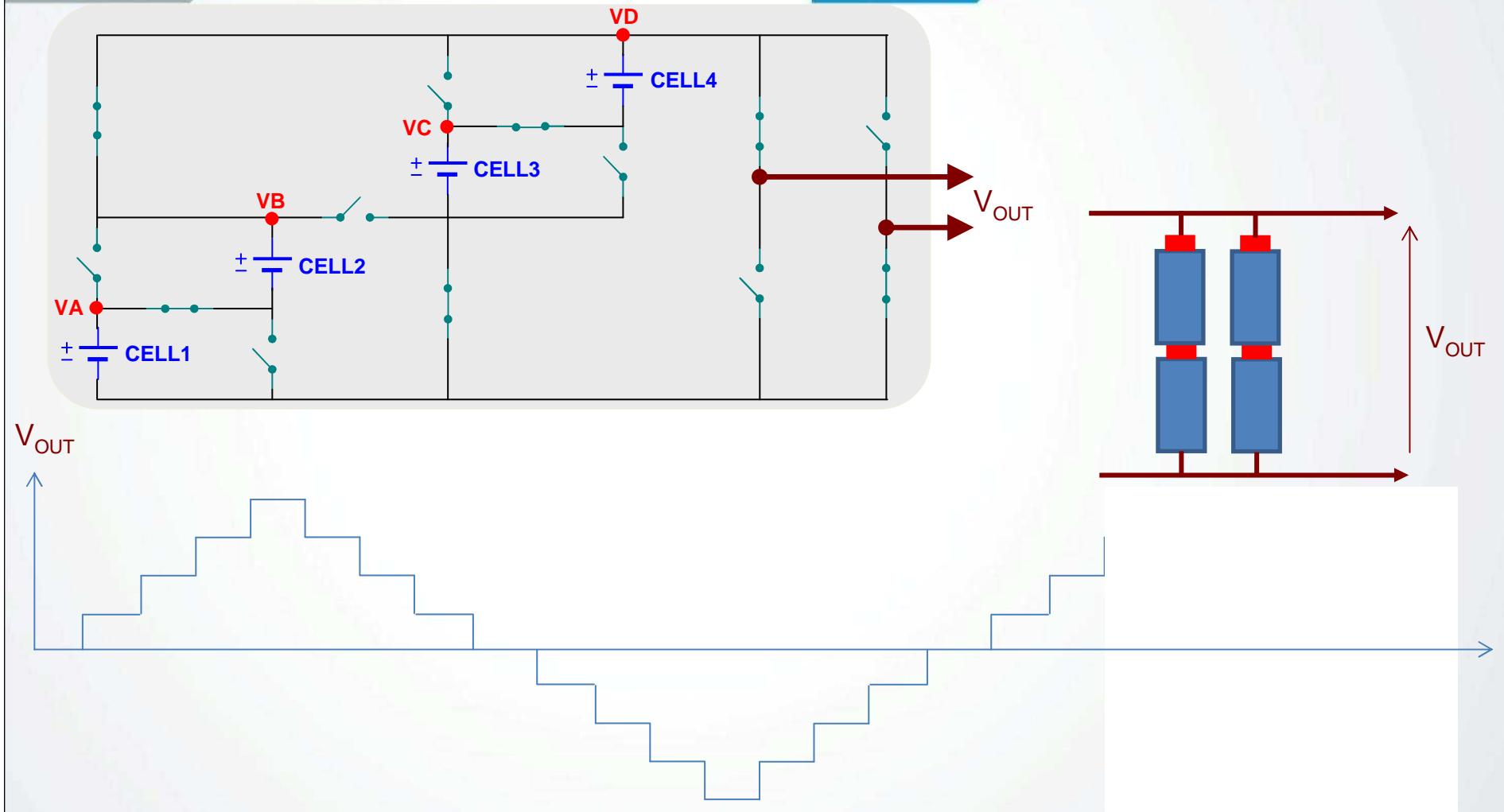
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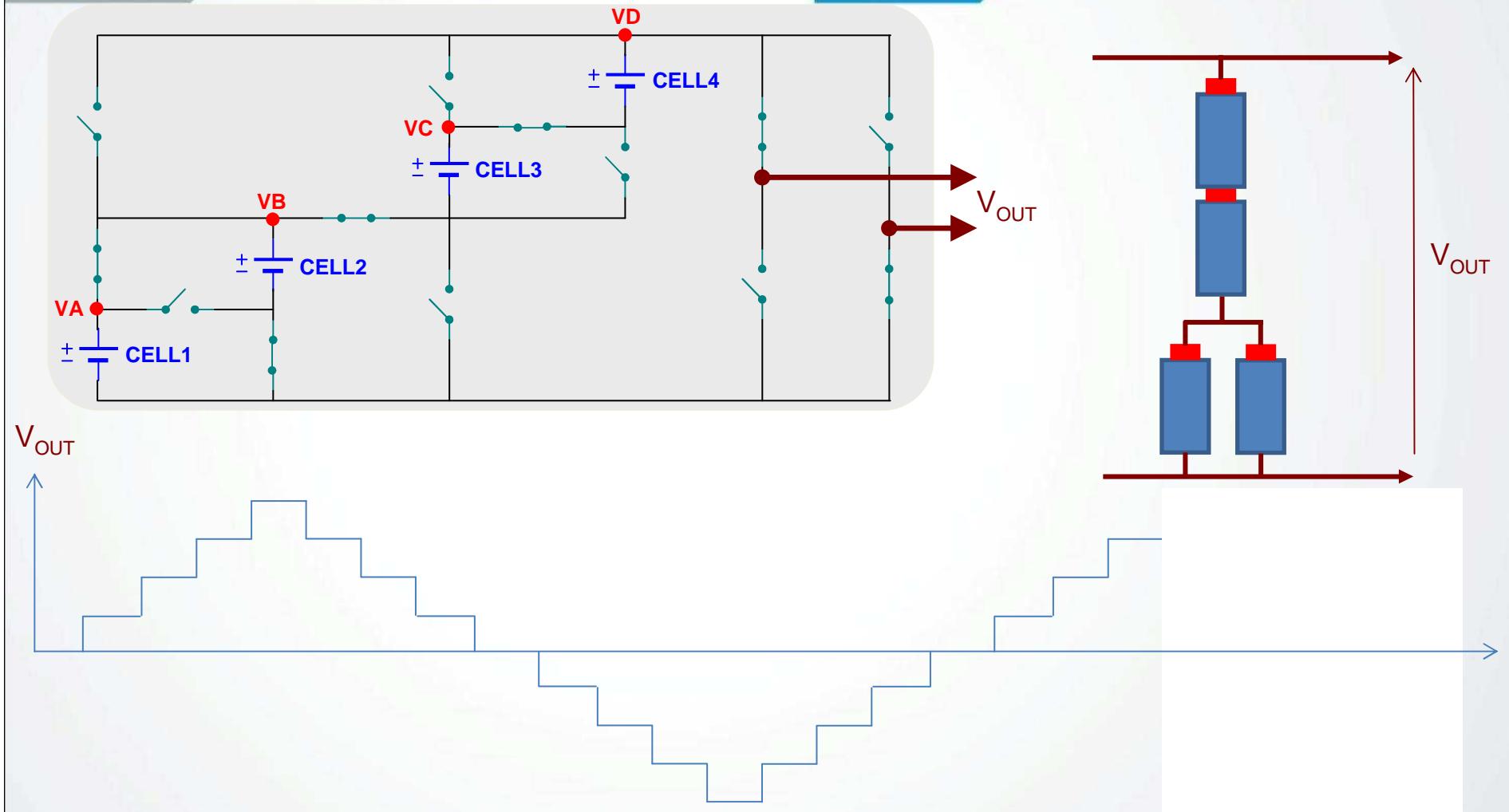
