





# Battery Monitoring System

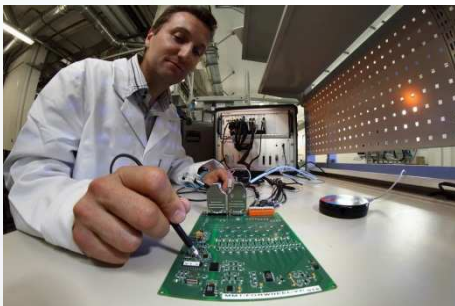
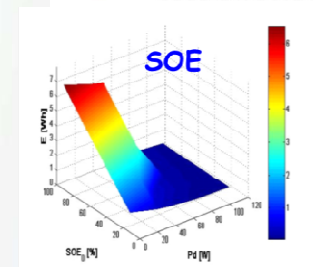
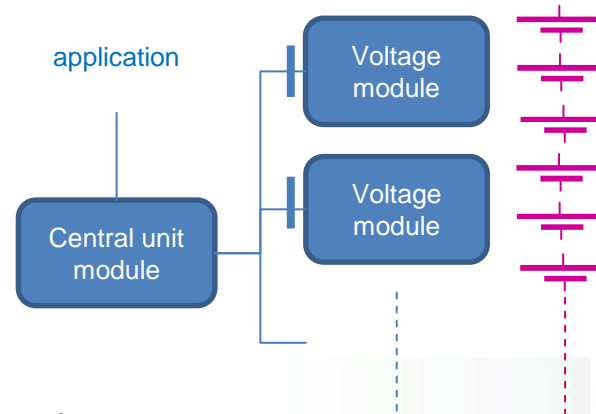
G. Despesse, S. Gery, S. Le Chat, S. Brulais, L. Cassarino, P.A. Ramahefa-Andry, J-P. Gros  
CEA LETI&LITEN

## BMS – rôle et fonctions

- BMS = Battery Management System
- Fonctions principales
  - Assurer le fonctionnement de la batterie dans des **conditions sécurisées**
    - Monitoring des tensions, de température
  - Permettre un **fonctionnement performant**
    - Équilibrage des cellules pour optimiser l'énergie disponible
    - Fournir l'état de charge de la batterie
- Autres fonctions
  - Pilotage des organes de sécurité
    - Information ou contrôle de l'ouverture du circuit de puissance
  - Estimateurs d'états spécifiques
    - État de santé de la batterie (ou vieillissement)
    - État d'énergie de la batterie 
    - Courant ou puissance maximale disponible
  - Contrôle de l'isolement du pack batterie
  - Gestion du management thermique (exemple : pilotage de ventilateurs ...)
  - Isolation d'un accumulateur défectueux 

# Modular BMS

- Sensors characterization
- Expert on Li-ion BMS
  - Voltage measurements module
    - Passive cells balancing
  - Central unit module
    - High precision current measurement
    - Algorithms and electrochemical indicators embedded
  - CAN protocole communication
- BMS prototypes based on proven concepts



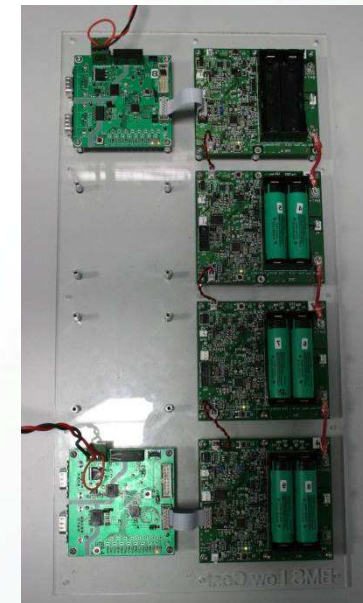
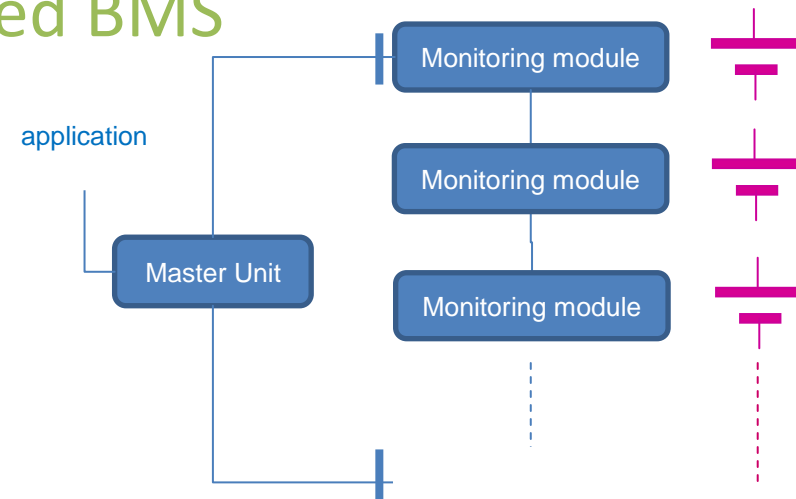
8 projects  
10 to 80 kWh  
< 50 000 km

transferred to industry

TRL  
8

## Chained BMS

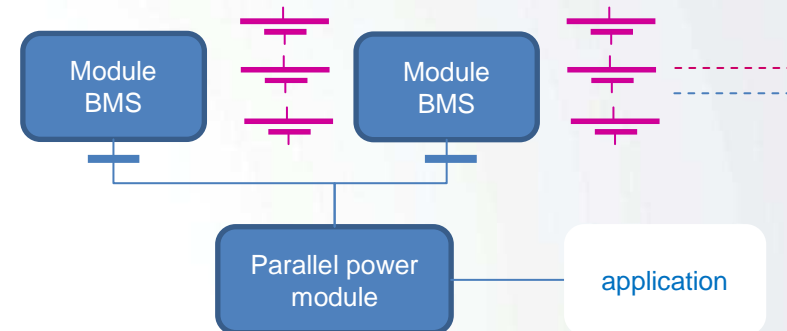
- Simplified electronic
- Redondance optimization
  - Measurement
  - Communications
- Local balancing
- Local calculators
- Isolation optimization



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## Parallel plug BMS

- Local BMS for module
  - Voltage module measurements
  - Passive cells balancing
  - Current module measurement
  - Algorithms and electrochemical indicators embedded
  - Internal and external communication
- Power module to parallel plug
  - Power current control strategy

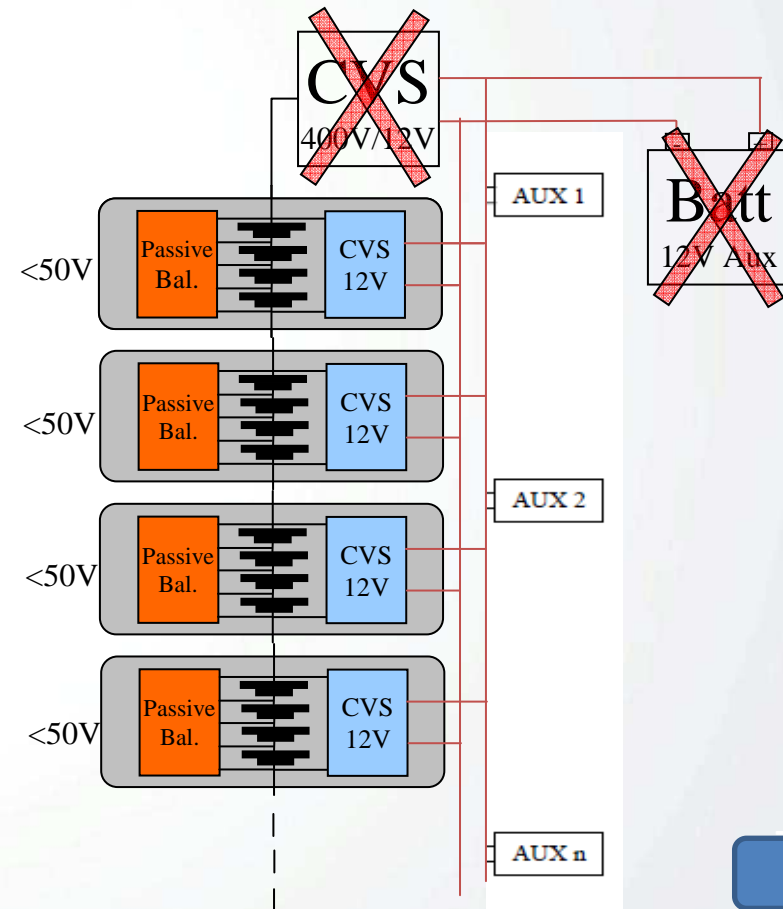
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# Active balancing BMS

- High current
  - cell balancing
  - module balancing
- Modularity
- Safety
  - Modules voltage < 50 V
  - 12 CVS redundancy



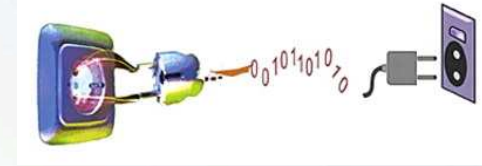
Redistribution topologies  
Cell-to-battery, battery-to-cell, bidirectional

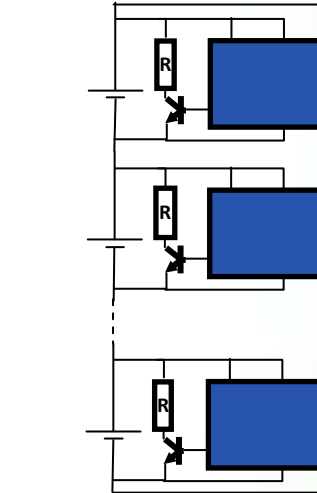


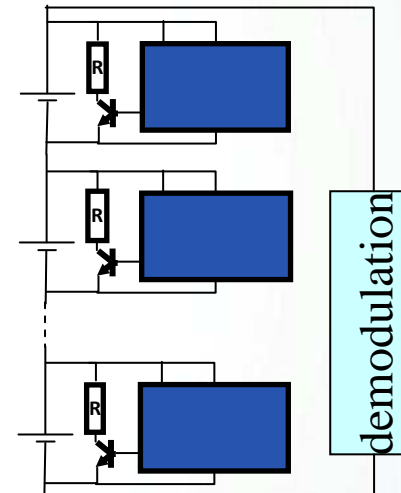
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# Communication means



- Power line current of energy sources
    - On battery cells
    - On PV
  - Specific bus
    - High rate
    - redundant
  - Simply analogic module
  - Standard
- 



# Modulation /demodulation



*transferred to industry*

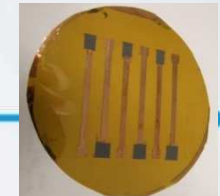
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Specific  
measurements

In collaboration with LETI/DCOS

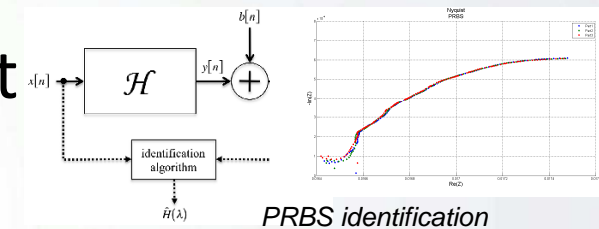


Active measurement

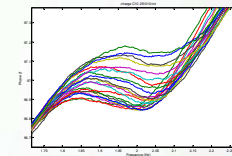
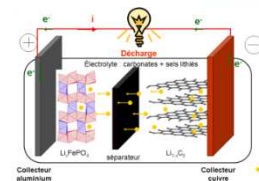


Reference electrode

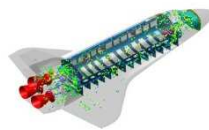
- Electric impedance measurement
- Mechanical impedance measurement
- Security battery measurements
  - Inside battery sensors
- Short circuit detection
- Electric arc measurement



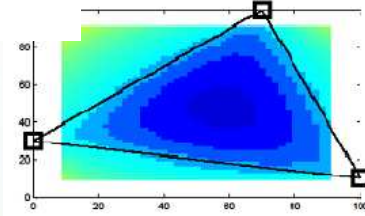
PRBS identification



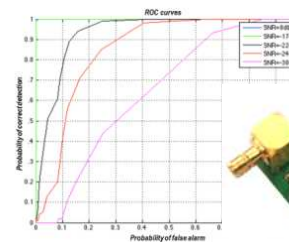
Inside mechanical impedance tracking



localization



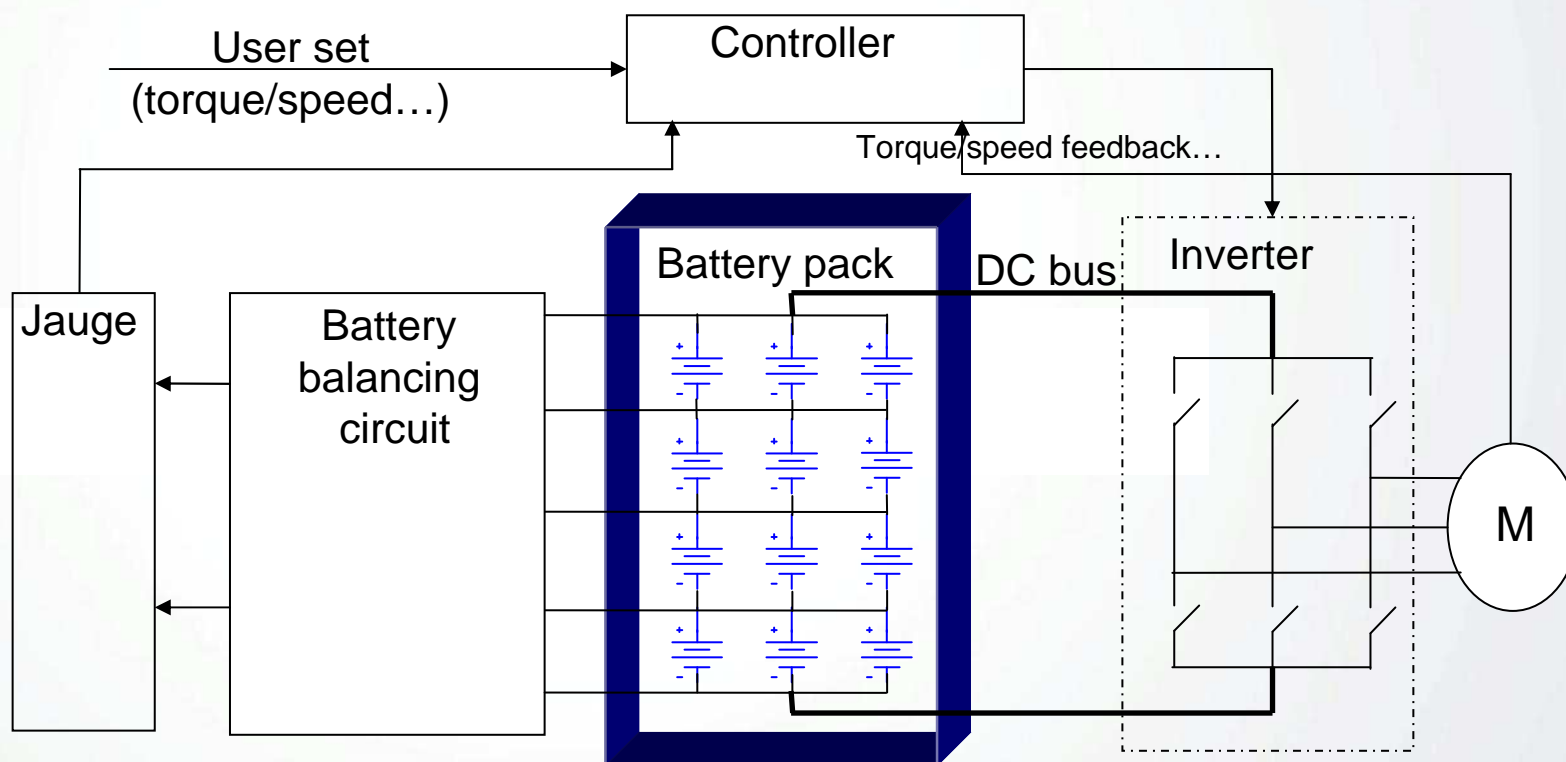
In situ detection



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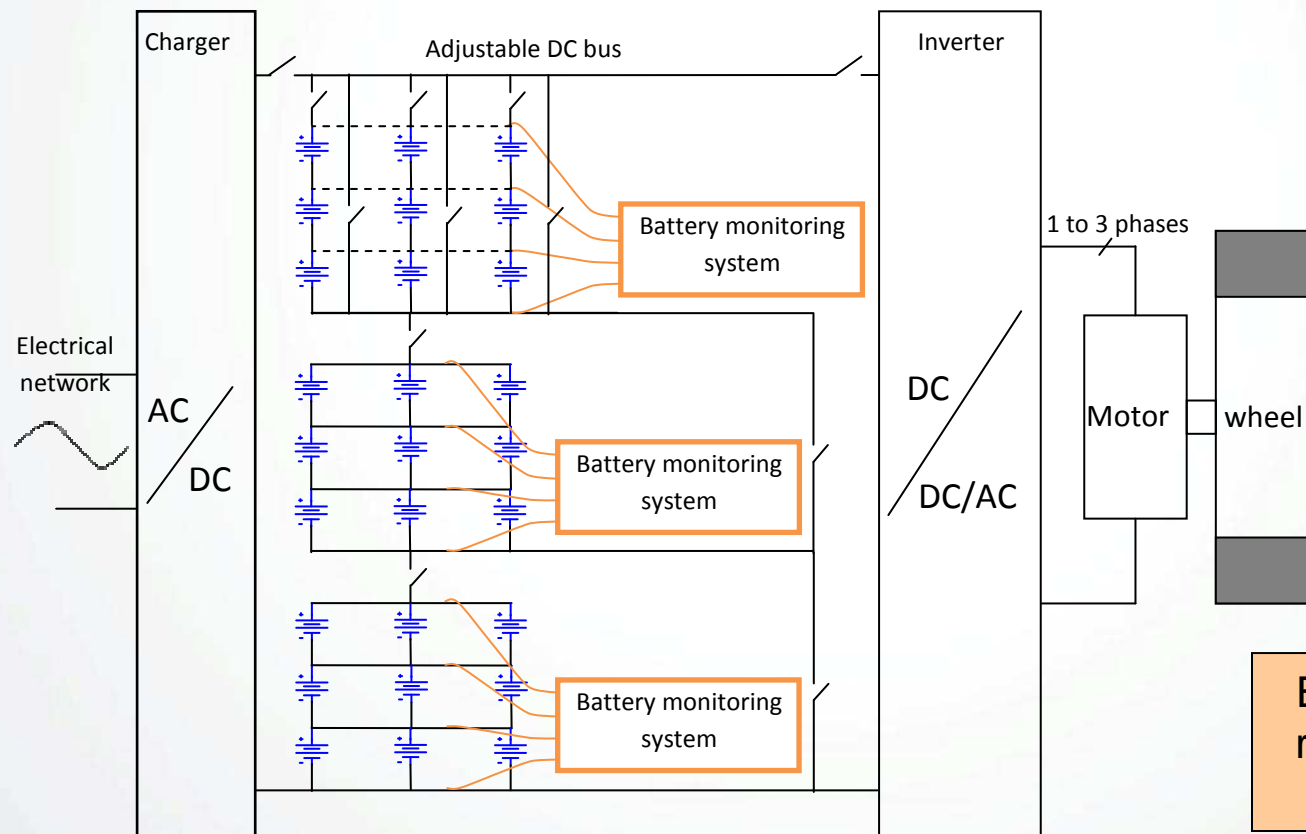