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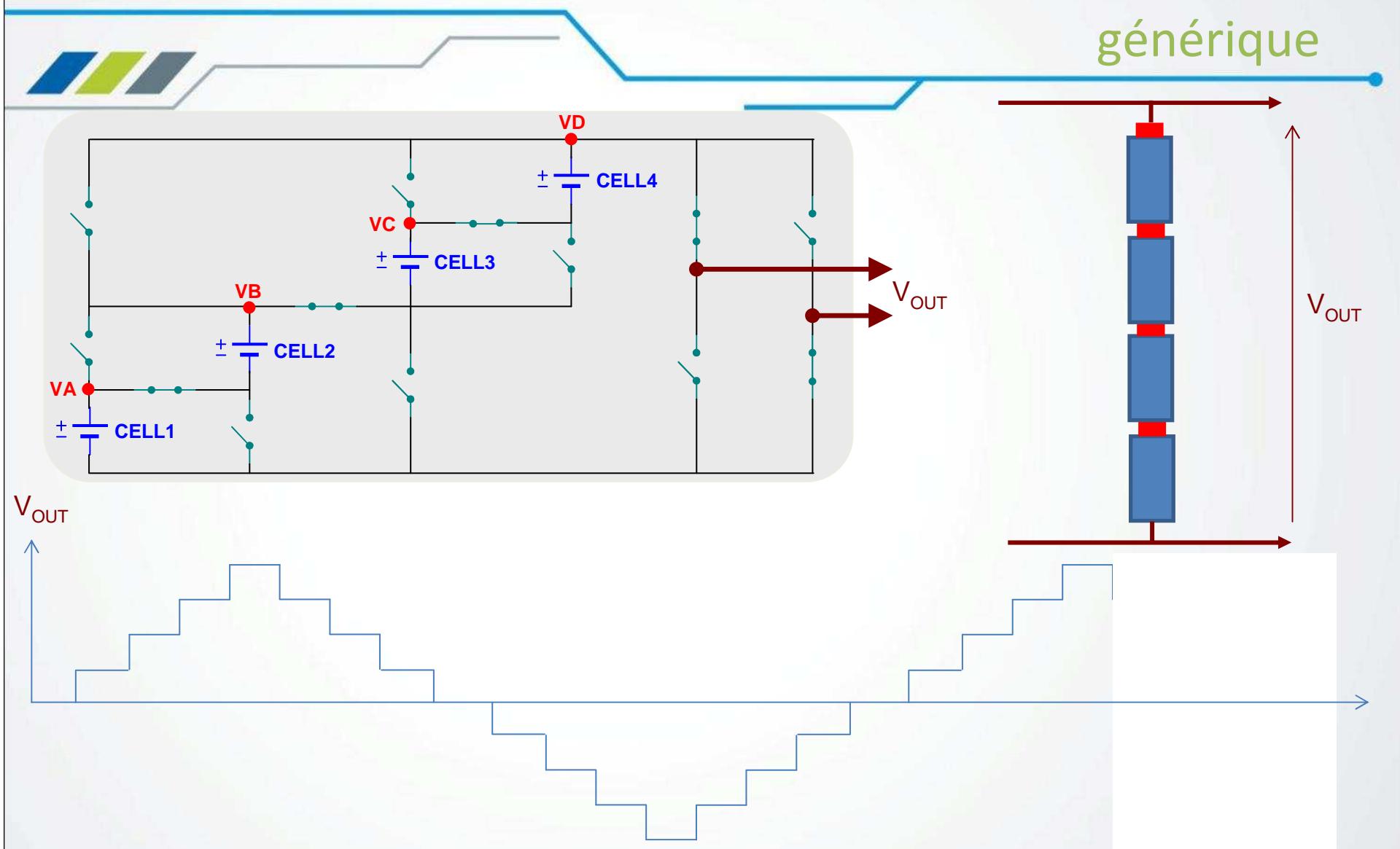
Le BMS commuté : l'architecture générée