## Actual electrical propulsion principle



## How to overcome a battery cell failure

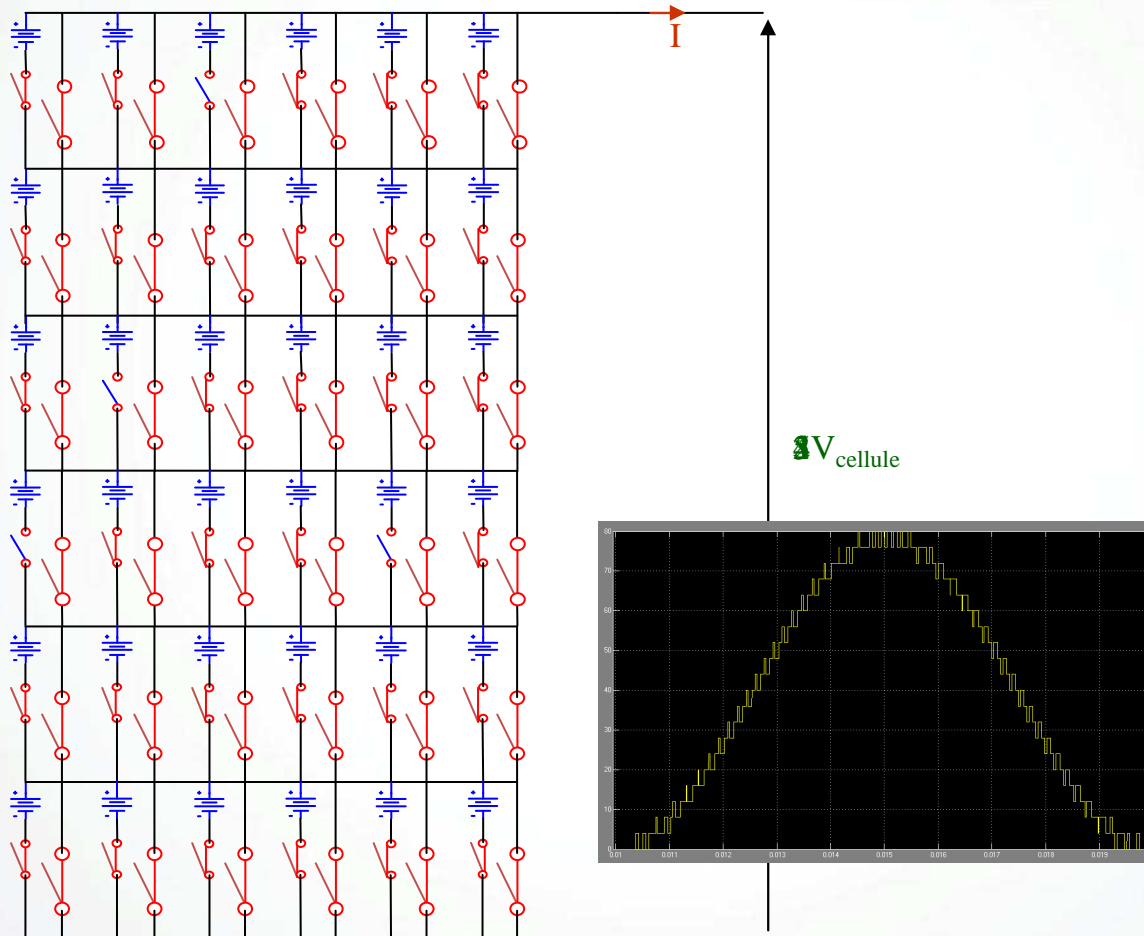
- Actually if one cell is failed, all the battery pack is impacted as all the battery cell are in serial
- One solution is to cut the battery pack in several disconnectables modules



- Adjustable DC bus voltage
- As the current can be large (up to 300 A) several transistors in parallel are required -> each module can be cut in several columns at same cost
- As transistor cost is quite proportionnal to its voltage over 25 V, it is interesting to cut the battery pack in modules voltage of around 20 V (4 to 5 serial Li-ion cells)

But that solution continues to require a charger, an inverter and a cell balancing circuit

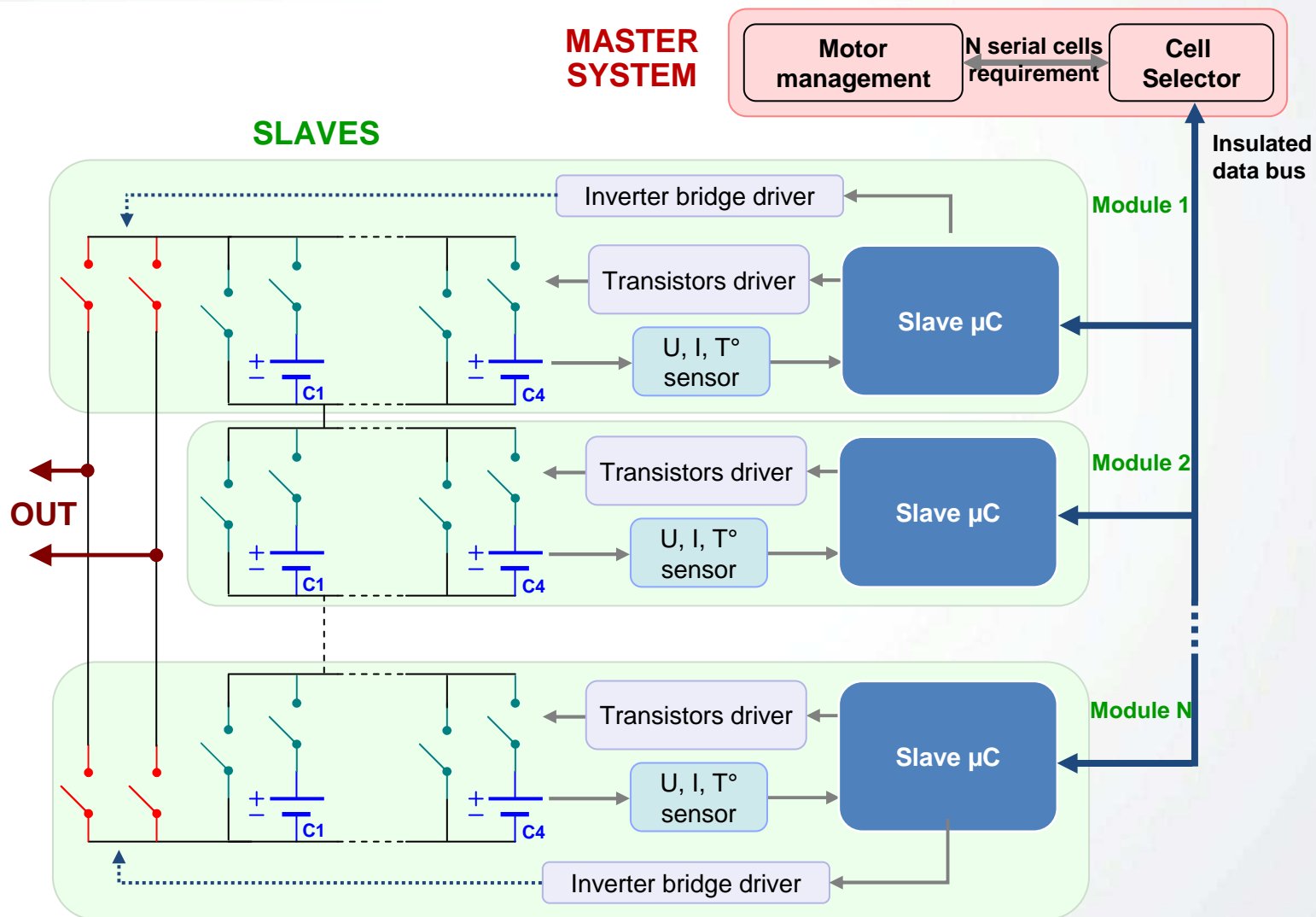
# Toward modules having only one serial cell



- Cell balancing in real time and with the full useful flowing current → no losses and no additional weight or cost for cell balancing
- No high frequency and high voltage switching → very low commutations losses
- Can work as well for charge or discharge
- Replace the inverter
- Replace the charger
- Replace the costly converter of high speed charger stations
- Improve the current and voltage waveforms applied to the electrical motor or get on the electrical network
- Can reduce by a factor five the losses compare to an embeddable inverter

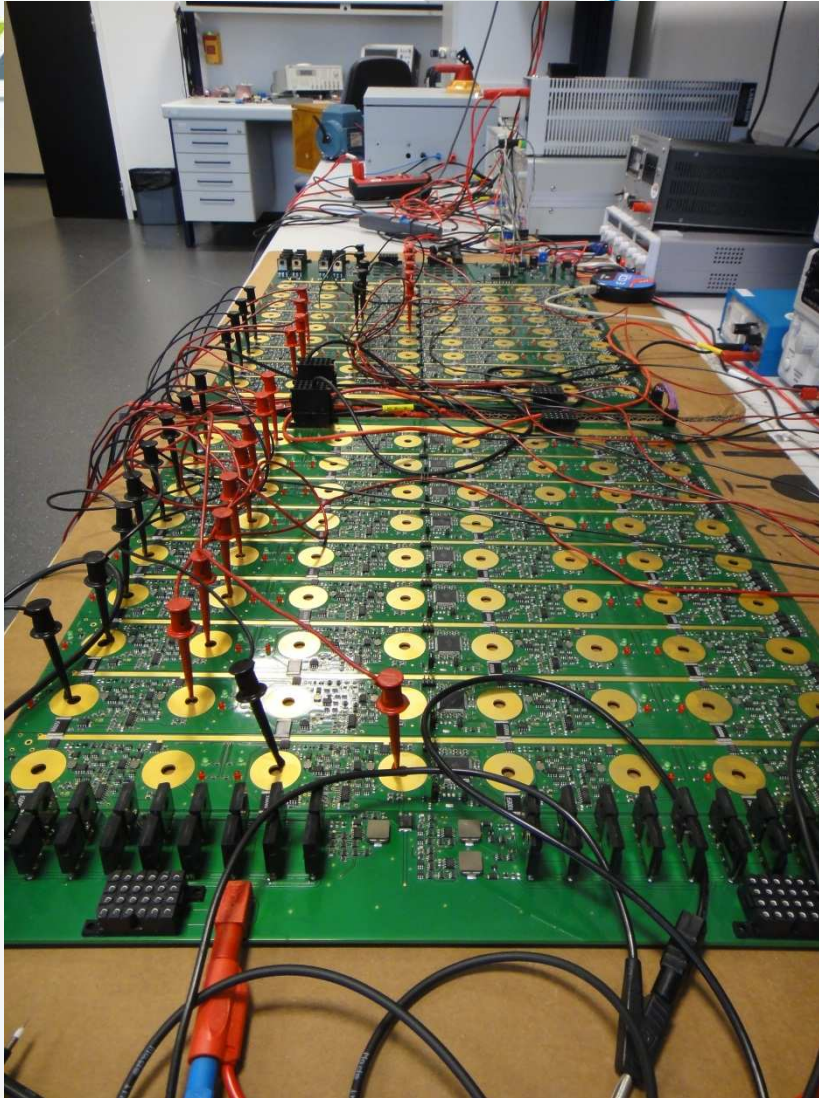
50 to 100€ of transistors cost per 10 kW to get an efficiency of 98,5%  
(catalogue price → could be significantly reduced with quantities)

## First prototype architecture

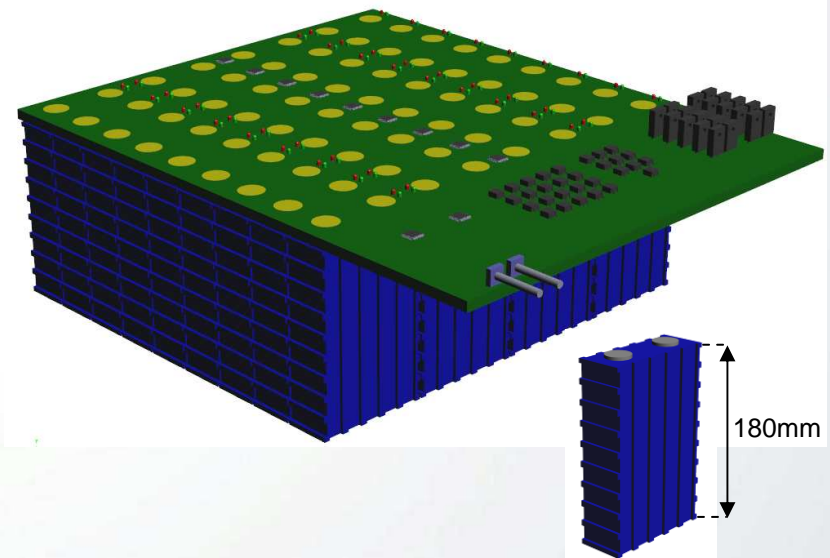




## 1st prototype fabrication

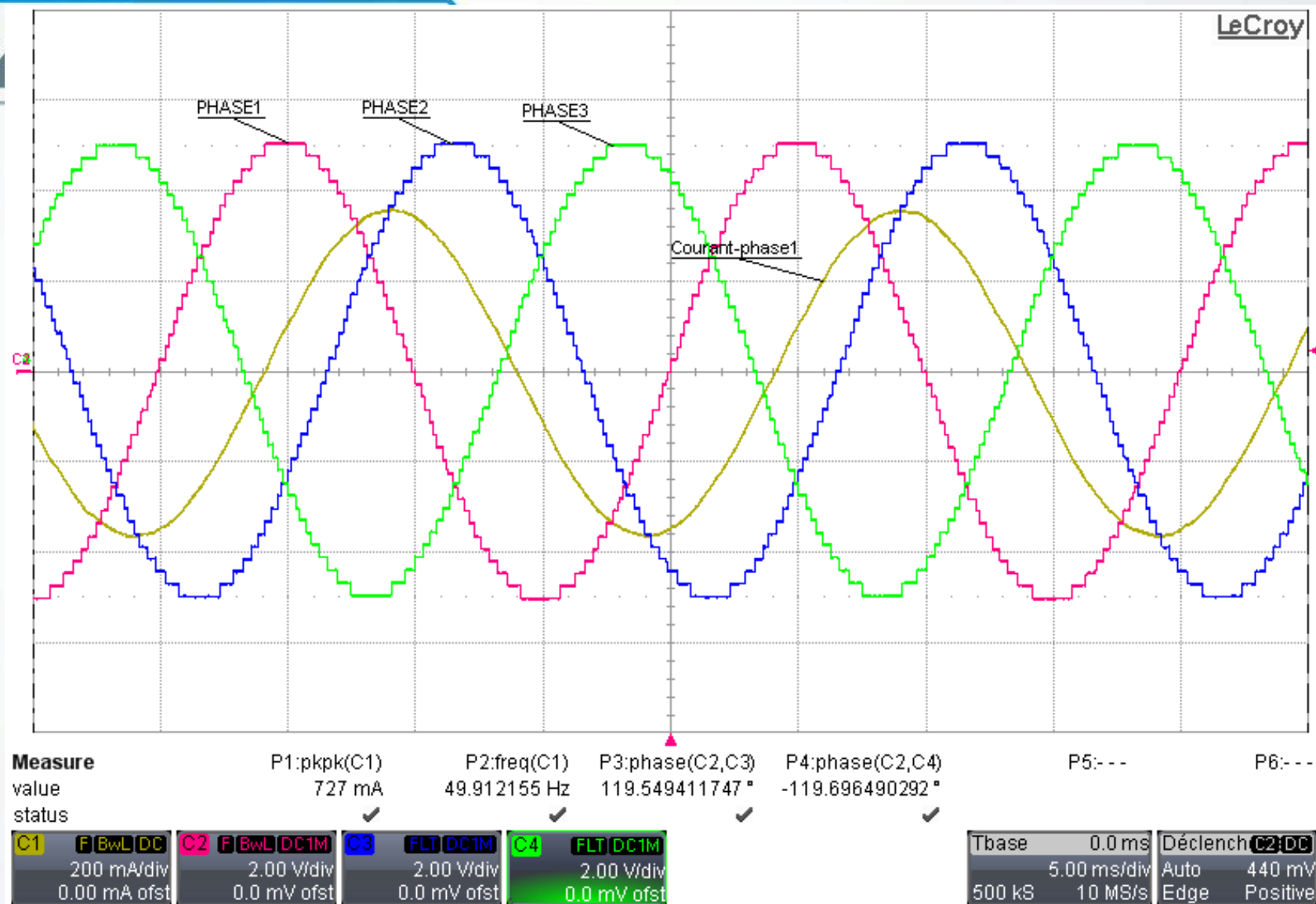


- 18 modules
- 4 cells of 40Ah per module
- Include an inverter to reverse the output voltage
- Permits to switch in serial/parallel two such systems

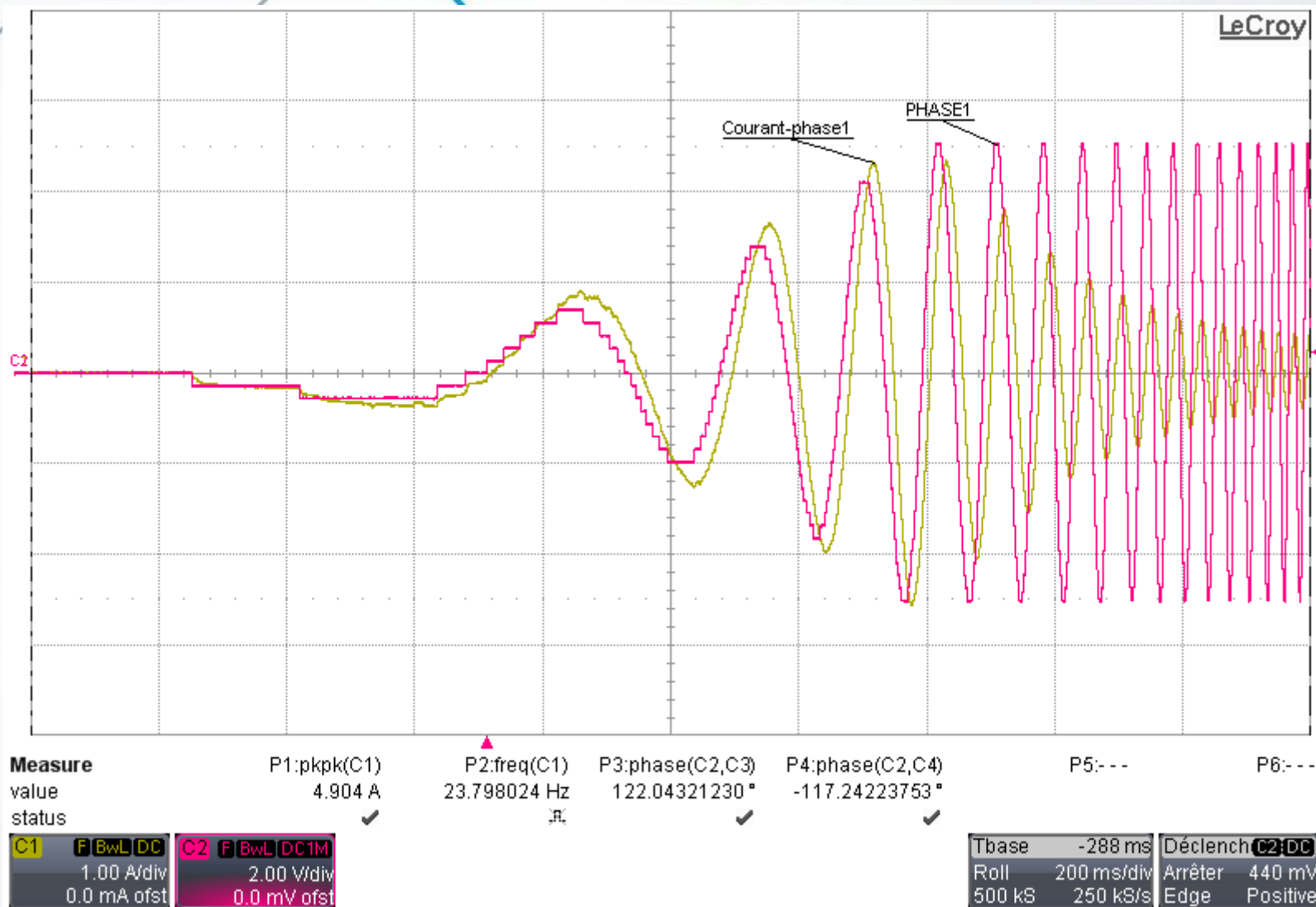




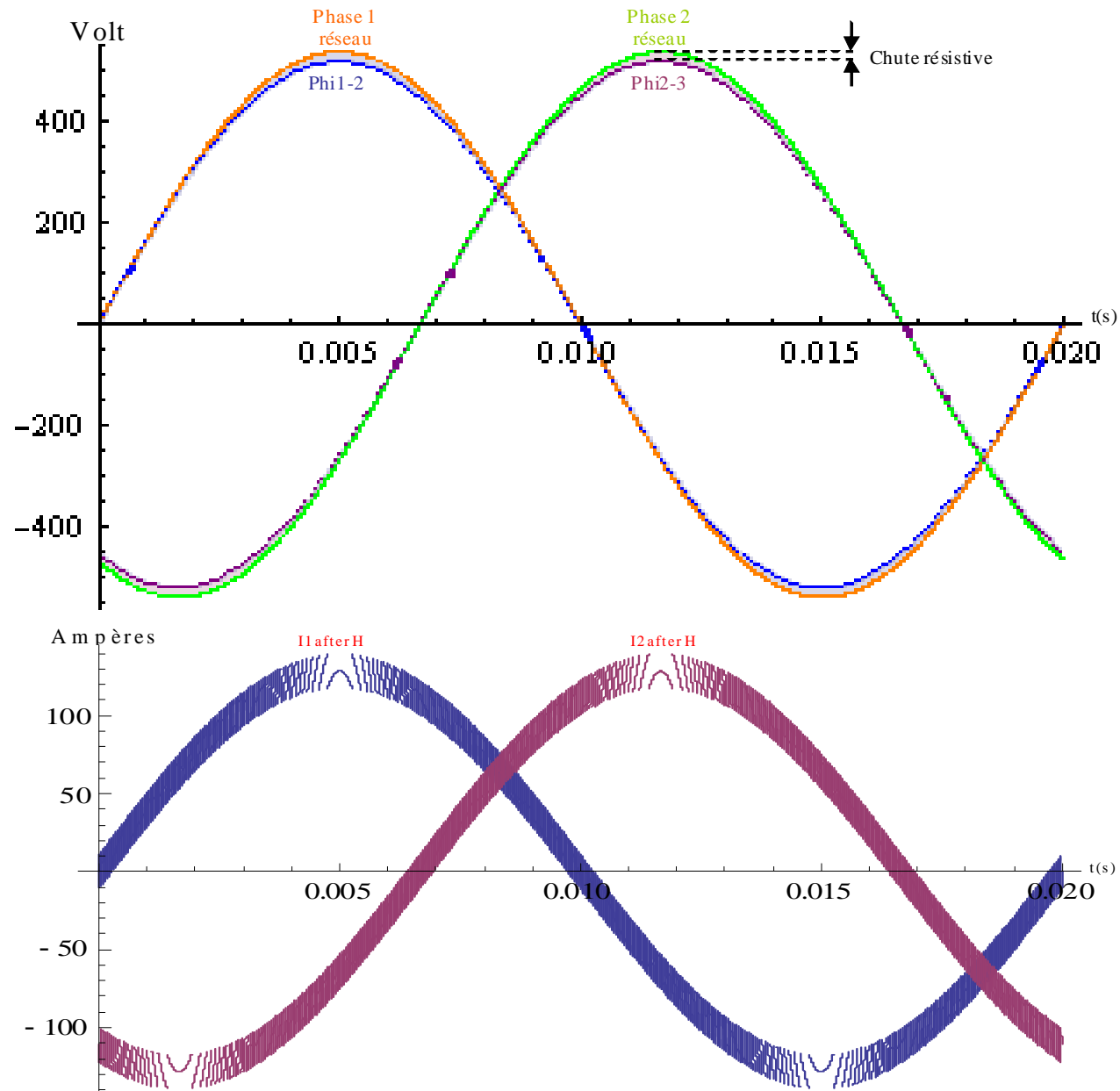
# Electrical motor driving: continuous regime (measurement)