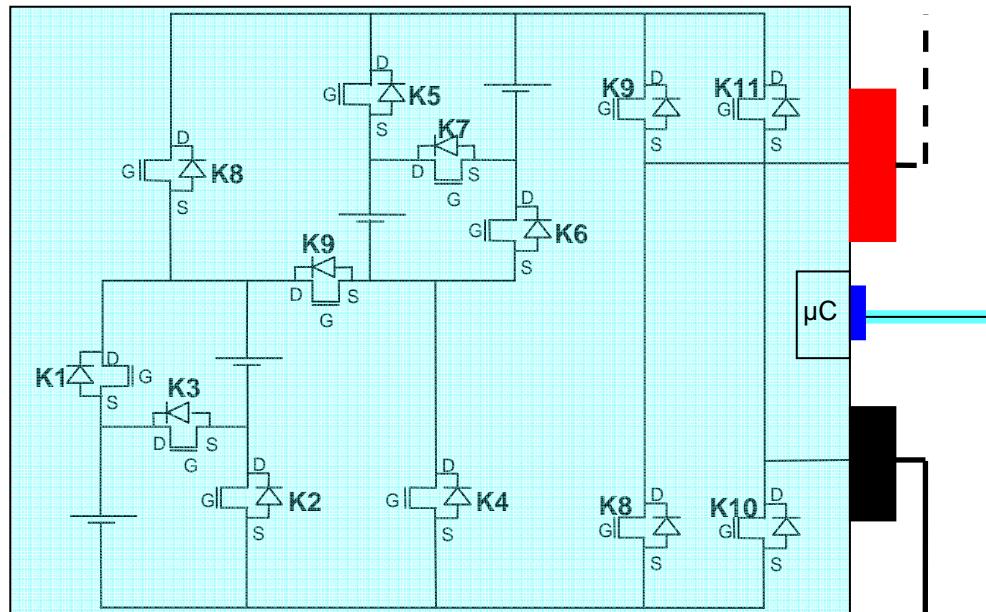
Le BMS commuté : l'architecture générée



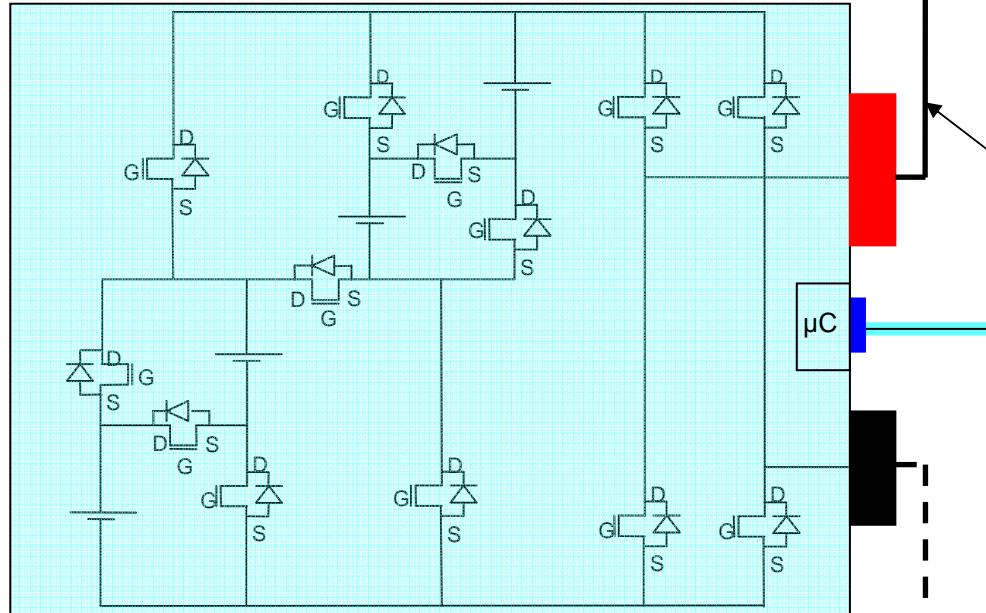
Le BMS commuté : l'architecture générée



Le BMS commuté : l'architecture



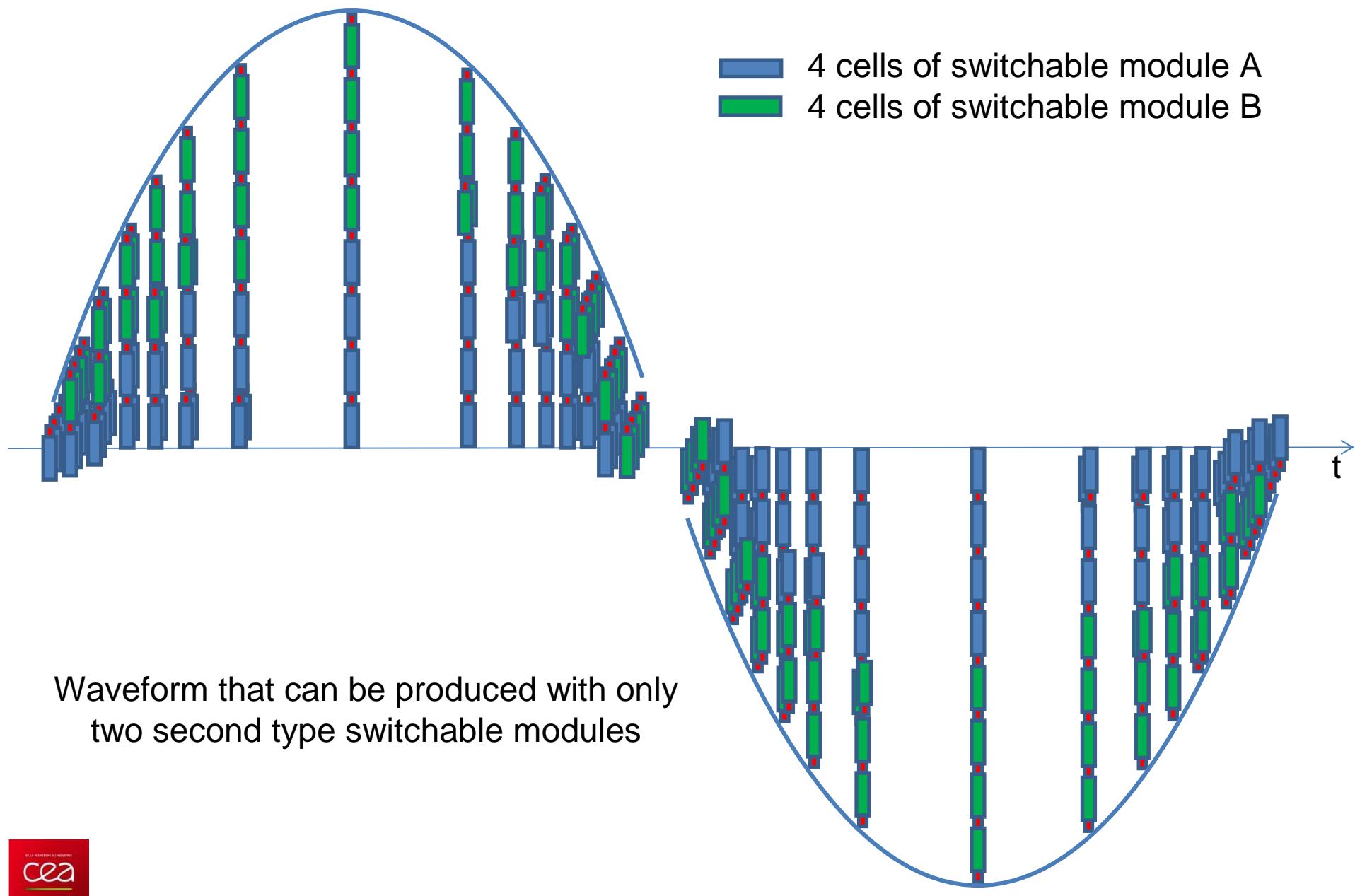
- Highly modulable: each module never see a voltage higher than its one
- Security: no voltage on the module during the storage or in abnormal cases
- The module can manage its own recharge



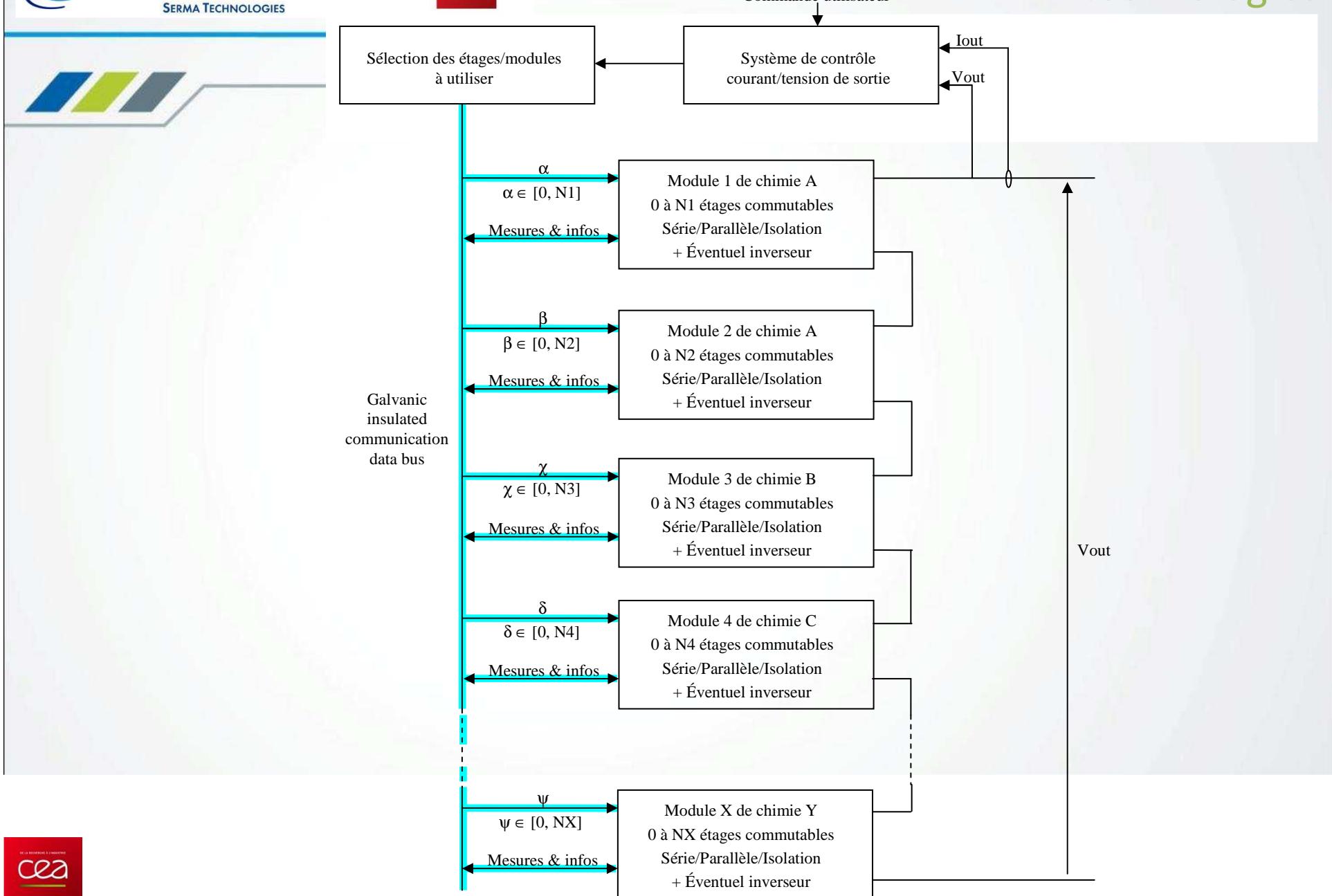
Power bus (serial connexion)