# Electrical motor driving: transient regime (measurement)

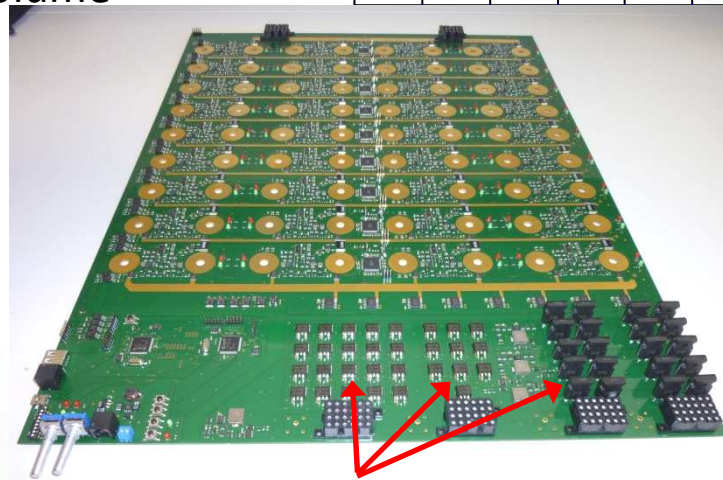


# Under 380V electrical network recharge (simulation)

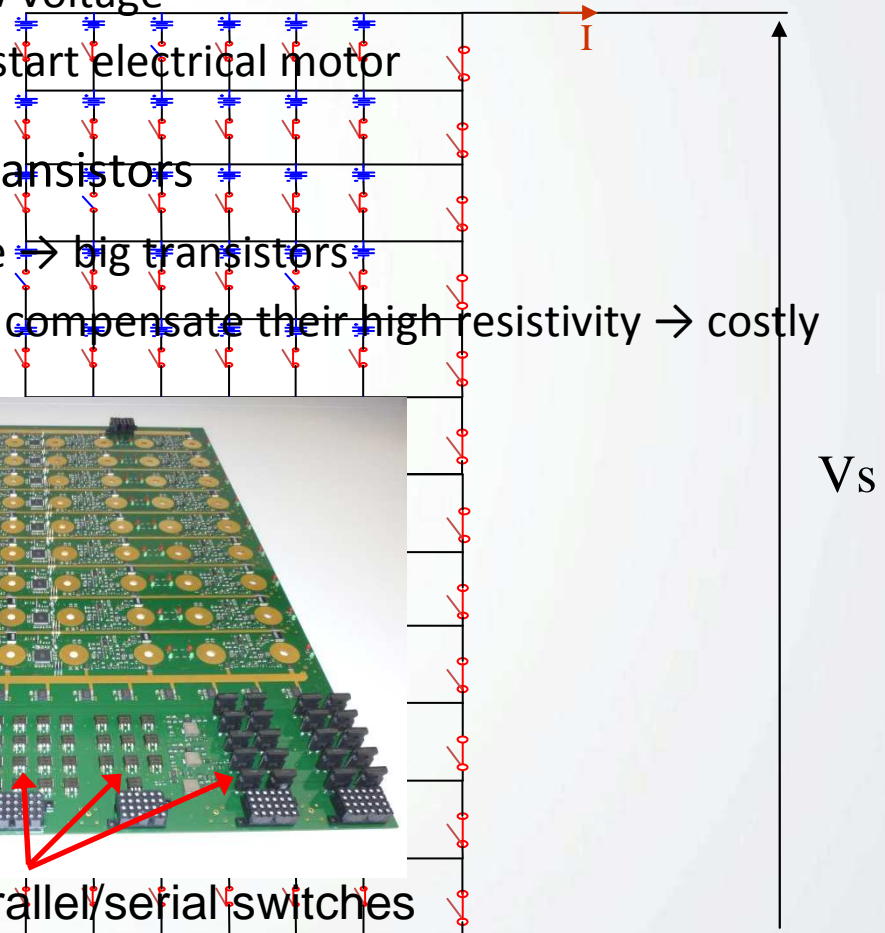


# Output current capability adjustment

- Parallel/serial switching of batteries blocks
  - Lower resistive losses at low voltage
  - Higher available current to start electrical motor
- Inverter and serial/parallel transistors
  - Have to sustain high voltage → big transistors
  - Many parallel transistors to compensate their high resistivity → costly and high volume

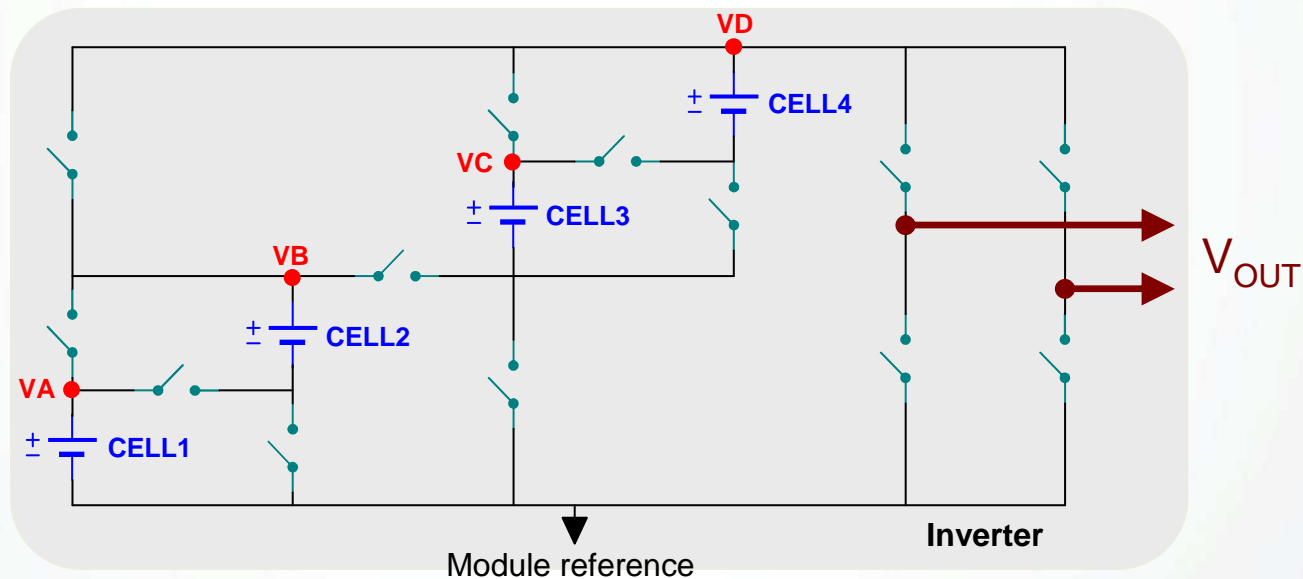


Inverter and parallel/serial switches



## 2d prototype: local switching design

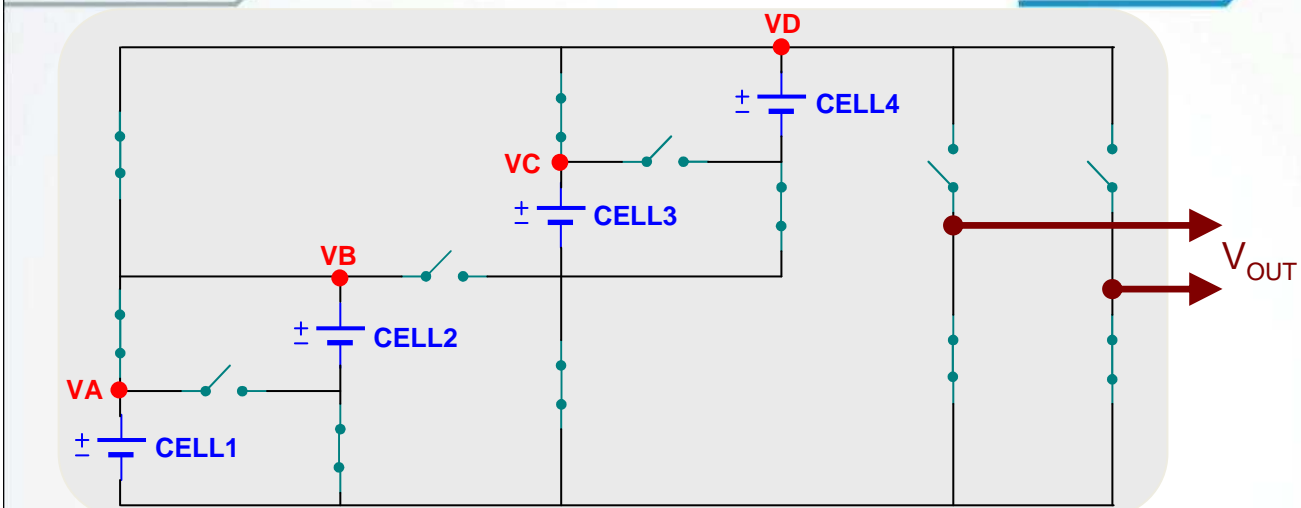
- Local inversion and serial/parallel switching
  - Under lower voltage → Smaller transistors
  - Easier to drive in synchronize the inverter



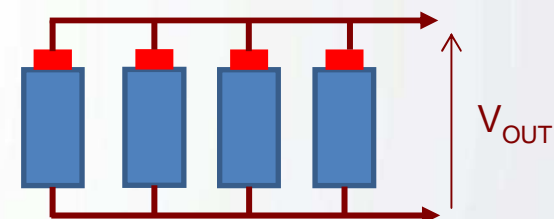
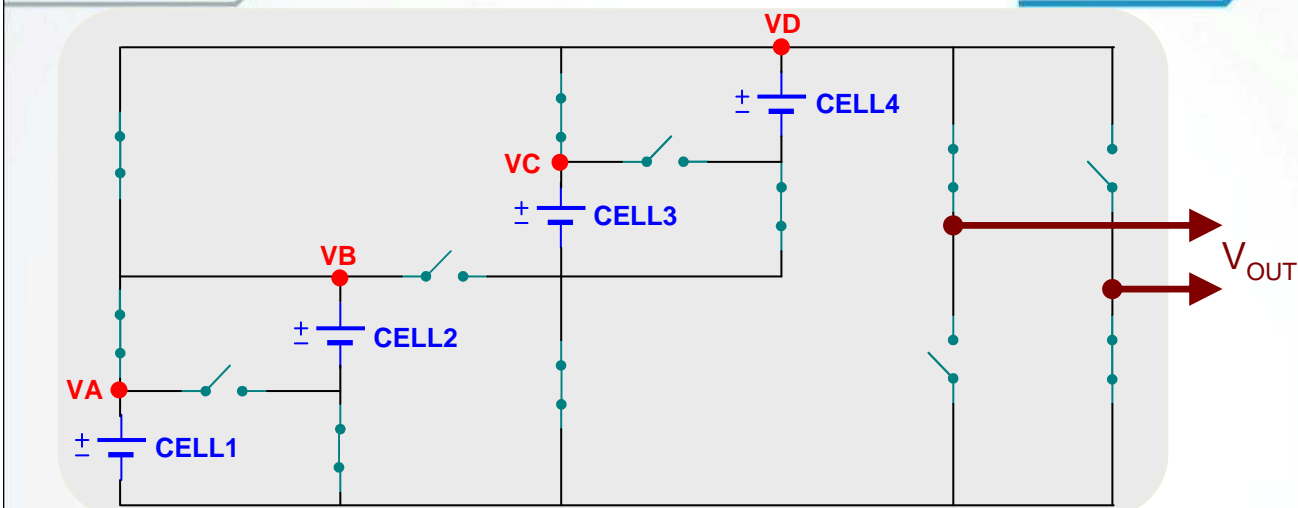
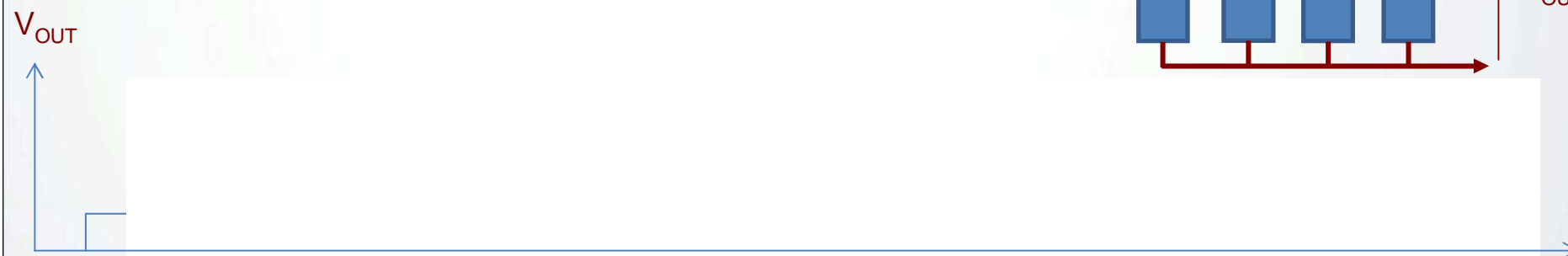
- Higher efficiency in low voltage: up to 4 cells in parallel



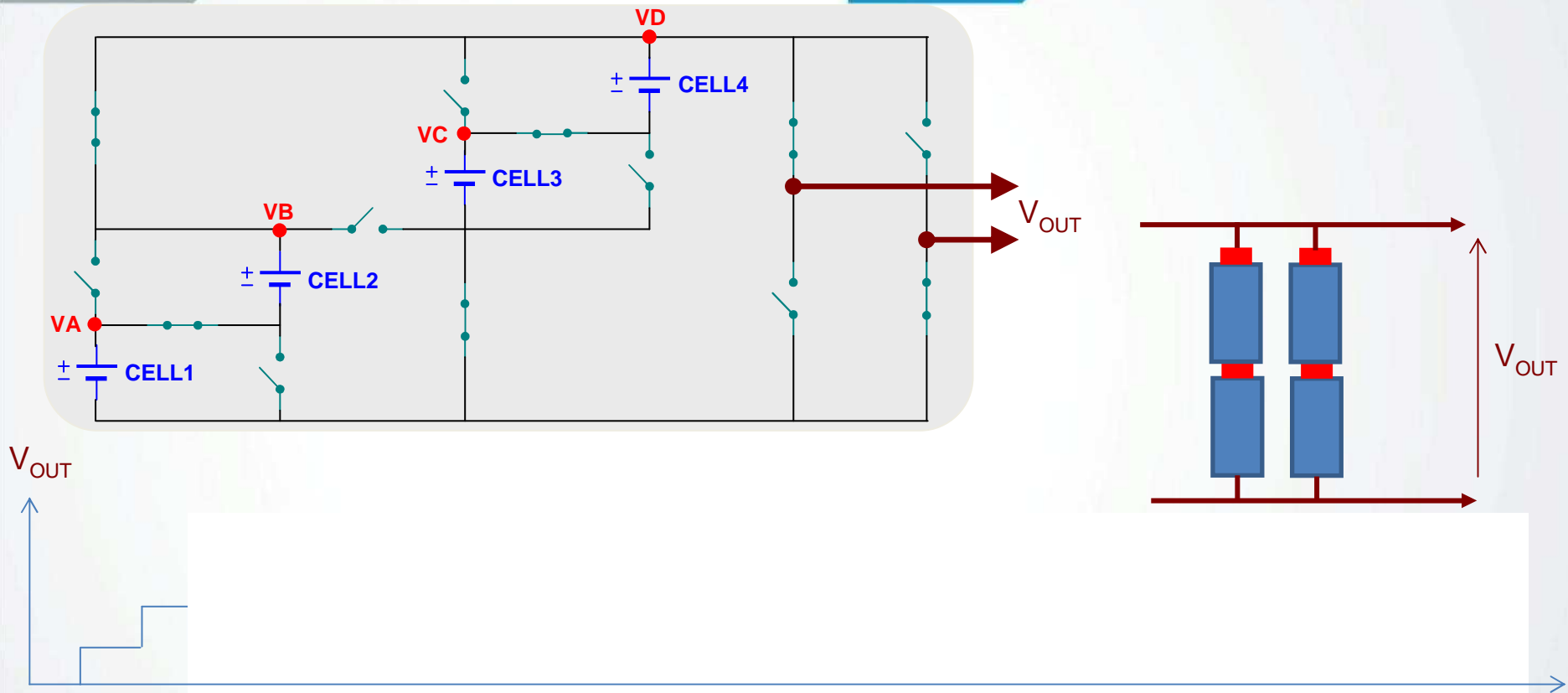
# Le BMS commuté : l'architecture générique

 $V_{OUT}$ 

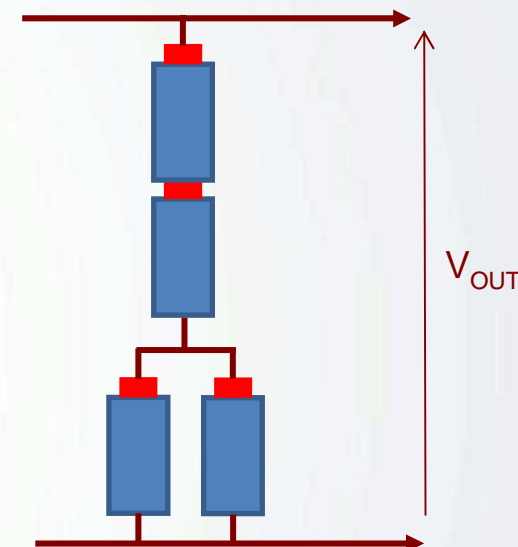
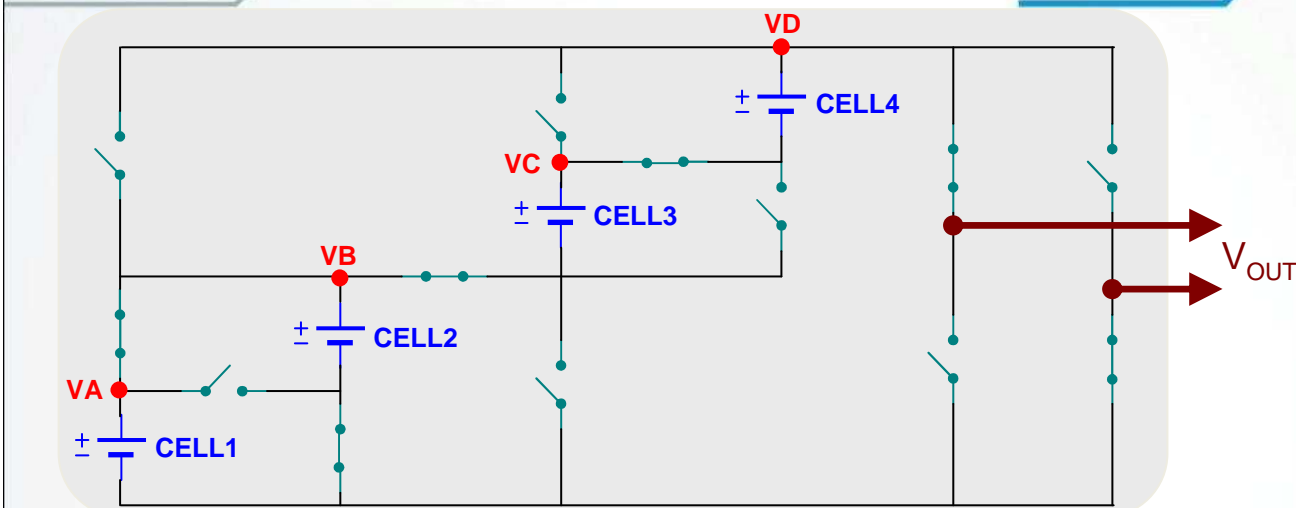
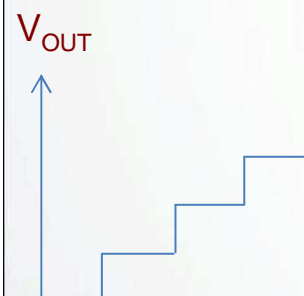
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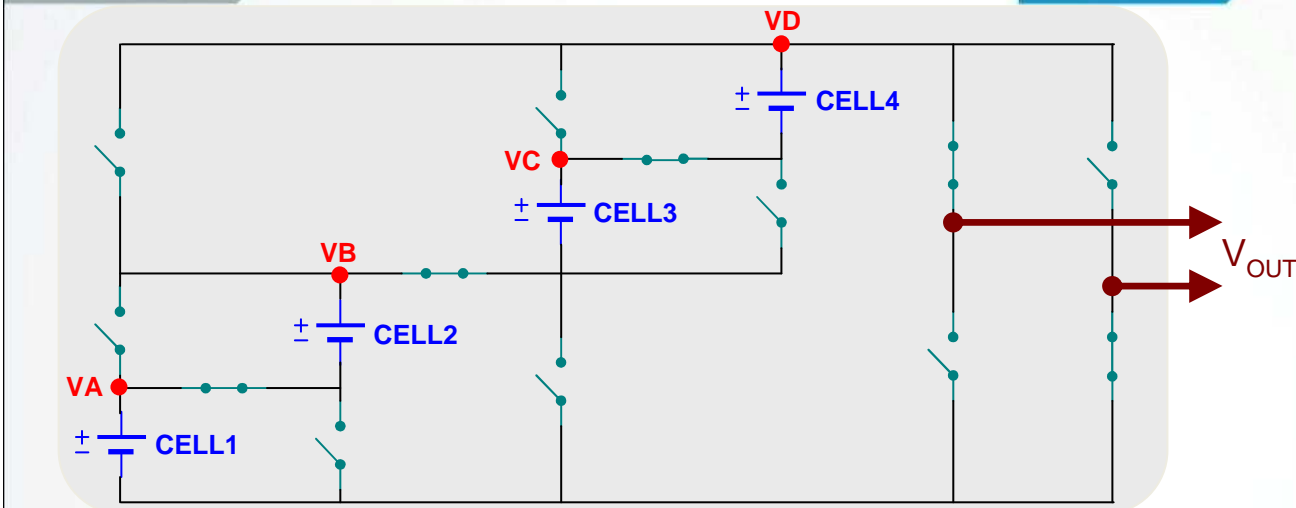
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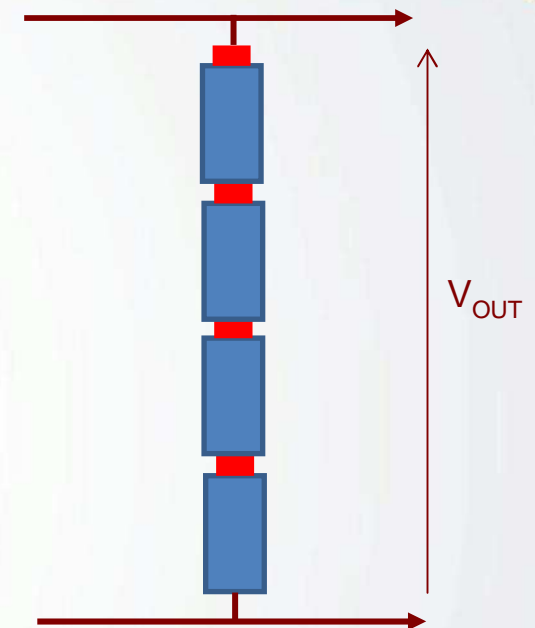
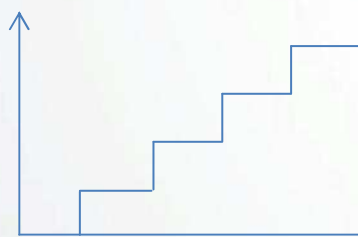
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 $V_{OUT}$ 

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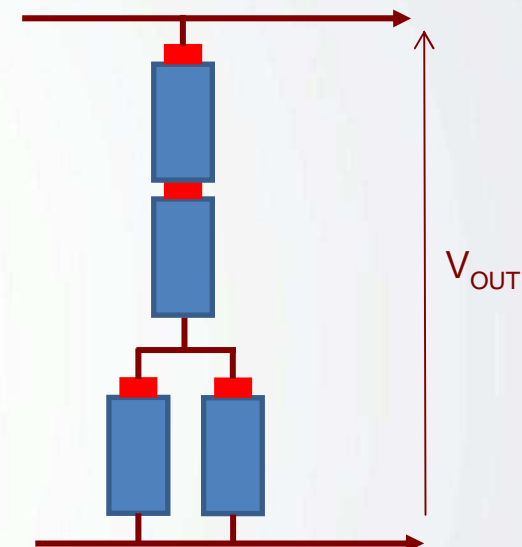
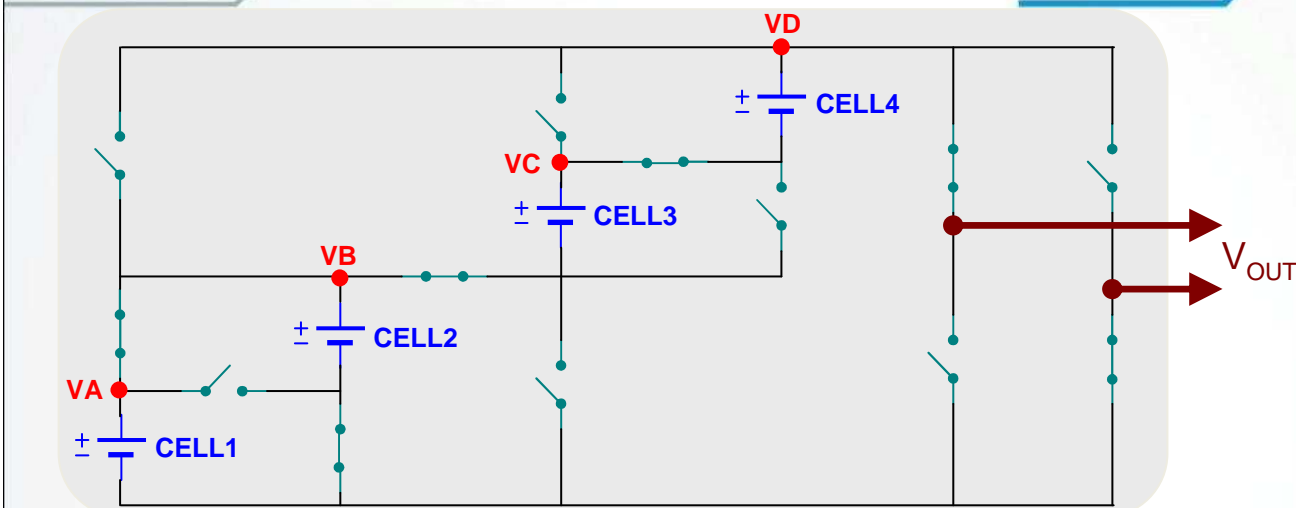
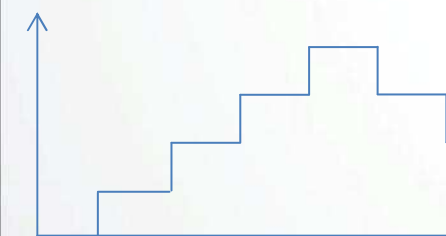


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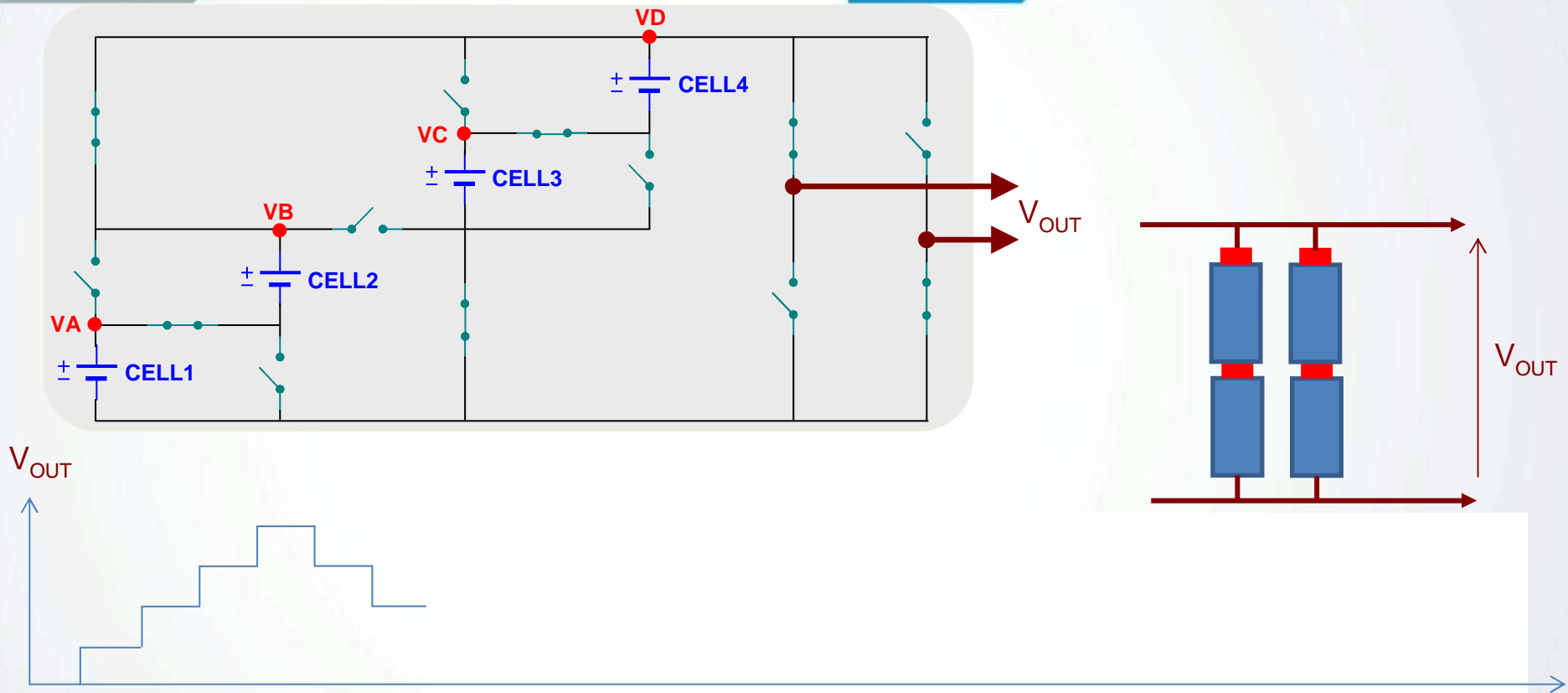




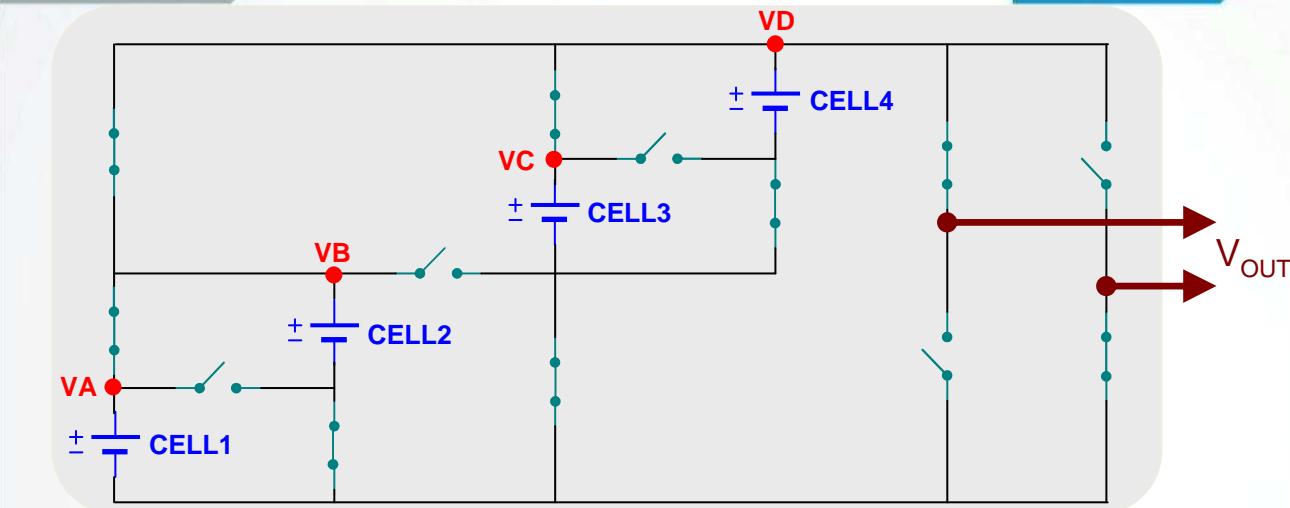
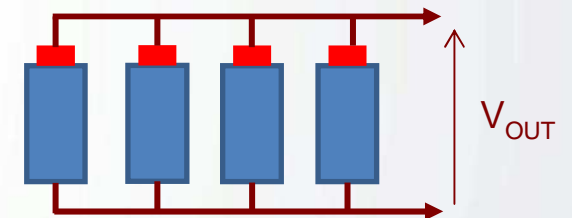
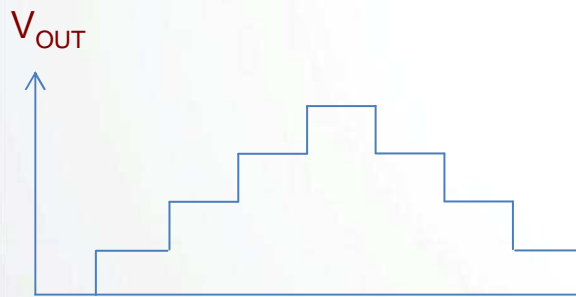
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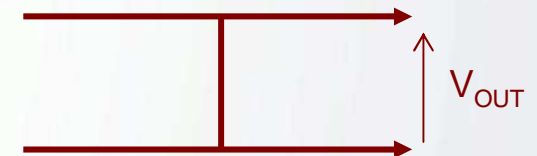
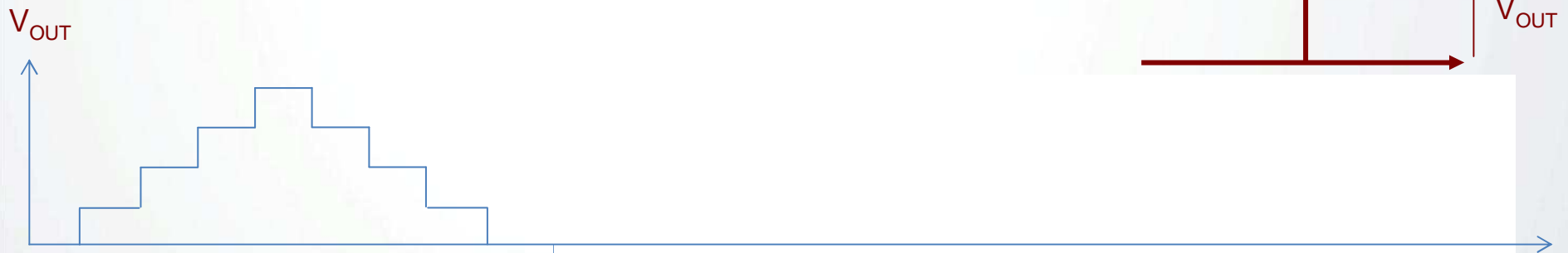
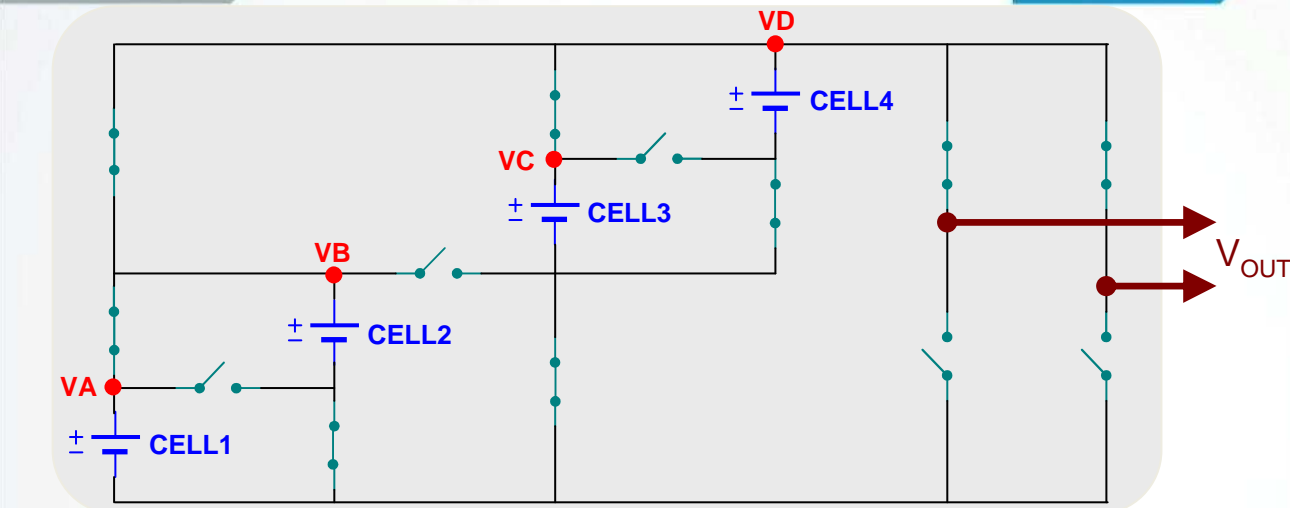
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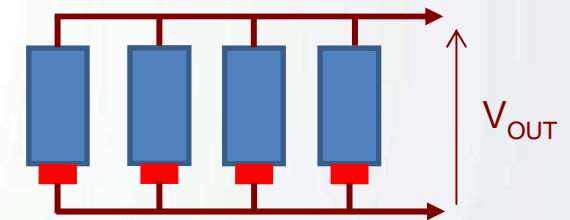
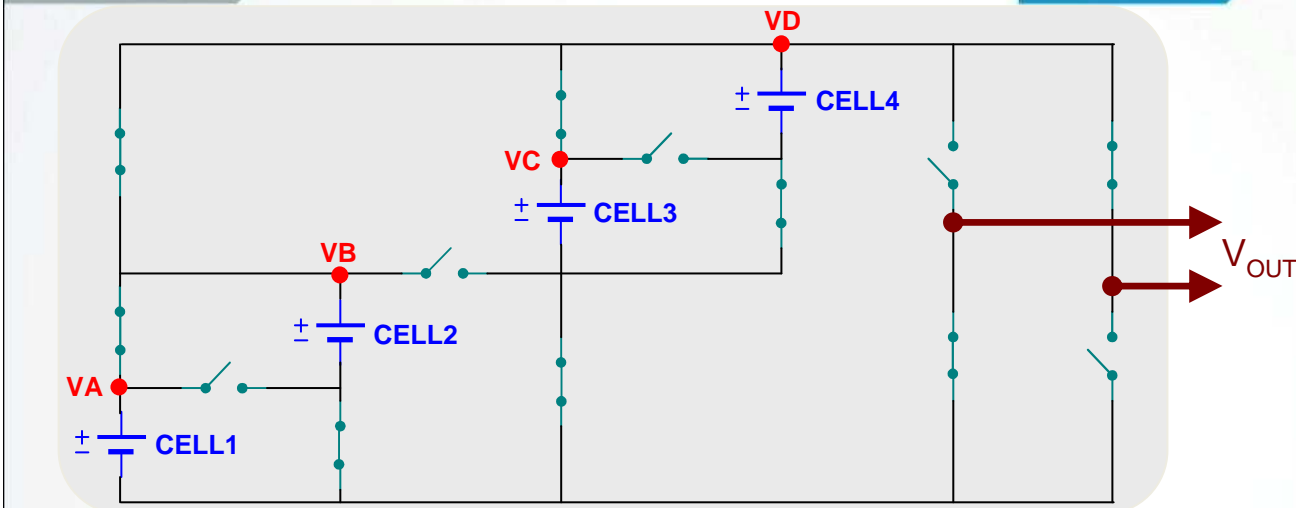
# Le BMS commuté : l'architecture générique