Insulated common data bus

2d prototype: principle

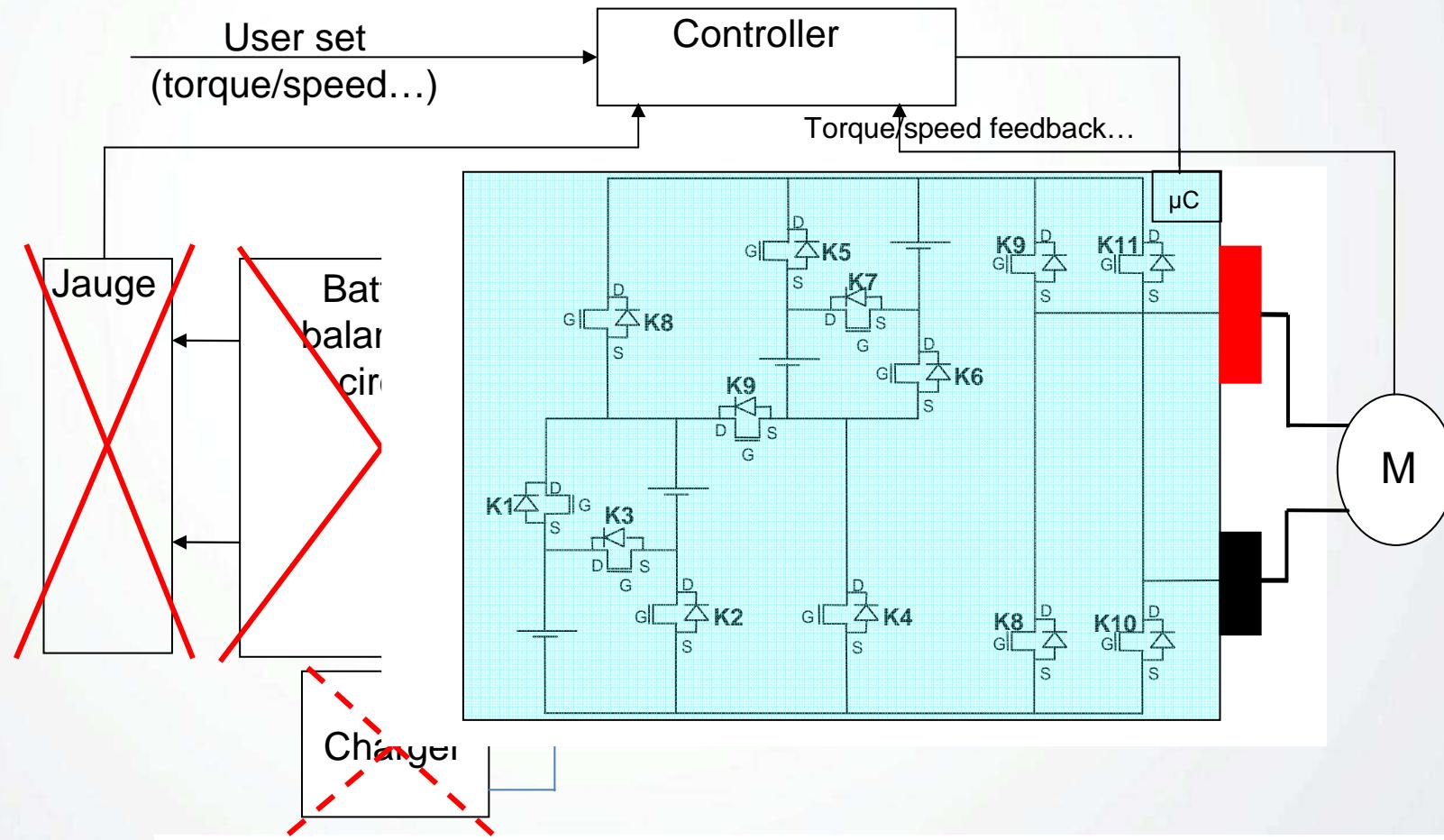


Possible to use various battery technologies



Le BMS commuté : l'architecture générée

Classical architecture versus switching architecture

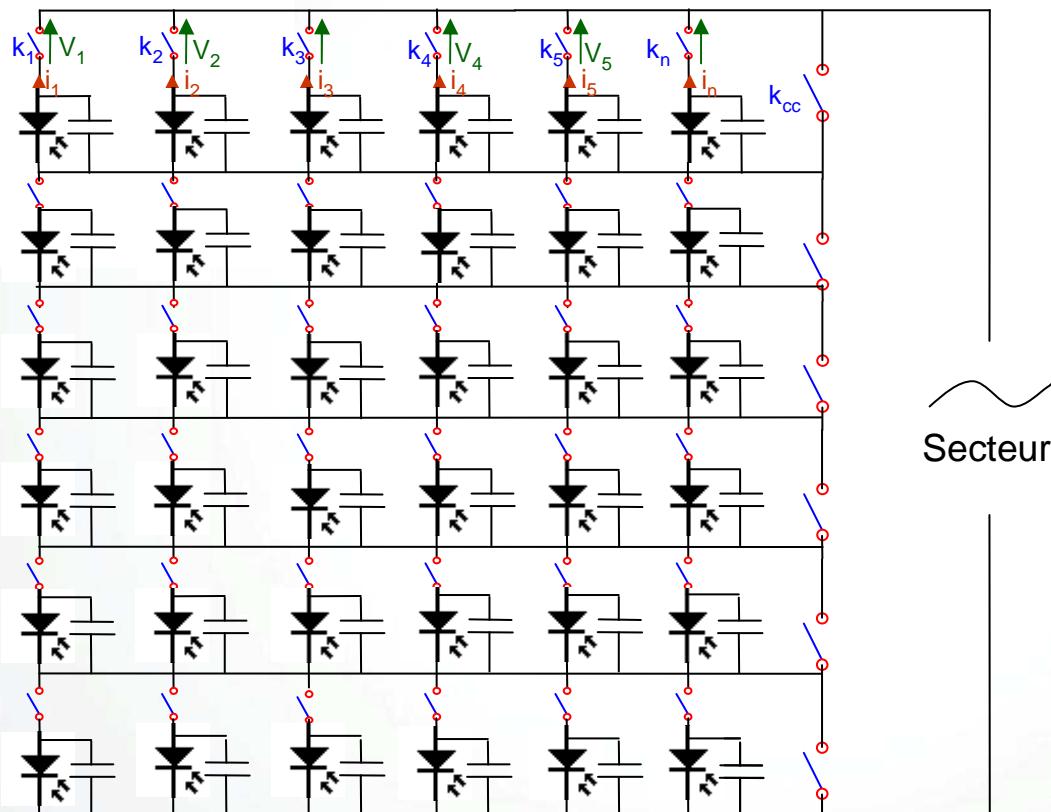


Exemple d'applications :

- Outils/objets électroportatifs
- Alimentation de secours (remplacement groupes électrogènes)
- Eclairages de secours
- Systèmes de transport électriques (bus, voiture, scooter, vélo, bateau, trottinette, jouets...)
- Eclairages solaire avec stockage
- Stockage stationnaire
- Systèmes autonomes

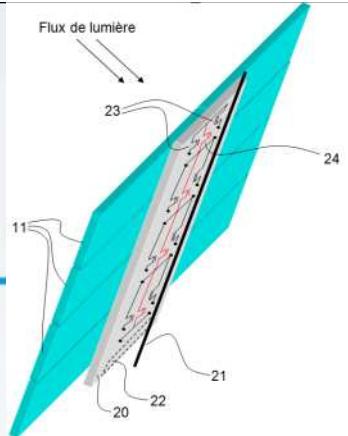
Photovoltaic extension

- Direct connexion to the electrical network



Advantages

- Remove the inverter
- Local MPPT without any costly and heavy inductive converters
- Disconnection of failed cells
- Optimal operation even with some dark areas