 $V_{OUT}$  $V_{OUT}$ 

# Le BMS commuté : l'architecture générique

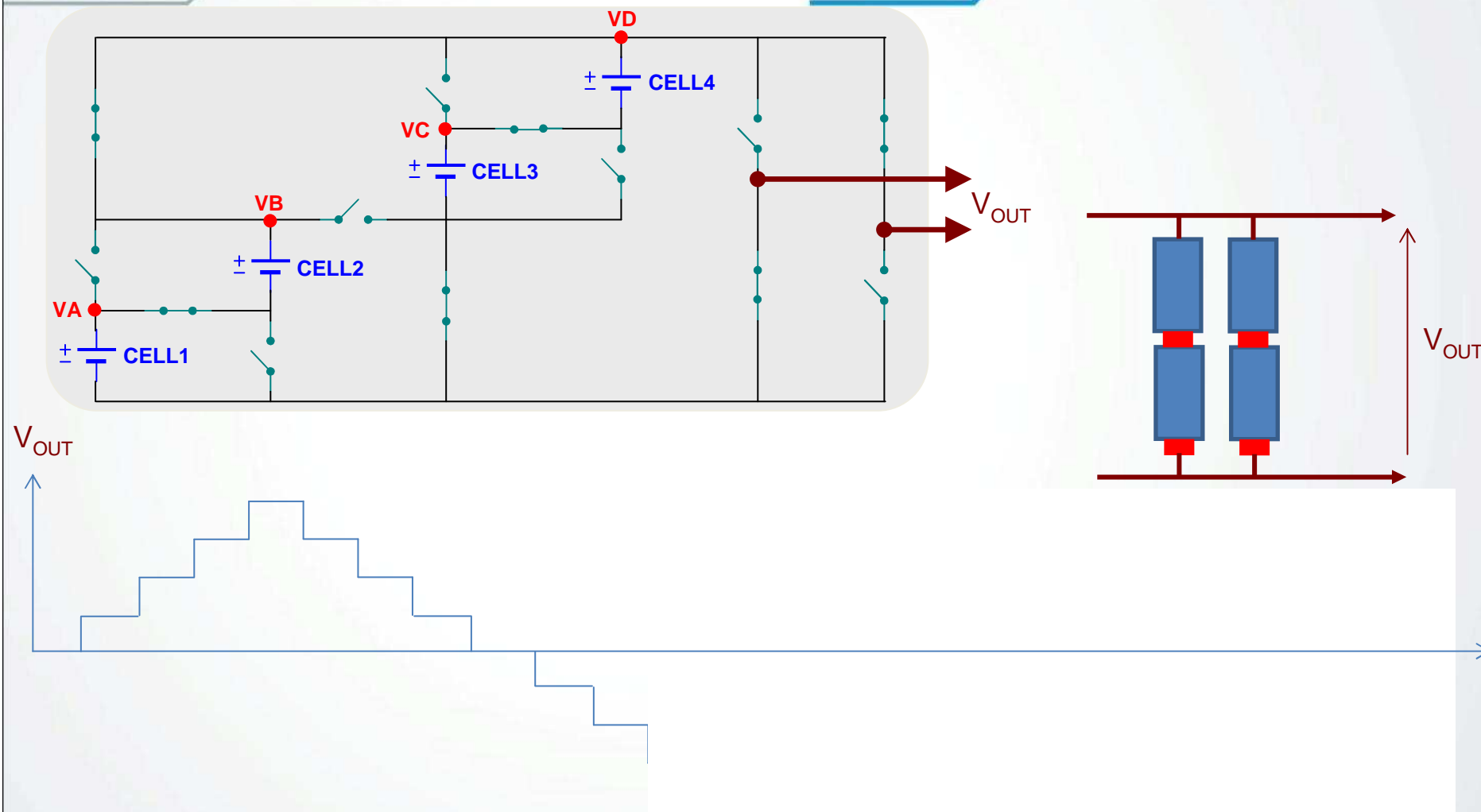


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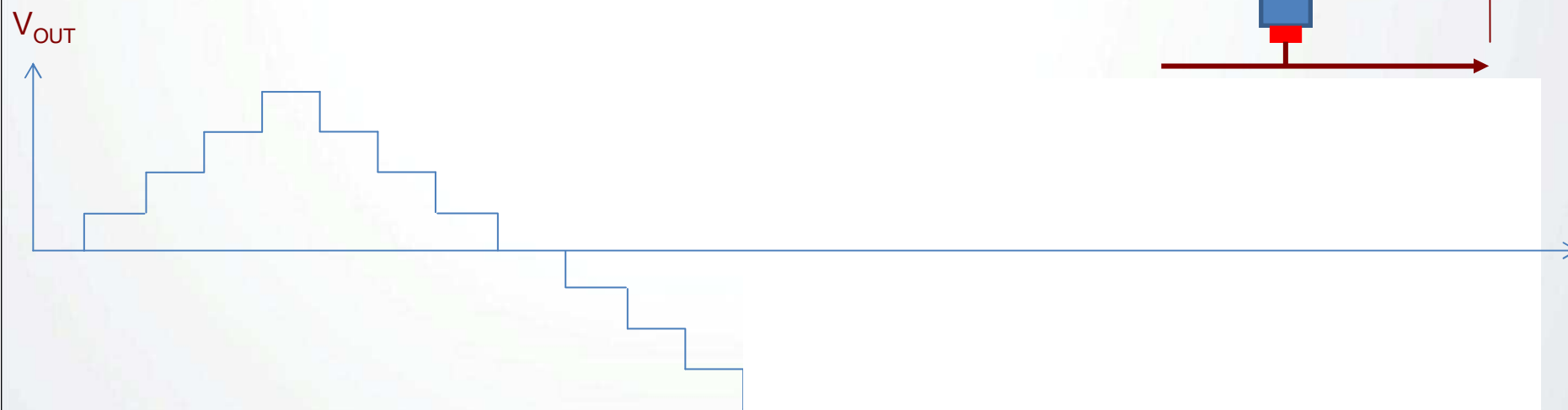
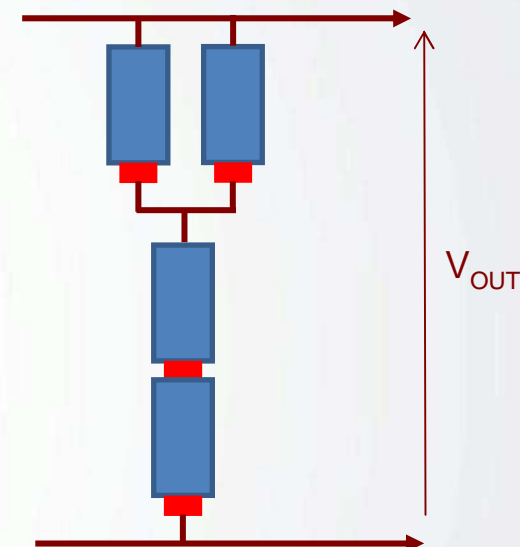
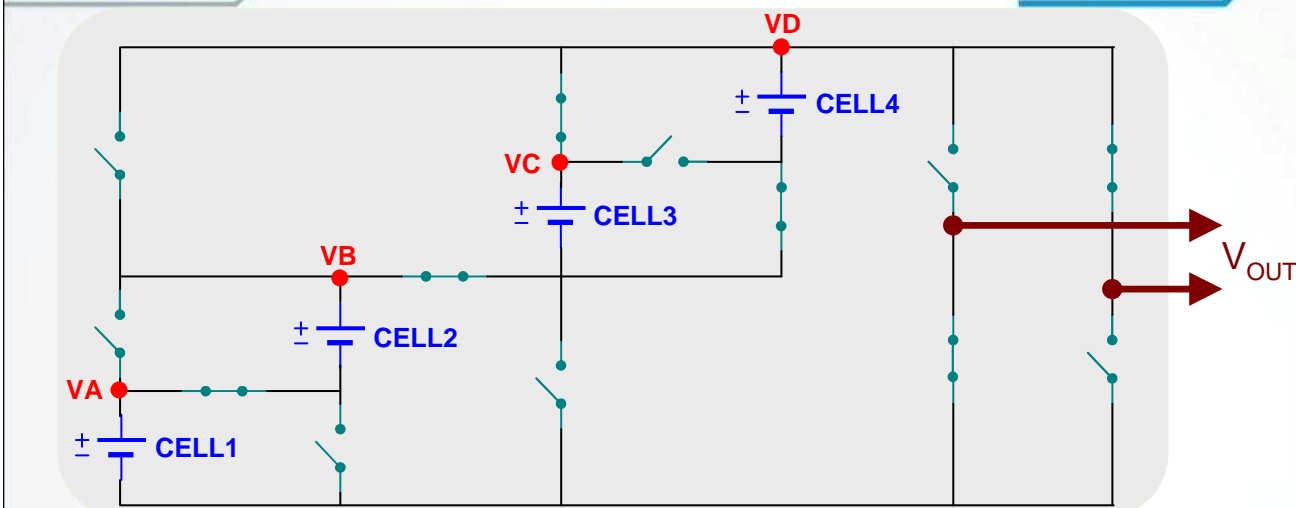




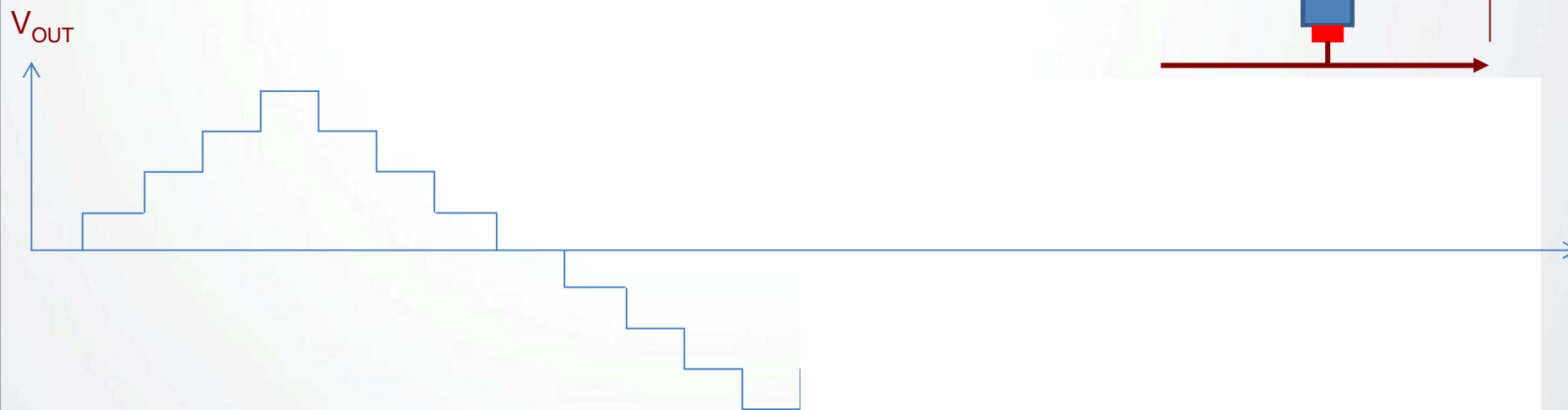
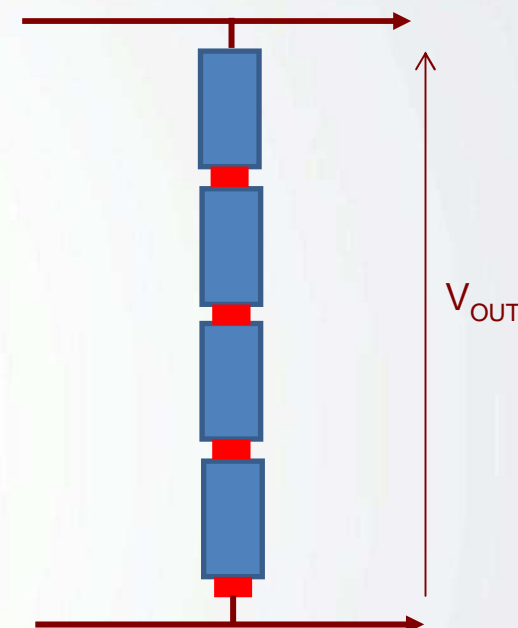
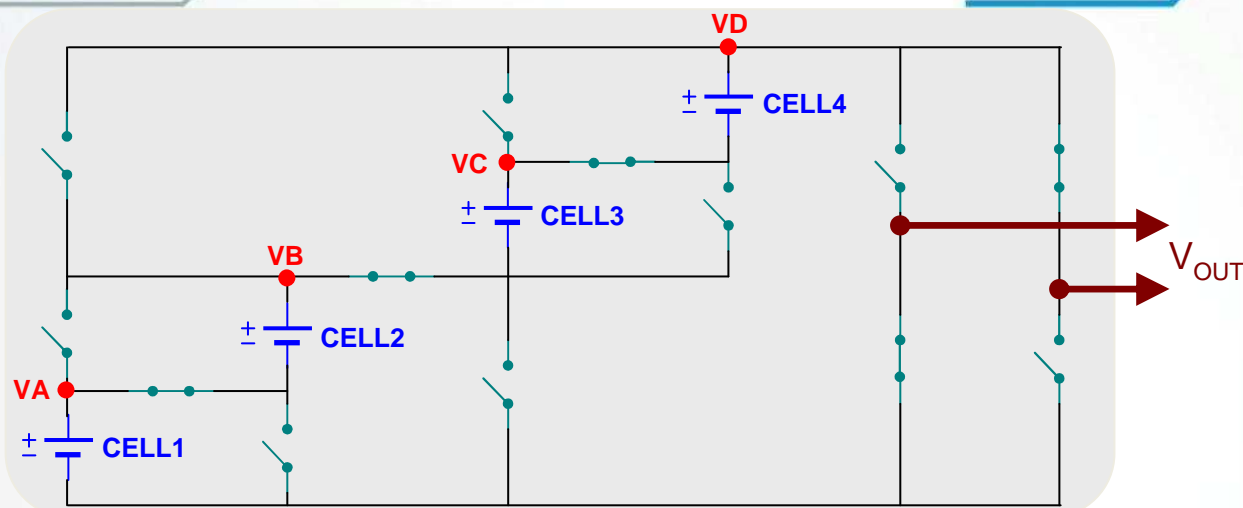
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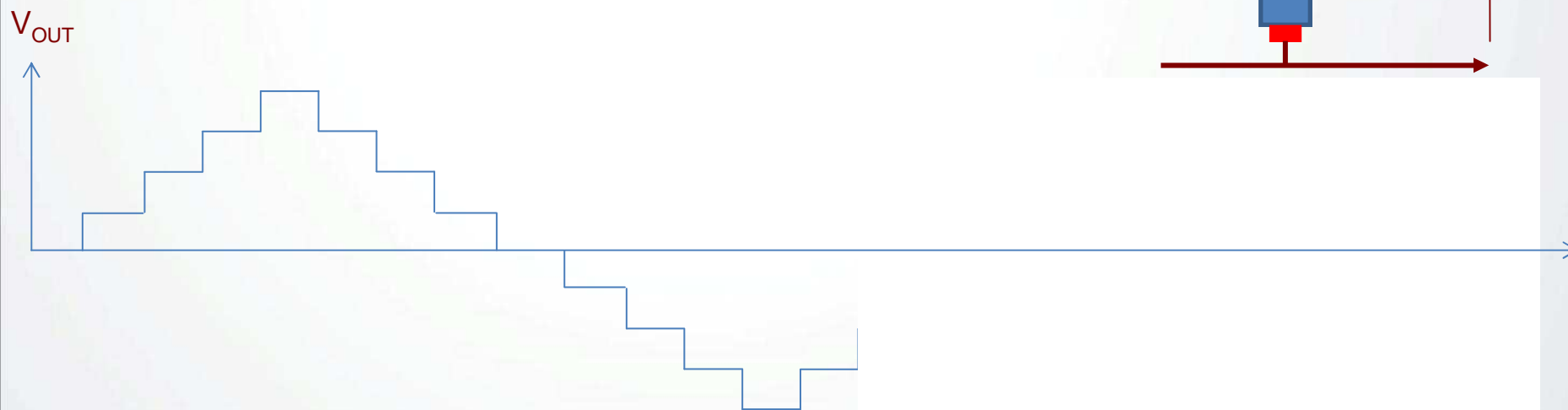
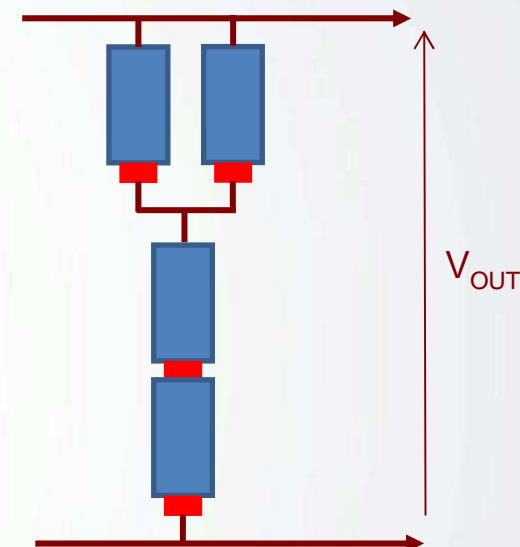
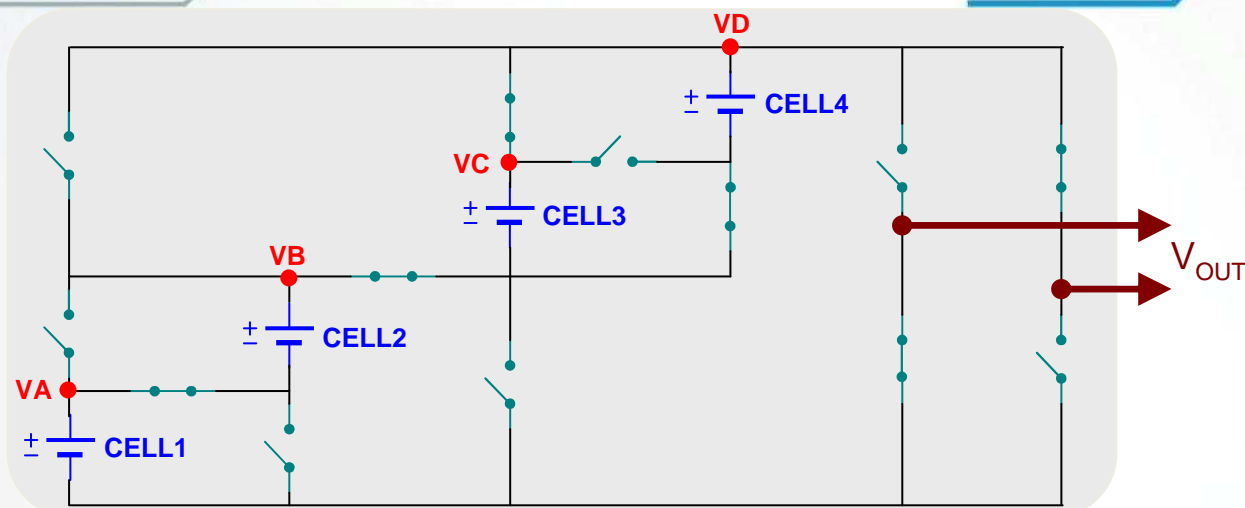
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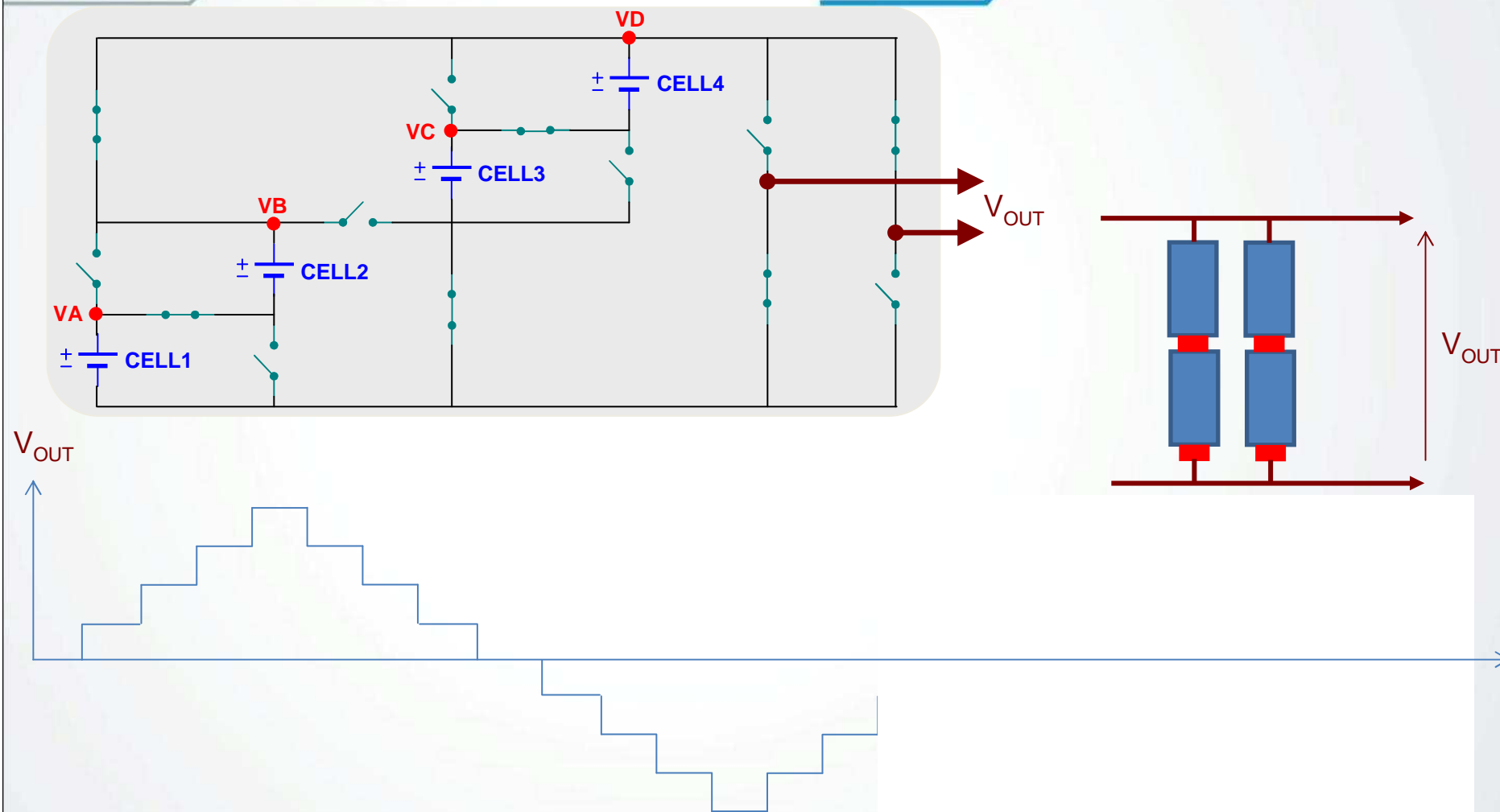
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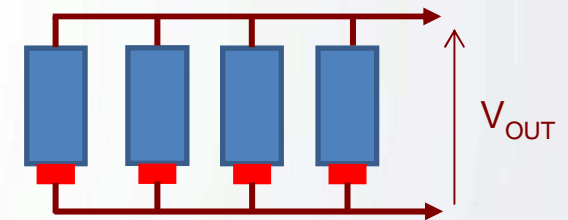
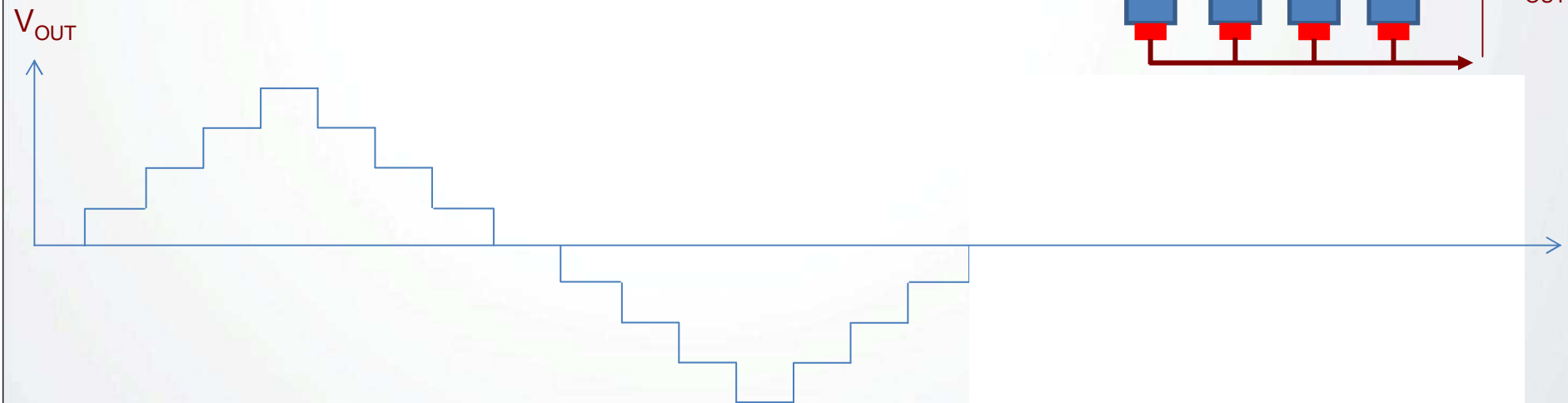
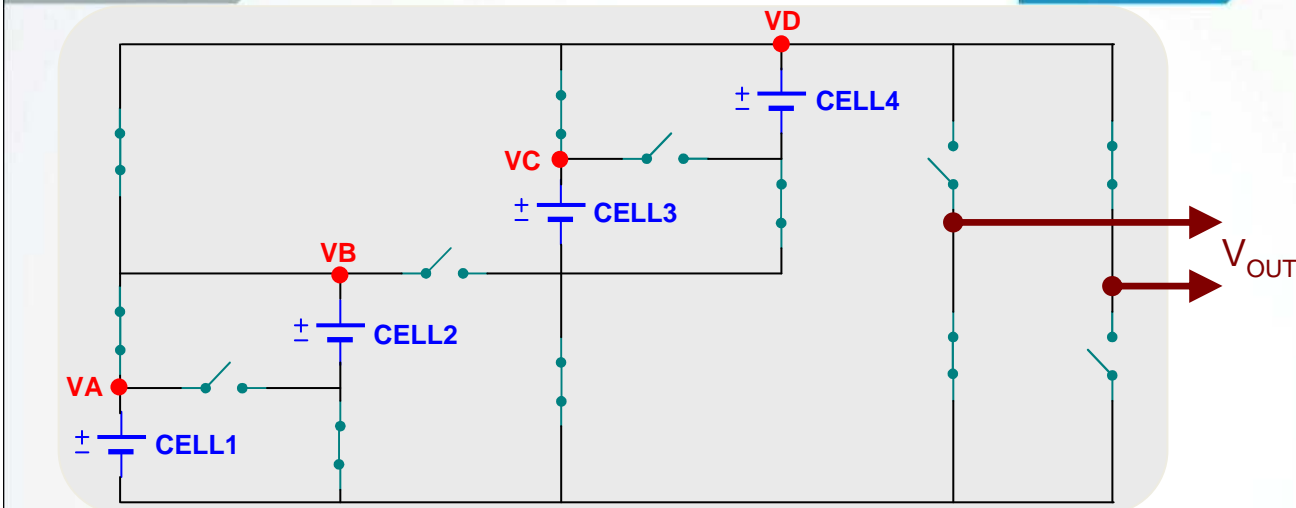
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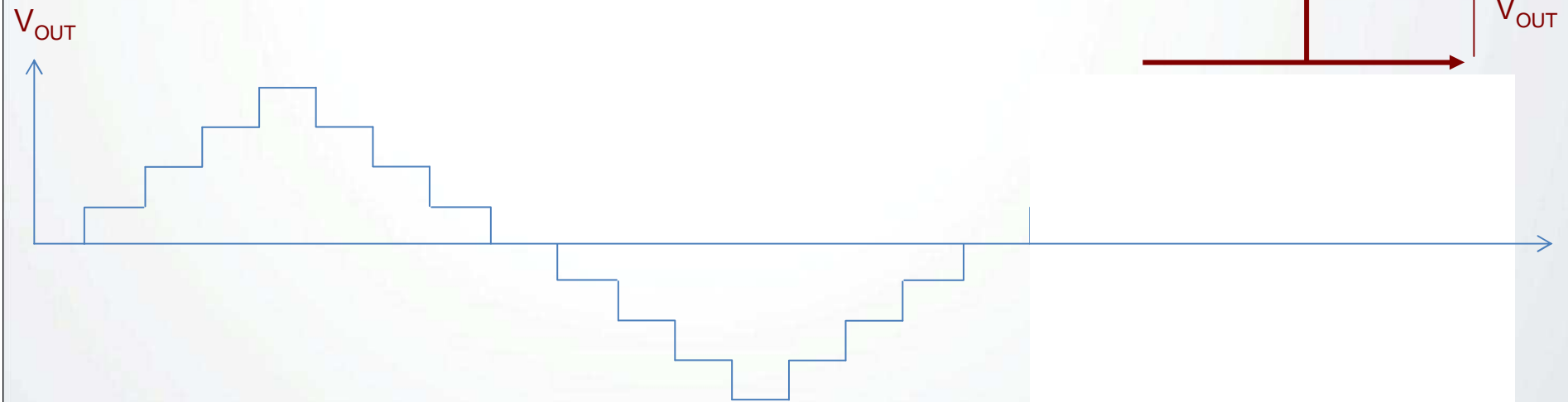
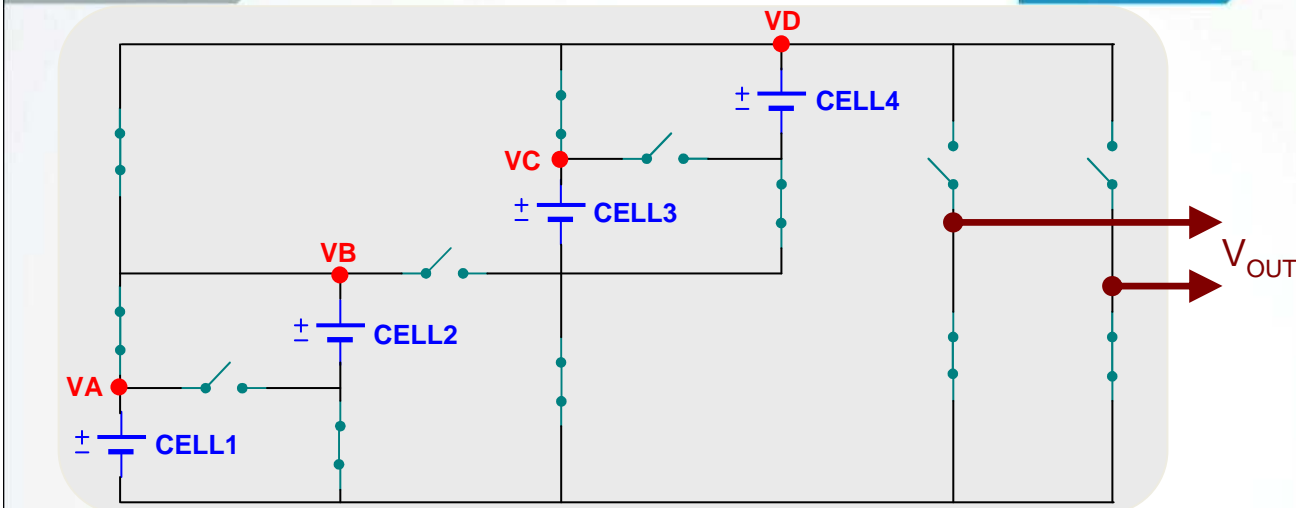
 $V_{OUT}$  $V_{OUT}$  $V_{OUT}$

# Le BMS commuté : l'architecture générique

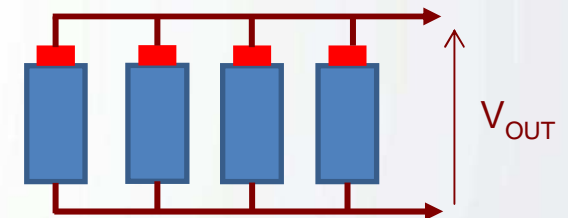
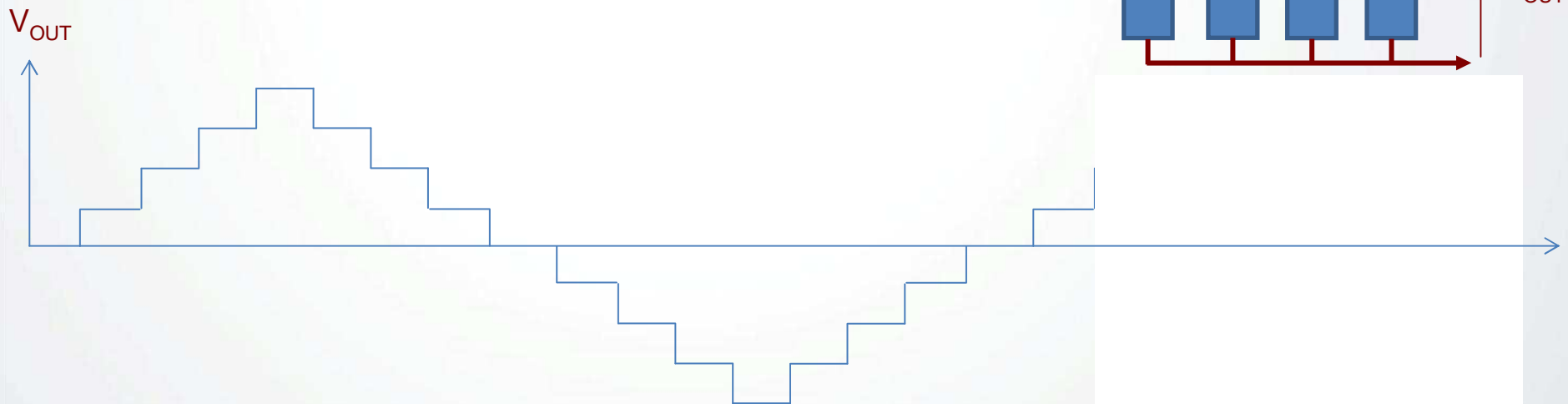
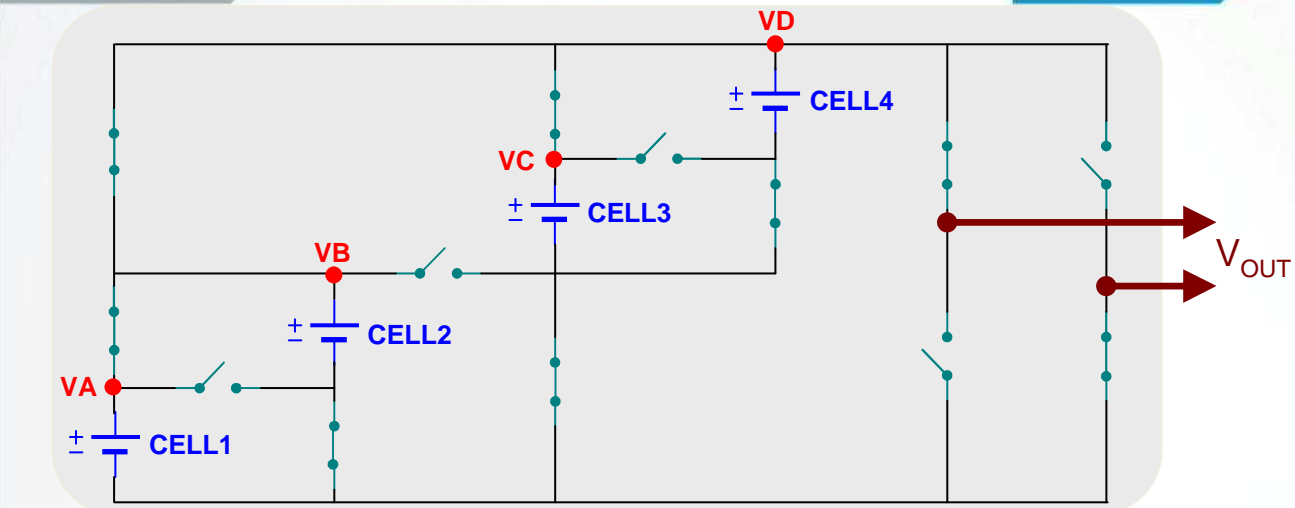