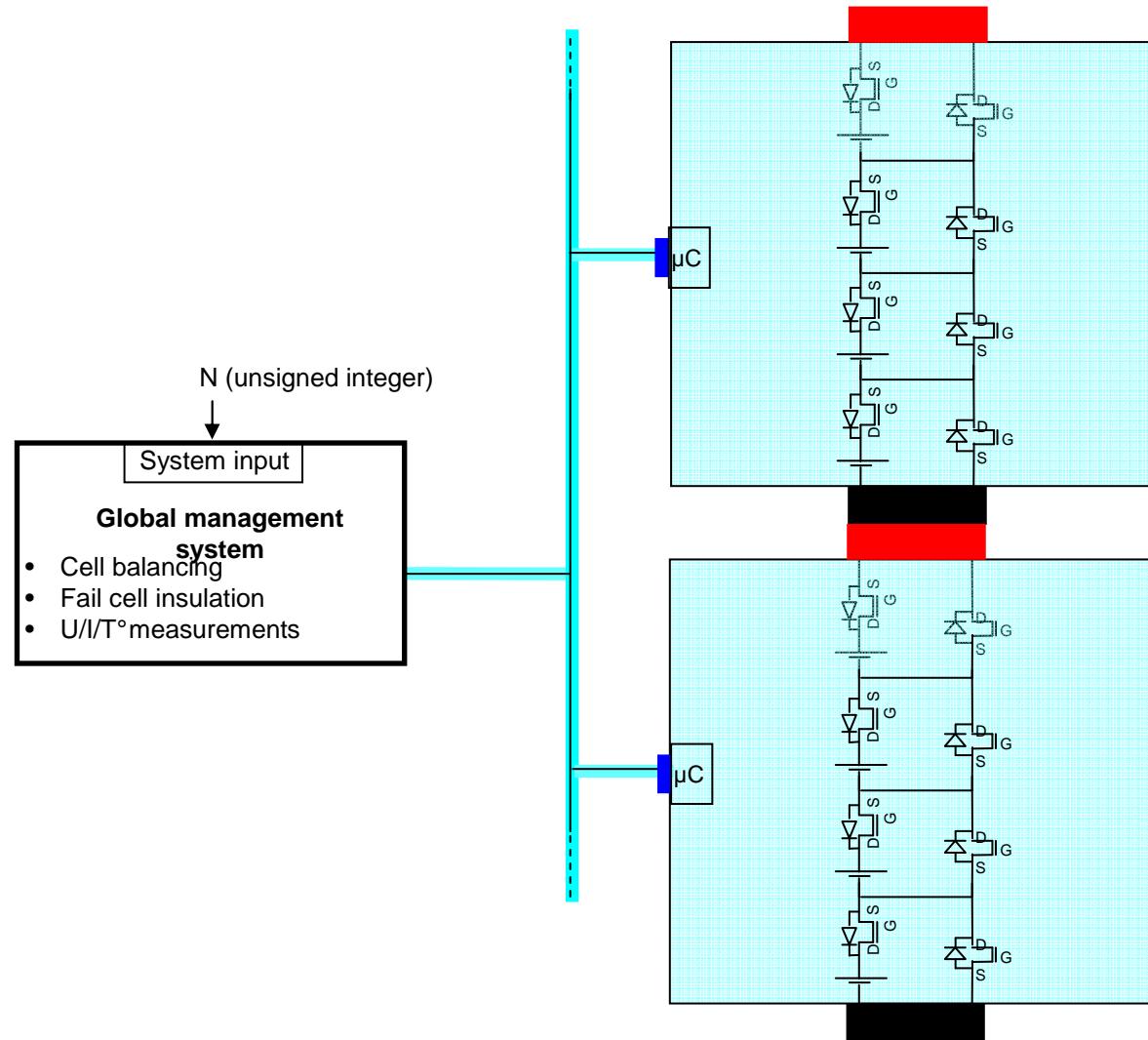
Le BMS commuté : conclusions

- Fonctions classiques
 - ☒ Monitoring des tensions et de température
 - ☒ Mesure du courant
 - ☒ Communication interne / externe
 - ☒ Estimation des indicateurs d'états (charge, santé, ou autres)
- Fonctions avancées
 - ☒ Équilibrage dynamique
 - ☒ Continuité de service en cas de défaut accumulateur
 - ☒ Régulation de la tension de sortie à la demande
 - Fonction d'écrêtage
 - Fonction de commande spécifique (exemple : contrôle moteur)
 - ☒ Optimisation de l'énergie embarquée
 - Par rapport au vieillissement
 - Par rapport à la thermique
 - ☒ Utilisation d'accumulateurs d'état de santé différent
 - ☒ Utilisation d'accumulateurs de chimie différente

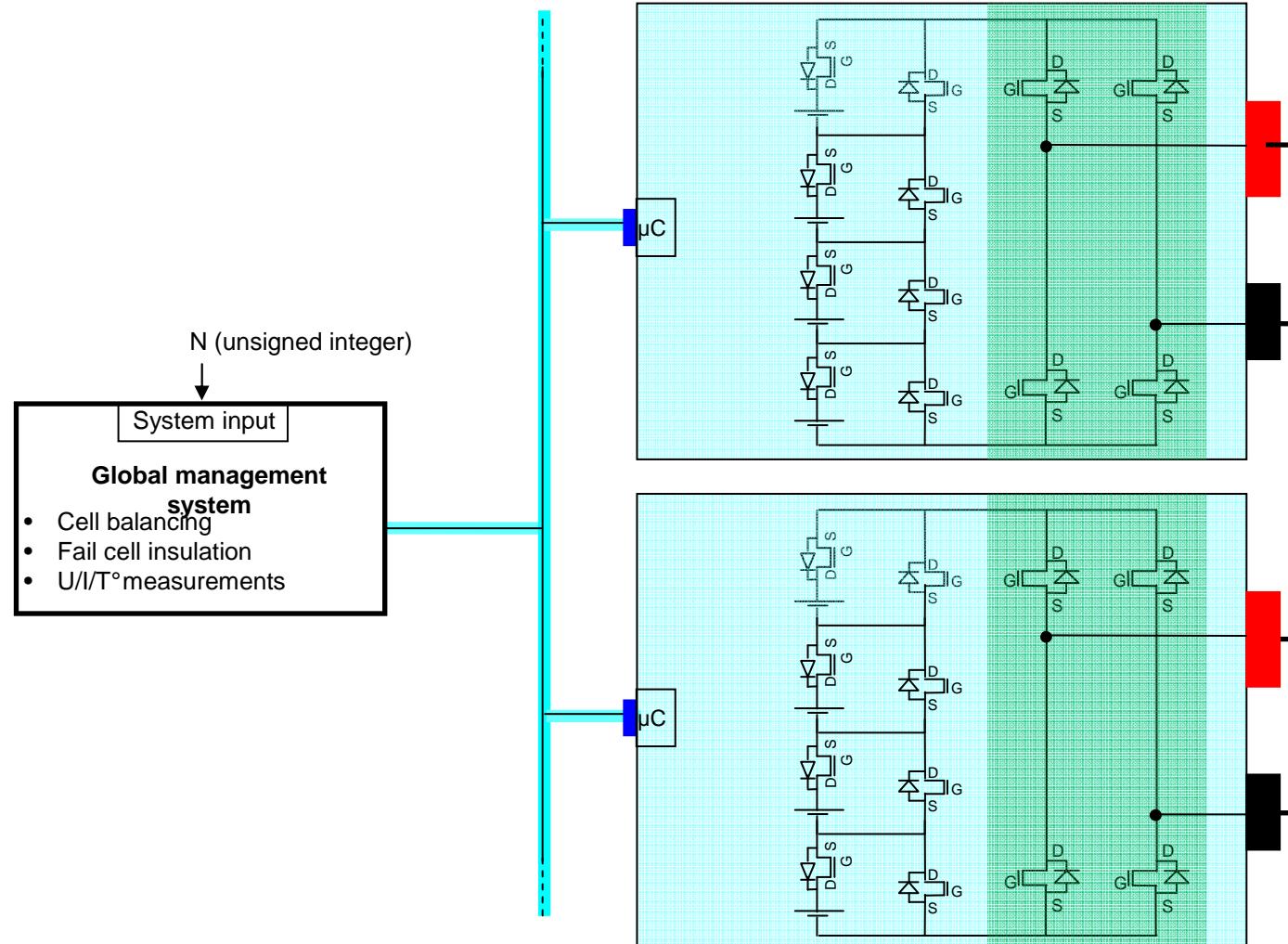


Thank you for your
attention

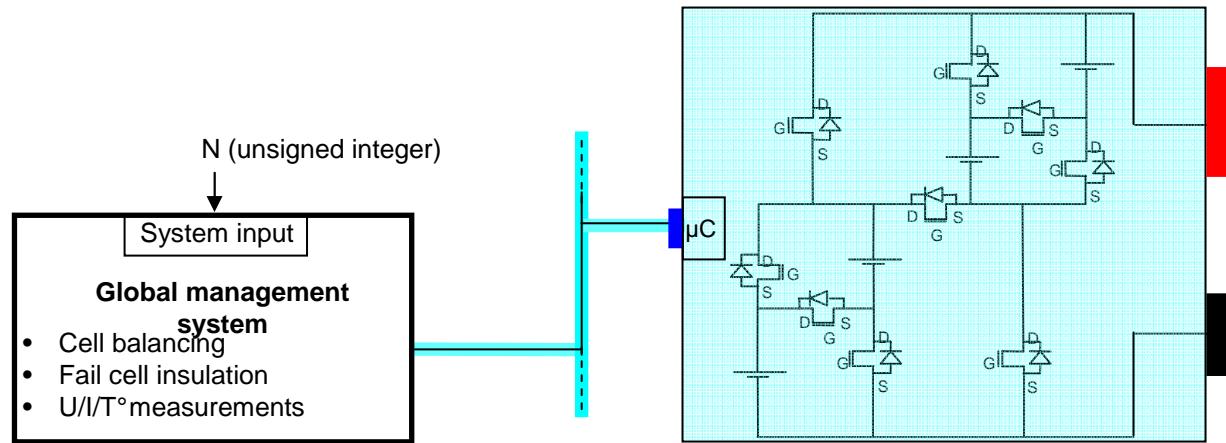
- Carte générique sans inversion de tension et sans mise en parallèle



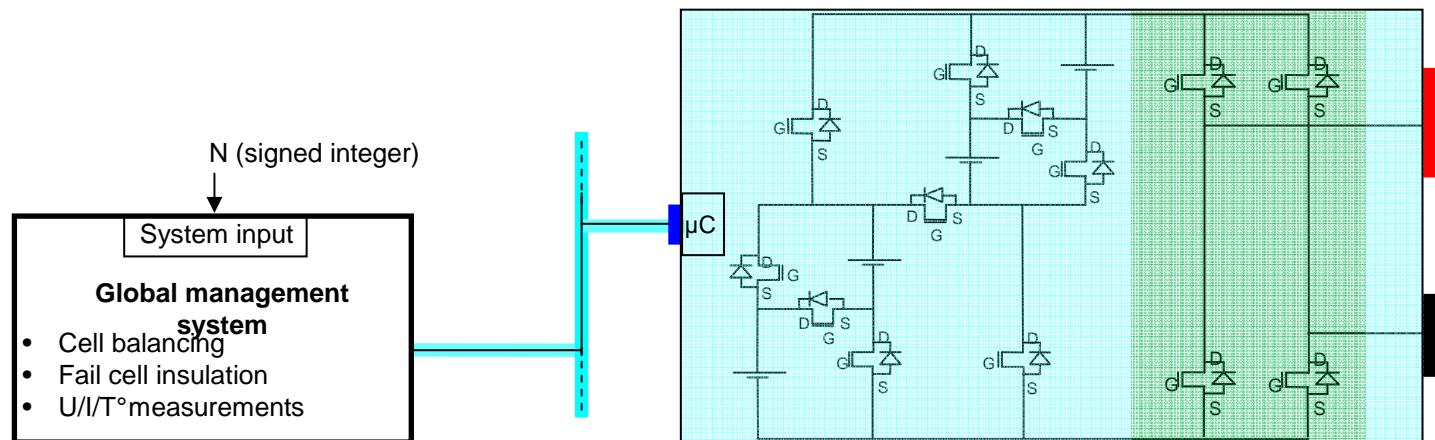
- Carte générique avec inversion de tension et sans mise en parallèle