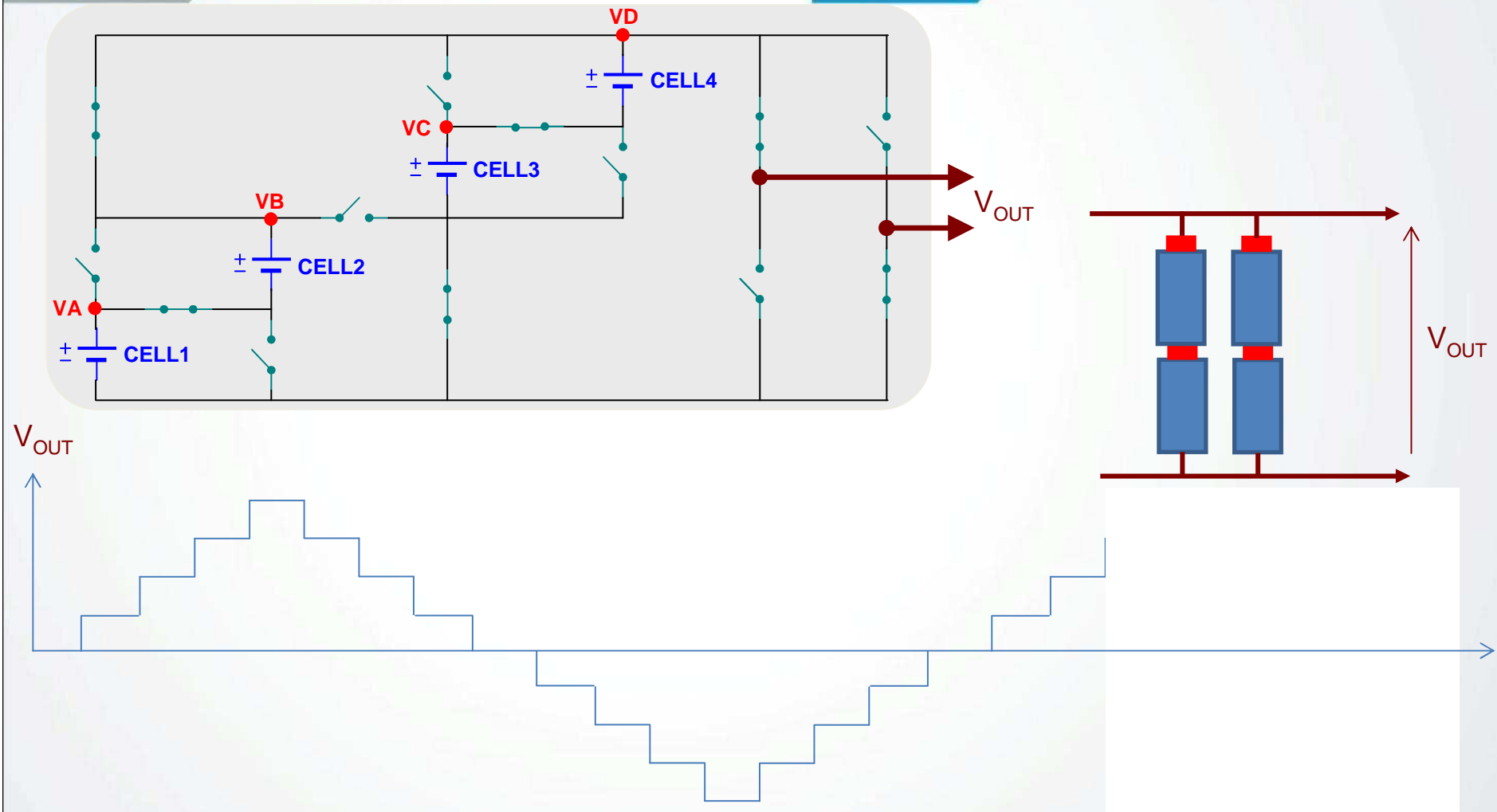
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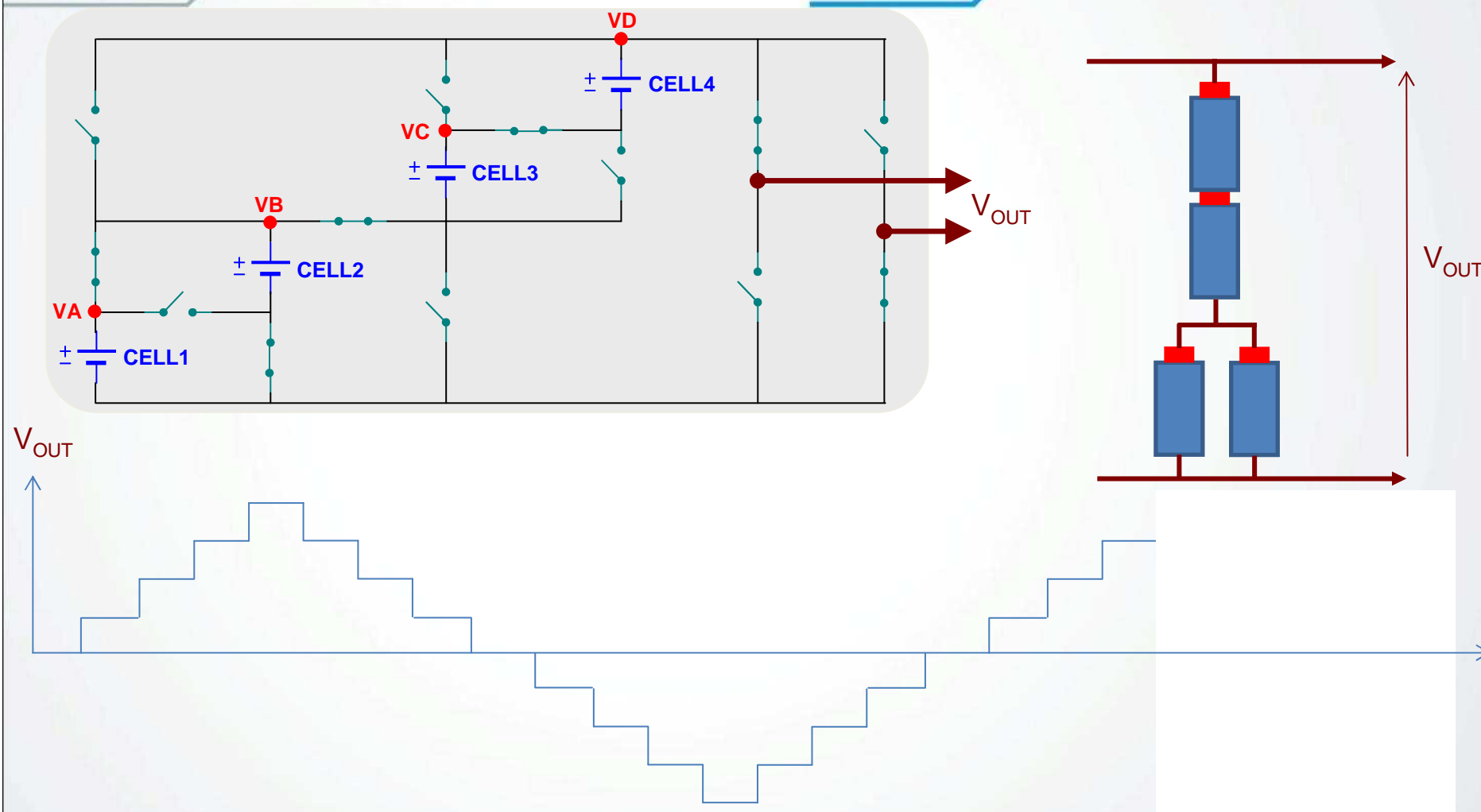
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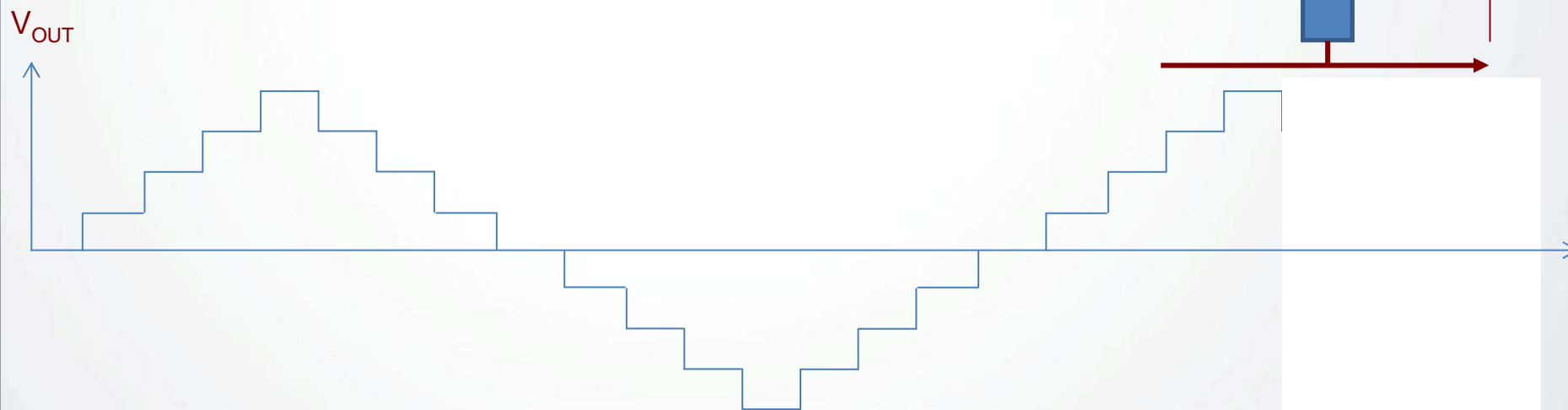
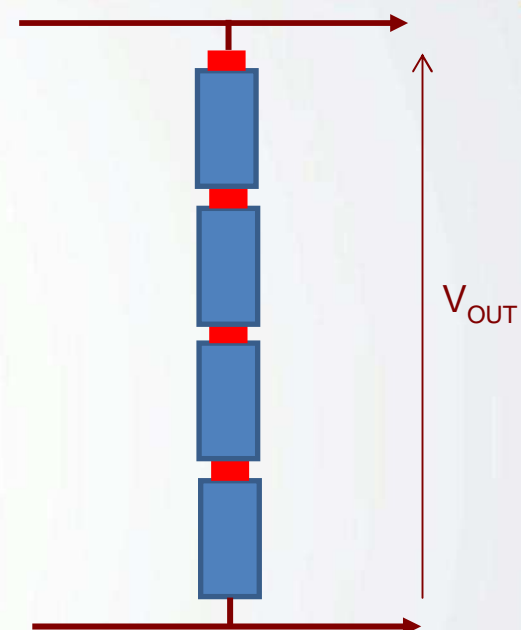
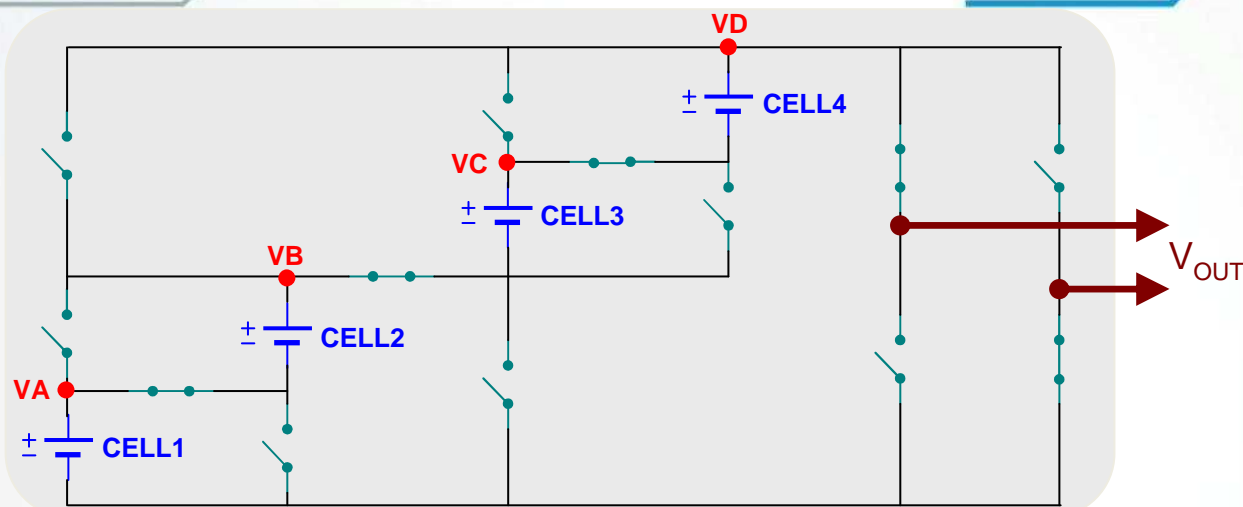
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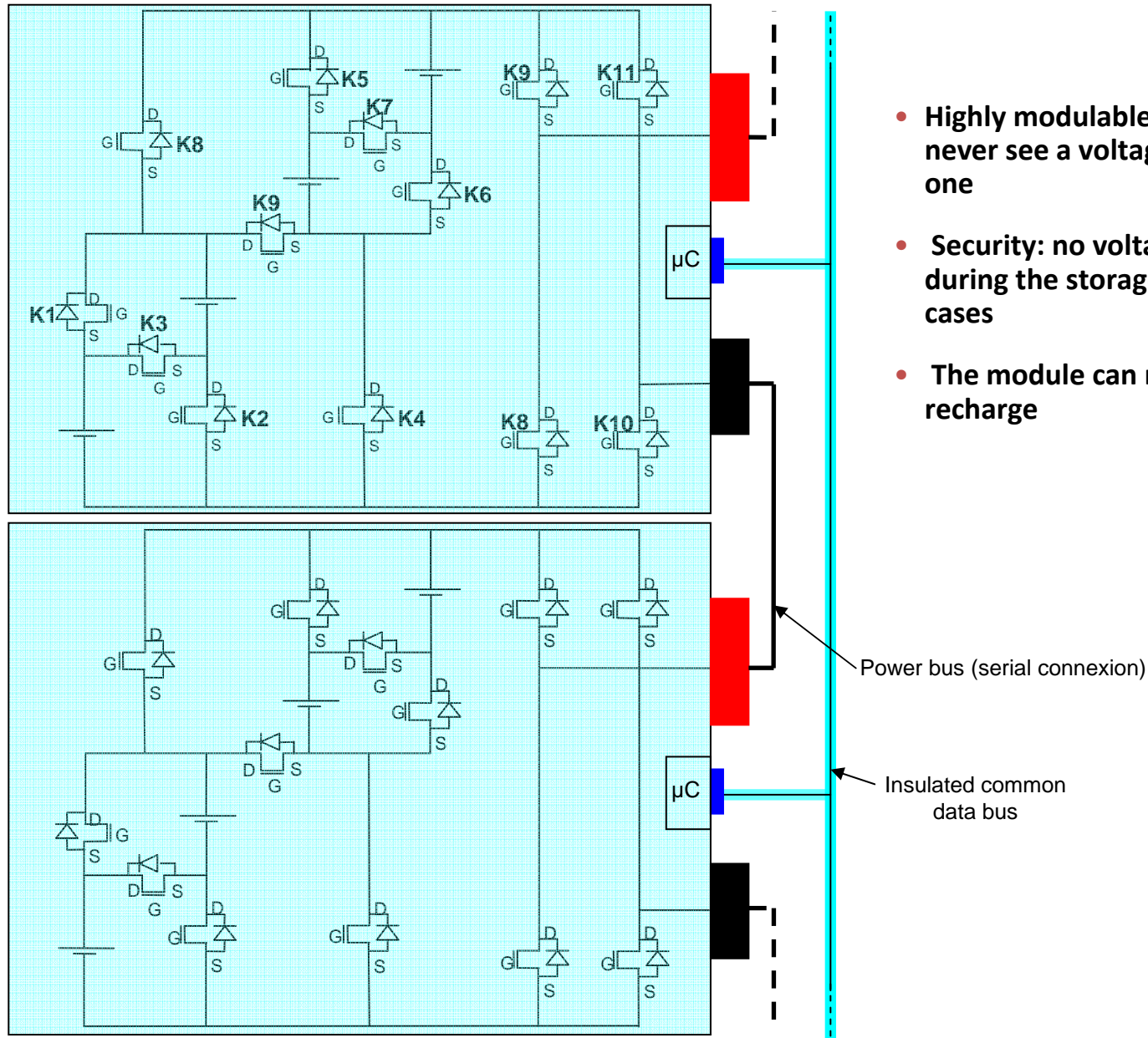
# Le BMS commuté : l'architecture générique



# Le BMS commuté : l'architecture générique



# Le BMS commuté : l'architecture



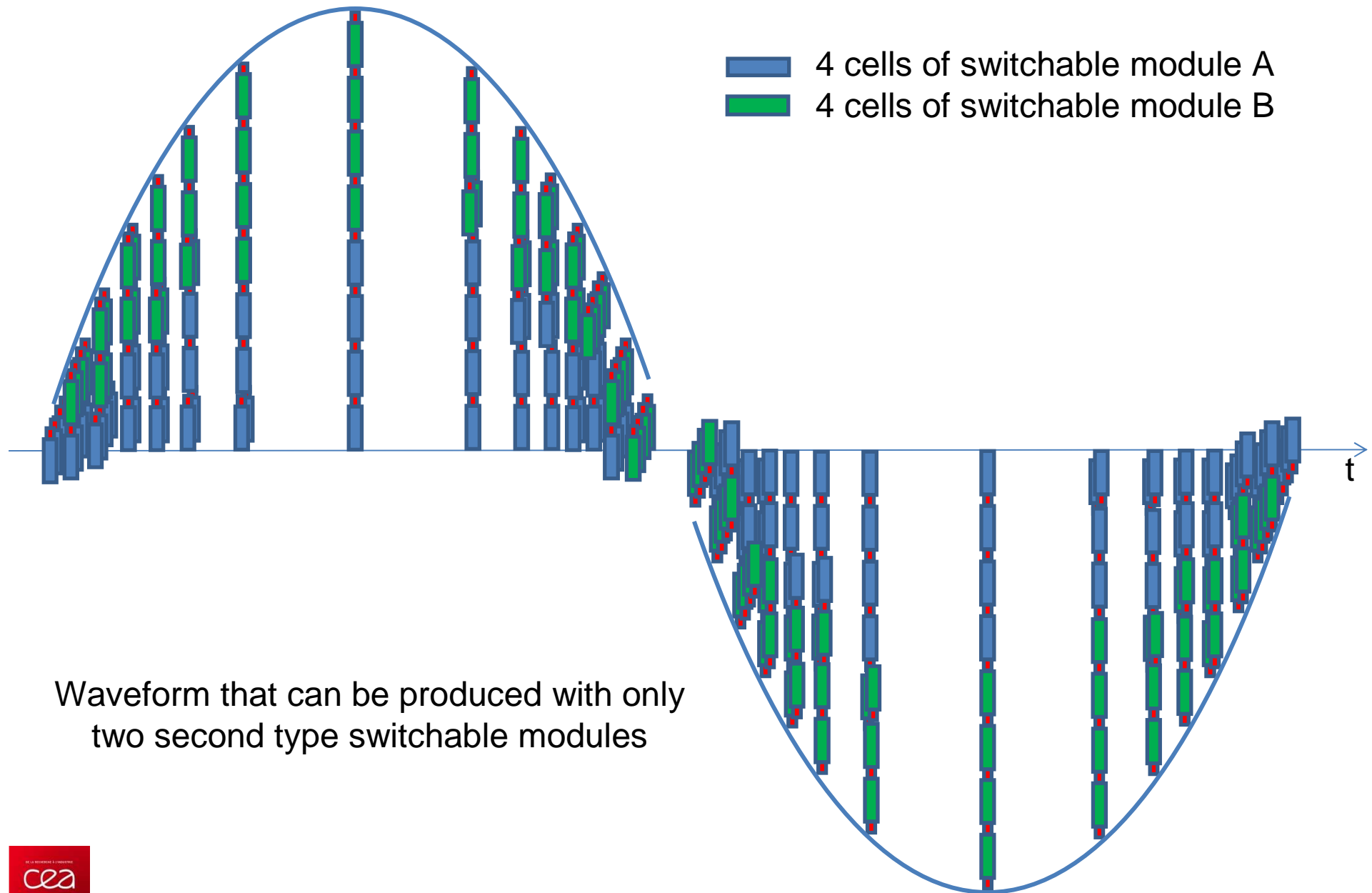
- **Highly modulable:** each module never see a voltage higher than its one
- **Security:** no voltage on the module during the storage or in abnormal cases
- **The module can manage its own recharge**

Power bus (serial connexion)