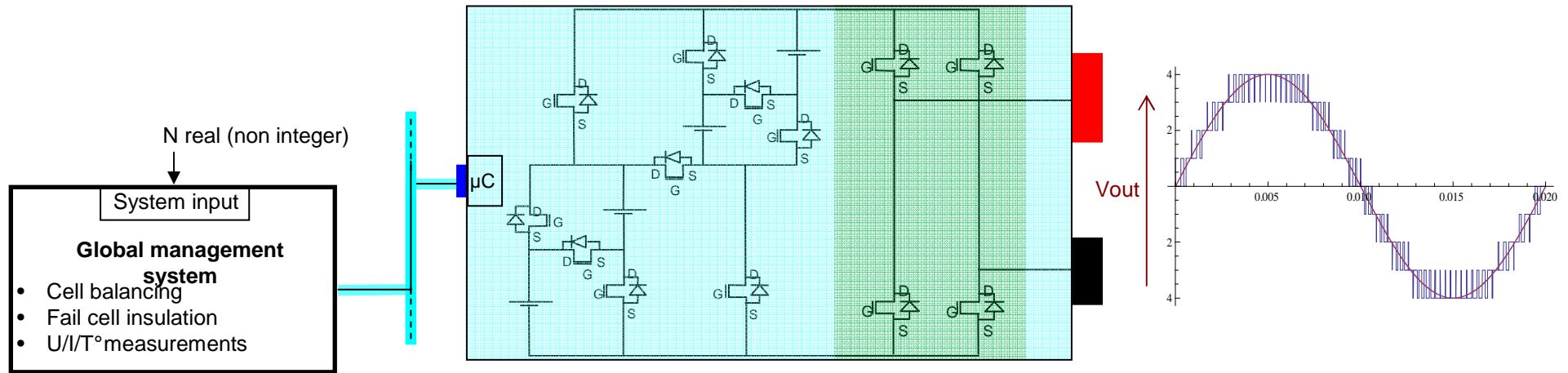
- Carte générique sans inversion de tension mais avec mise en parallèle



- Option 1 : avec inversion de tension et mise en parallèle



- Option 2 : avec niveaux intermédiaires (PWM inter-niveaux)



- Option 3 : avec pilotage system CEA