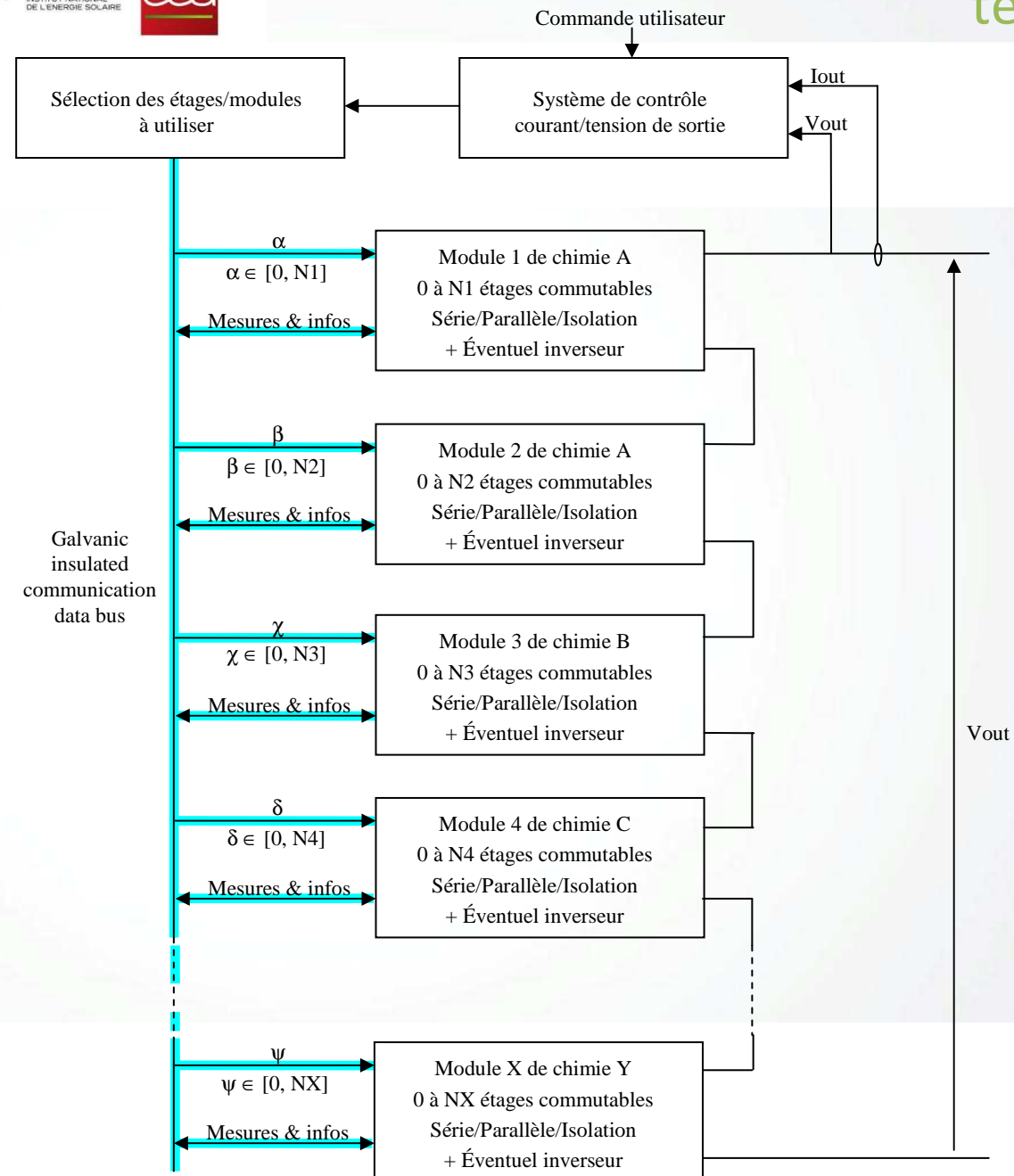
Insulated common data bus



## 2d prototype: principle

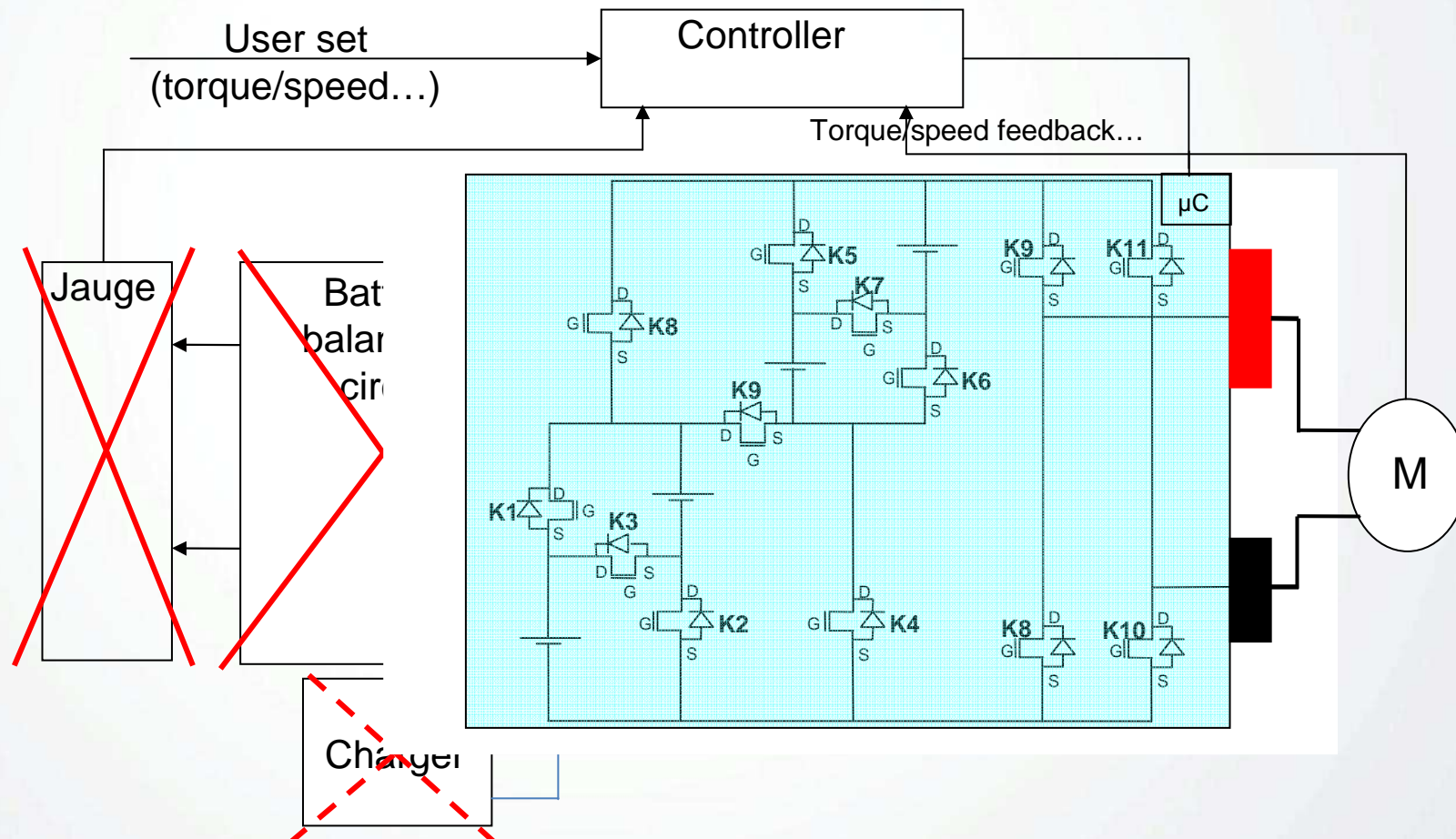


# Possible to use various battery technologies



# Le BMS commuté : l'architecture générique

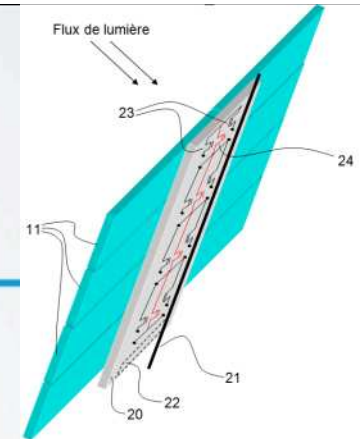
## Classical architecture versus switching architecture



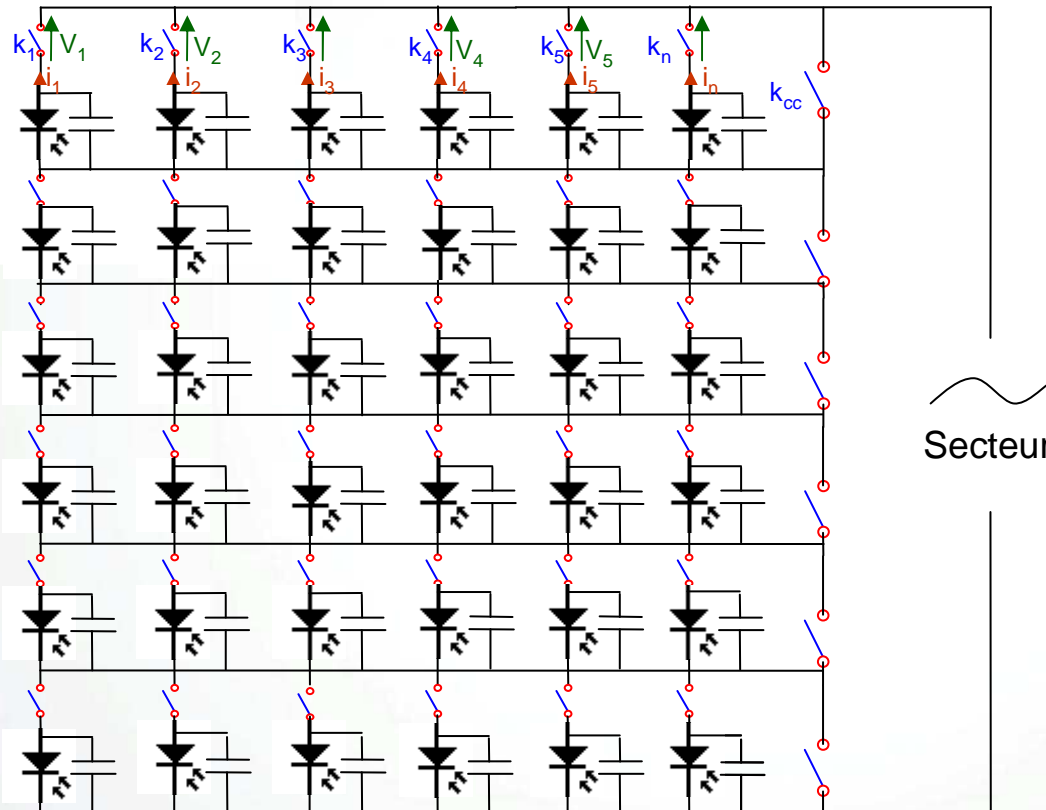
## Exemple d'applications :

- Outils/objets électroportatifs
- Alimentation de secours (remplacement groupes électrogènes)
- Eclairages de secours
- Systèmes de transport électriques (bus, voiture, scooter, vélo, bateau, trottinette, jouets...)
- Eclairages solaire avec stockage
- Stockage stationnaire
- Systèmes autonomes

# Photovoltaic extension



## • Direct connexion to the electrical network



### ■ Advantages

- Remove the inverter
- Local MPPT without any costly and heavy inductive converters
- Disconnection of failed cells
- Optimal operation even with some dark areas

## Le BMS commuté : conclusions

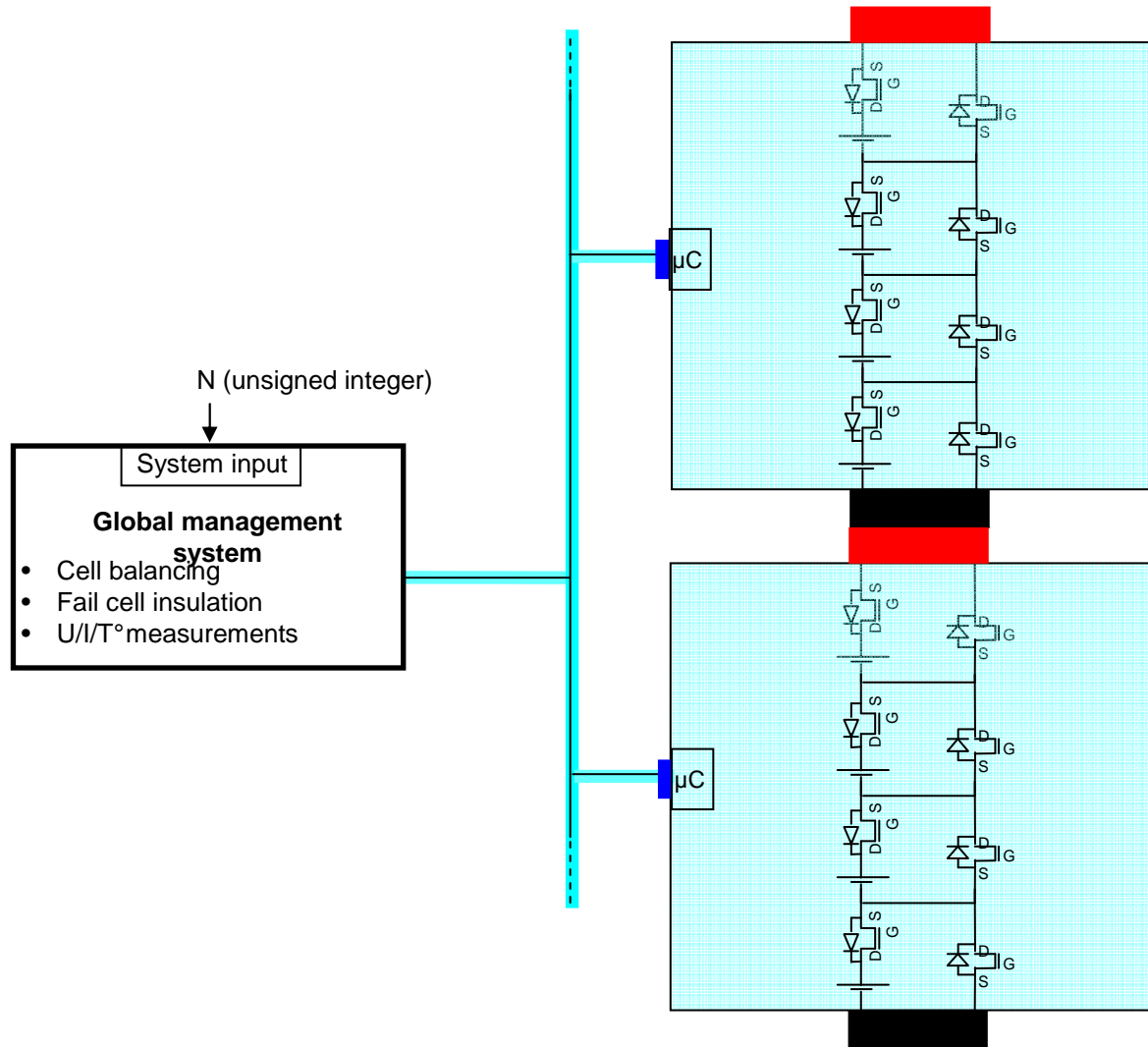
- Fonctions classiques
  - ☒ Monitoring des tensions et de température
  - ☒ Mesure du courant
  - ☒ Communication interne / externe
  - ☒ Estimation des indicateurs d'états (charge, santé, ou autres)
- Fonctions avancées
  - ☒ Équilibrage dynamique
  - ☒ Continuité de service en cas de défaut accumulateur
  - ☒ Régulation de la tension de sortie à la demande
    - Fonction d'écrtage
    - Fonction de commande spécifique (exemple : contrôle moteur)
  - ☒ Optimisation de l'énergie embarquée
    - Par rapport au vieillissement
    - Par rapport à la thermique
  - ☒ Utilisation d'accumulateurs d'état de santé différent
  - ☒ Utilisation d'accumulateurs de chimie différente



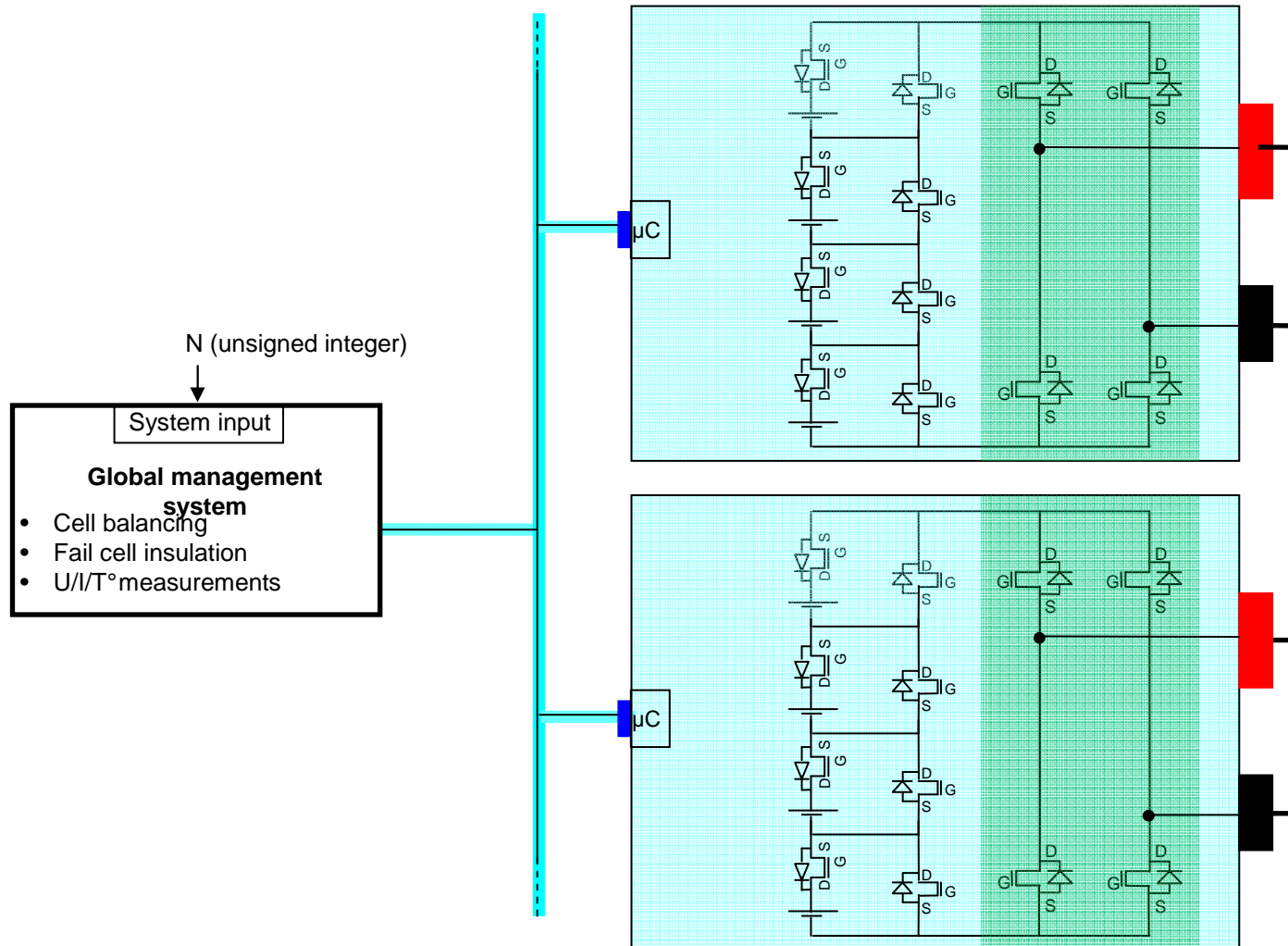


Thank you for your  
attention

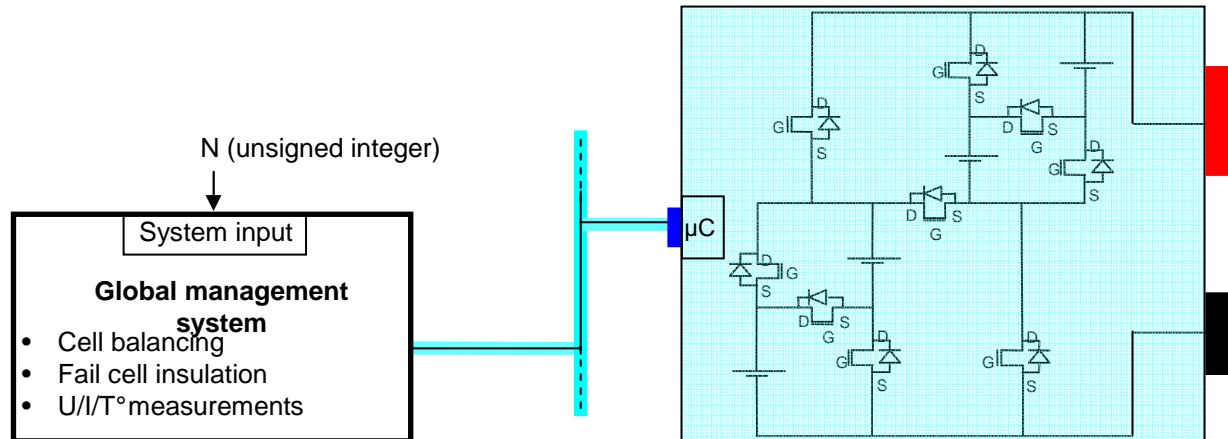
- Carte générique sans inversion de tension et sans mise en parallèle



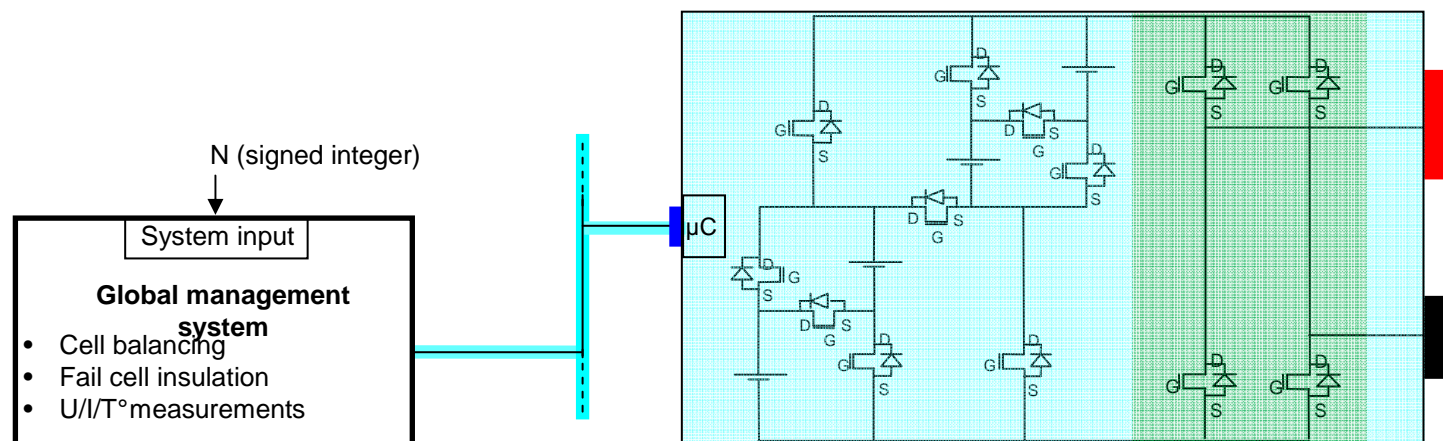
- Carte générique avec inversion de tension et sans mise en parallèle



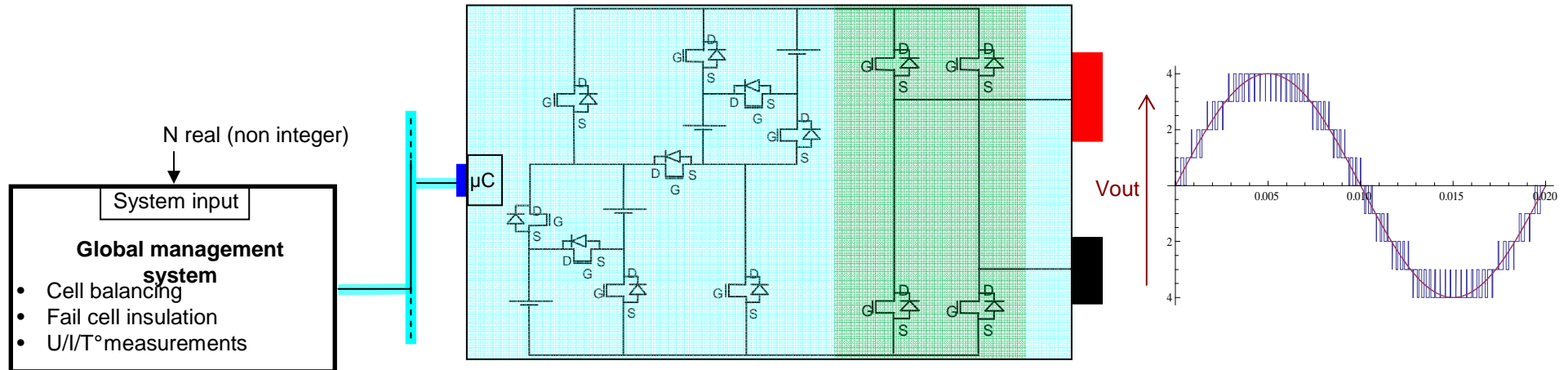
- Carte générique sans inversion de tension mais avec mise en parallèle



- Option 1 : avec inversion de tension et mise en parallèle



- Option 2 : avec niveaux intermédiaires (PWM inter-niveaux)



- Option 3 : avec pilotage system CEA

